

High Energy Physics Center for Computational Excellence: ORNL: Celeritas

DOE HEP CCE All-Hands
July 22-24 2024

Phase 2 Objectives: Detector Simulation

Detector Simulation HEP-CCE Objectives

- Platform portable, accelerated optical photon transport integrated in luminescent detector frameworks
 - E.g., BACCARAT, art, CalVision, Gaudi or others
- Platform portable geometry representation and navigation
 - Monte Carlo detector simulation fully validated and accepted by experiments
 - Reconstruction e.g., integration with ACTS (ATLAS Common Tracking Software)

Completion Criterion

- Validate optical photon physics on defined benchmarks
- Improve LZ optical photon simulation throughput by 20–25× for G2; 50× for G3
- Reduce cost of geometric operations in particle event tracking loop by a factor of > 2
- Verify geometric tracking on community detector benchmark models demonstrated on DOE LCF architectures including full CMS and ATLAS/TileCal models

Cross-Cutting Activities and SIM Outreach

External Collaborations

- Participate in community meetings
 - Geant4 collaboration
 - CHEP
 - HSF Simulation Working Group
 - Experiment Software Weeks and simulation group meetings
- DOE CSGF practicums
- Current university collaborators
 - University of Virginia (CalVision)
 - University of Massachusetts - Amherst
- External Collaborators
 - SWIFT-HEP
 - AdePT (CERN SFT)
 - CMS, ATLAS, ALICE, DUNE/SBND, LHCb, LZ, CalVision simulation teams

Cross cuts across HEP-CCE

- SIM
 - Coupled event-generator/detector simulation on-device
- SOP
 - Migration to RNTuple for parallel I/O
- SMiLe
 - Training data generation

Celeritas/SIM Meetings

- **bi-weekly open slot**
 - 2/week team standups
 - update hep-sim email list
 - update indico HEP-CCE page
- **Open Issue tracking**
 - github:celeritas-project



Detector Simulation Milestones - FY24

Optical Photons

1. Implement GPU optical physics models (Nvidia/AMD)
2. Integrate GPU optical photon event loop into Celeritas with verification and baseline performance on (simplified) LZ geometry models

Geometry

1. Develop GPU-enabled surface-based shape models needed for ATLAS, CMS, and other experimental detector models

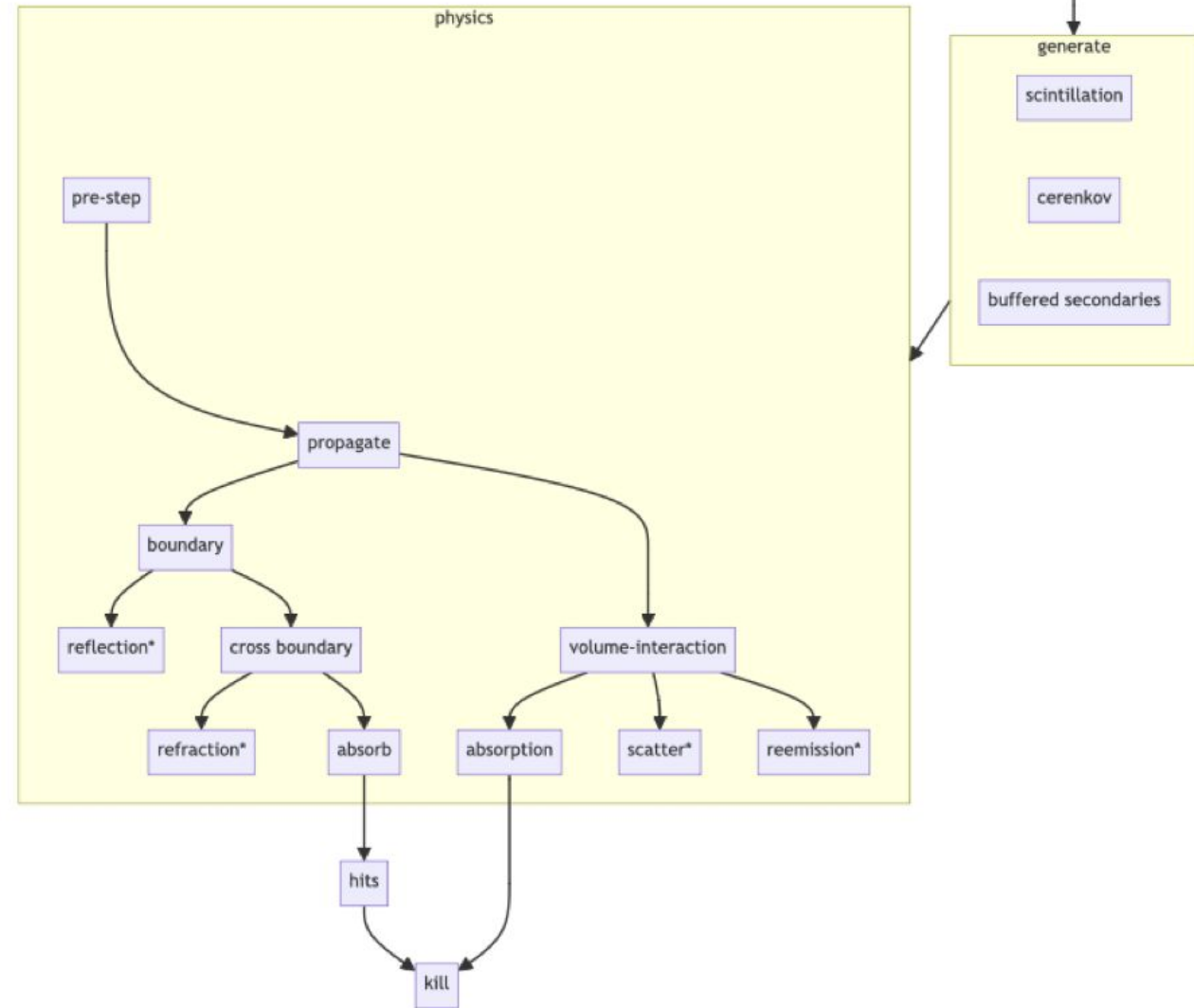
Optical Photons

Optical Photon Transport

Challenge: thousands of optical photons can be emitted per track per step, leading to long run times

Initial goal: integrated optical tracking loop with absorption by end of summer

- ✓ Geant4 optical data import
- ✓ Scintillation production
- ✓ Cerenkov production

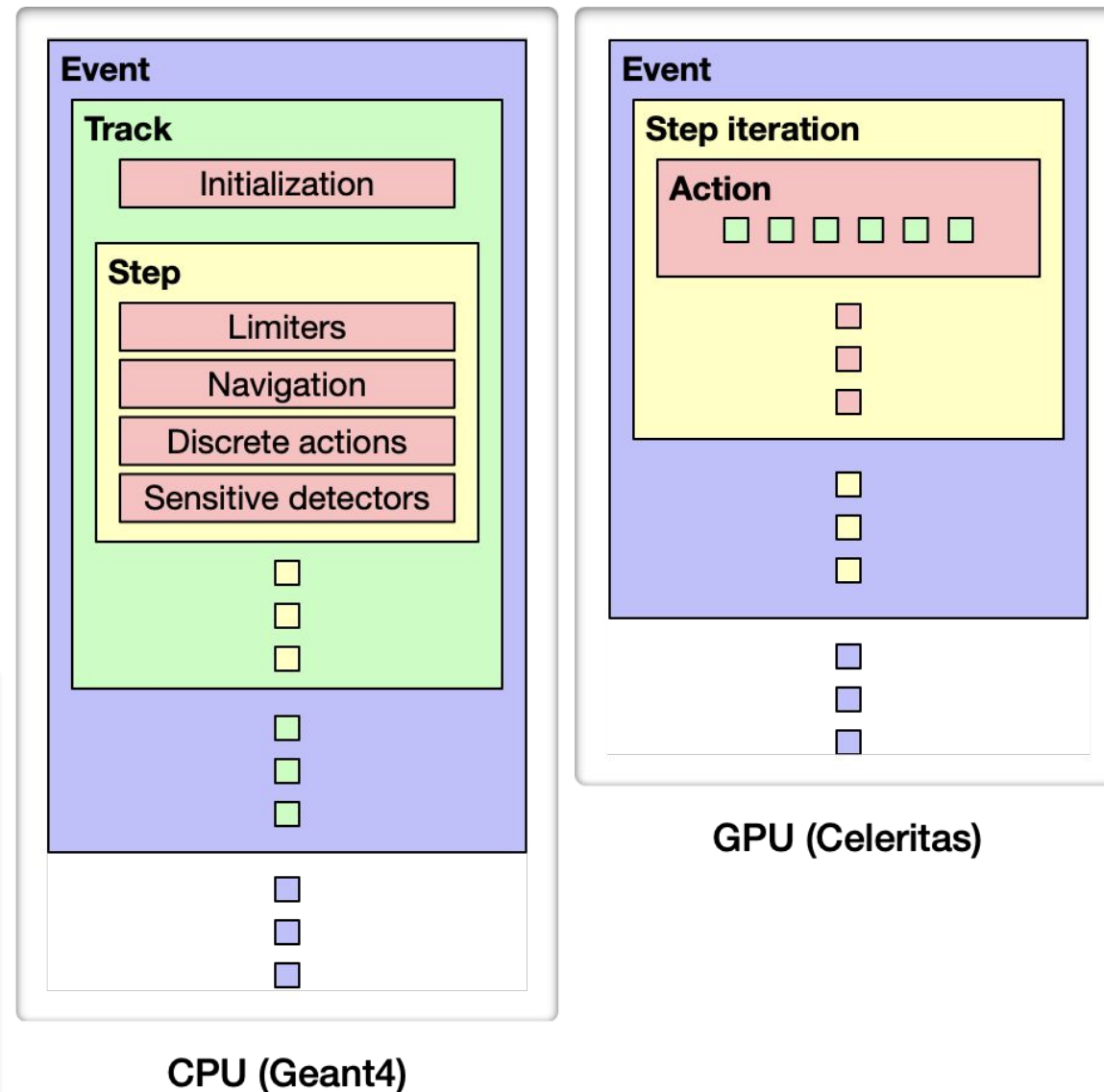


Core algorithm for simulation: stepping loop

- External synchronization point at each “event” ($p-p$ collision)
- Dependency between steps and independence of tracks allows *loop interchange*
- Instead of polymorphic functions operating on a single track, they launch a kernel over *many* tracks

Optical photon loop has simplified physics

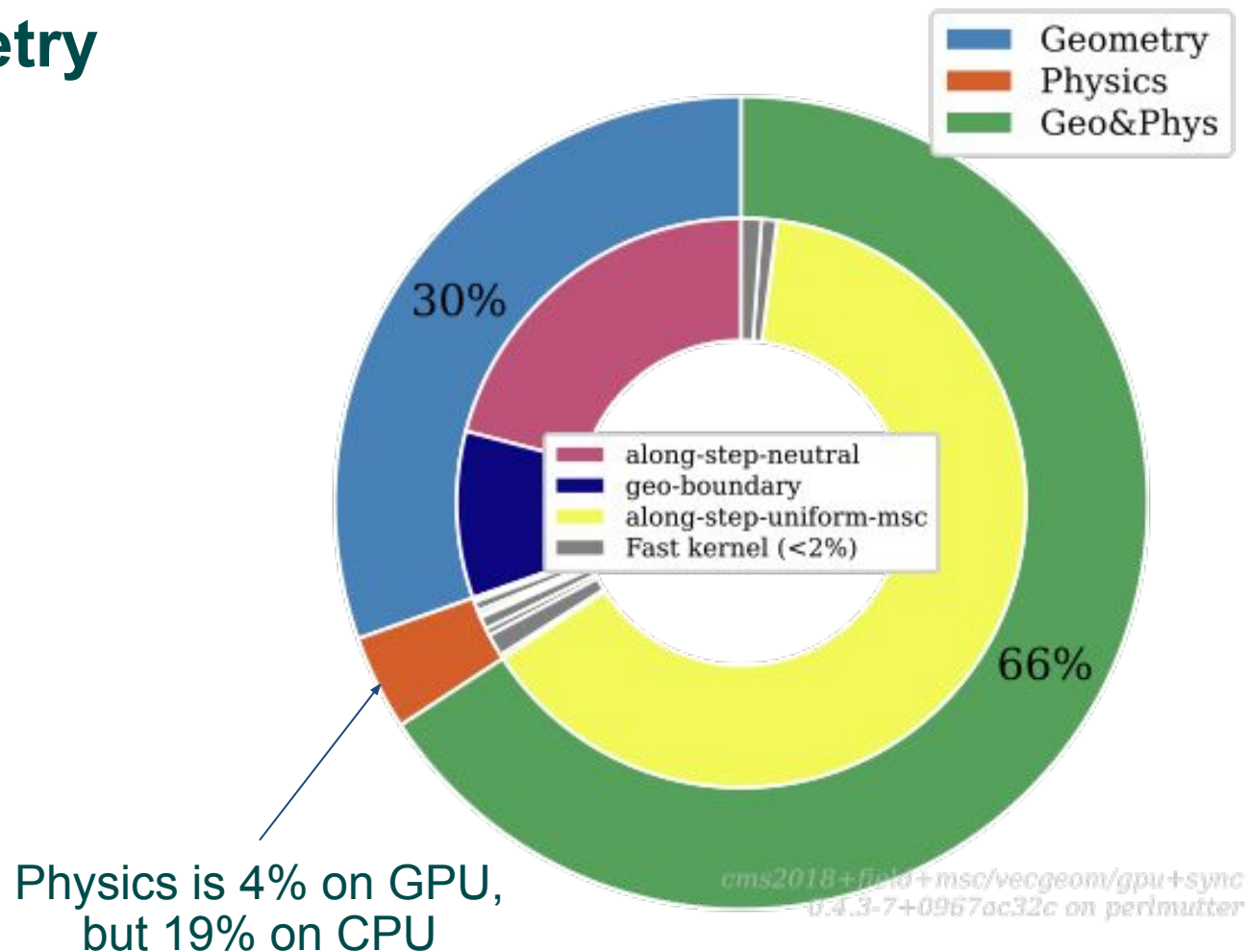
- discrete volume and surface physics only
- no safety distance
- no along-step processes
- ***specialized tracking loop to achieve desired performance***



Computational Tracking Geometry

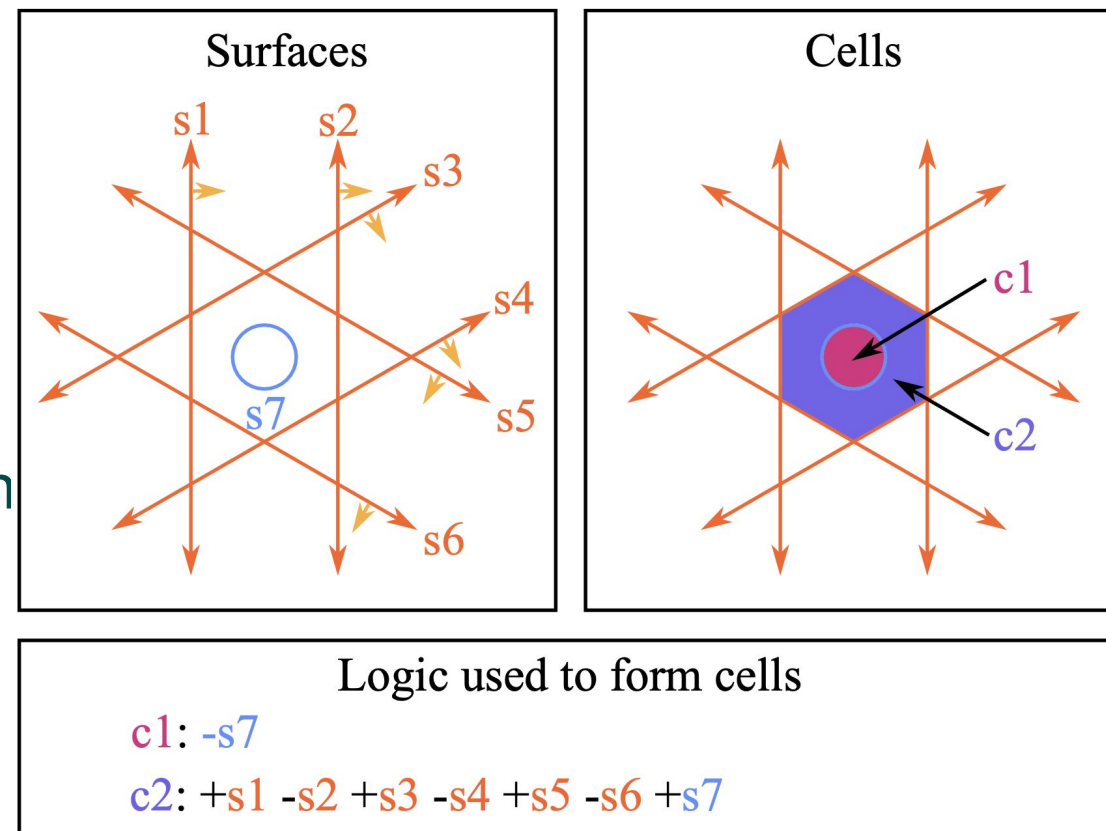
Primary LHC Bottleneck: Geometry

- Each step* may require 100 “distance to boundary” evaluation
* $\sim 1B$ steps per simulation!
- Up to $\sim 10^5$ distinct geometric elements per detector model
- CERN (VecGeom) and ORNL (ORANGE via HEP-CCE2) both implementing potential solutions



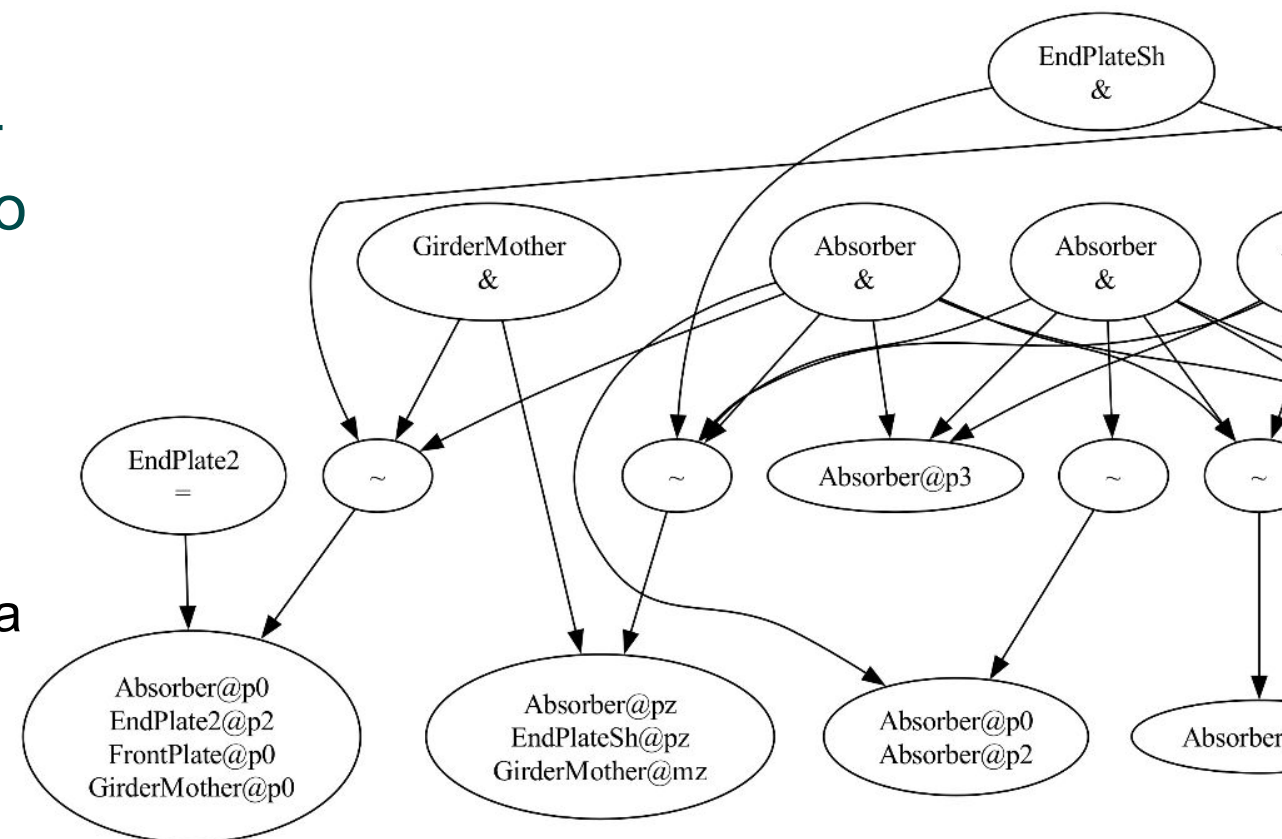
Geometry background and goals

- Universal volume-based detector geometry description
 - Multiple front ends: DD4HEP, GDML
 - Multiple back ends: Geant4, ROOT, VecGeom
- Volume-based tracking is not performant on GPU
- ORANGE: GPU-optimized geometry representation using surfaces
 - **New:** Geant4 volume conversion
 - **In progress:** safety distance



Volume-to-surface conversion

- Constructed in-memory using Geant4
- Combine multiple related volumes into a repeatable “unit”
 - Single-use volumes
 - Leaf nodes (no embedded volumes)
- For each unit:
 - Construct surfaces from each volume in a local reference frame
 - Apply transformations
 - Merge nearly-coincident surfaces



Some surfaces and volumes
constructed from ATLAS TileCal

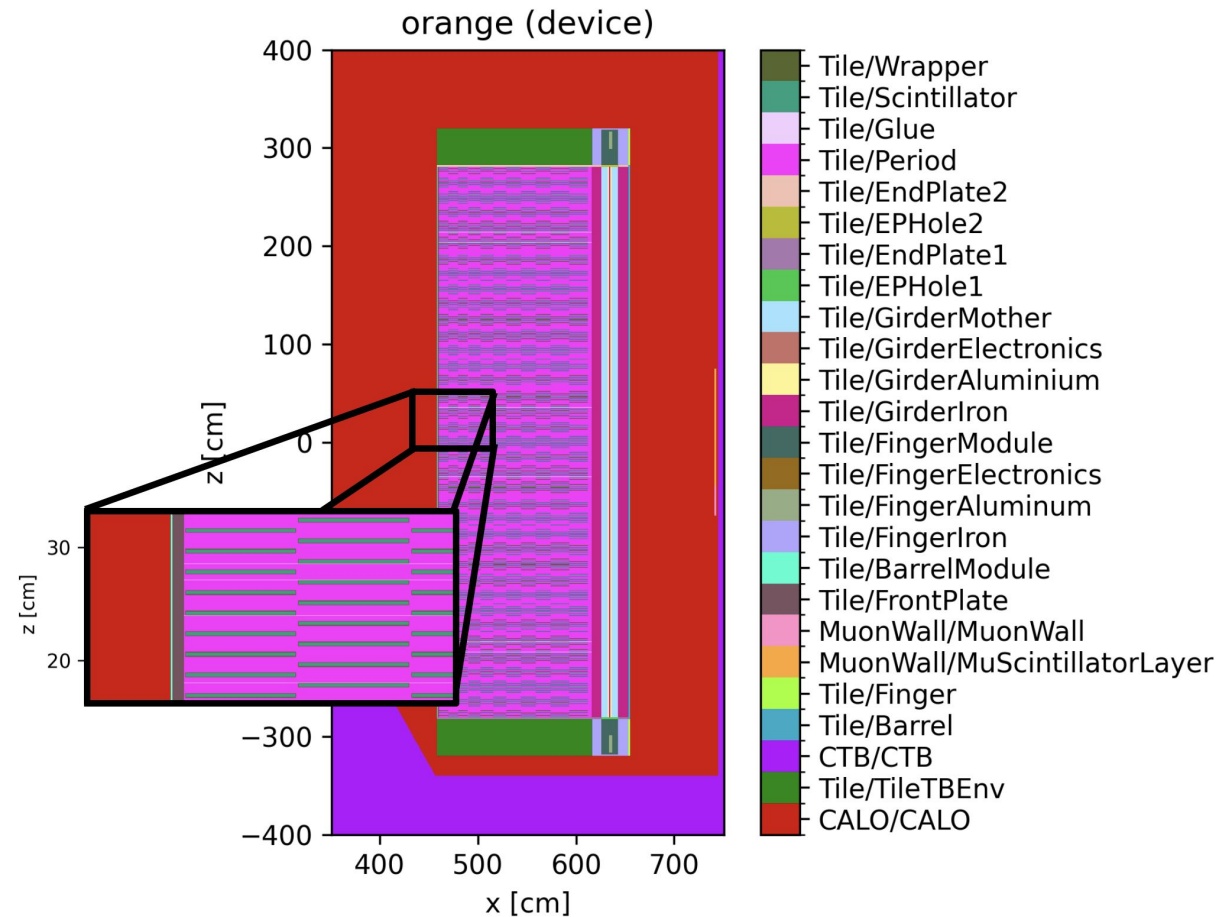
Task list

Challenge: most compute-intensive aspect of EM simulation on the GPU

- ✓ Model conversion
- ✓ Robust surface construction
- Model verification
- Performance optimization
- ✗ Safety calculation

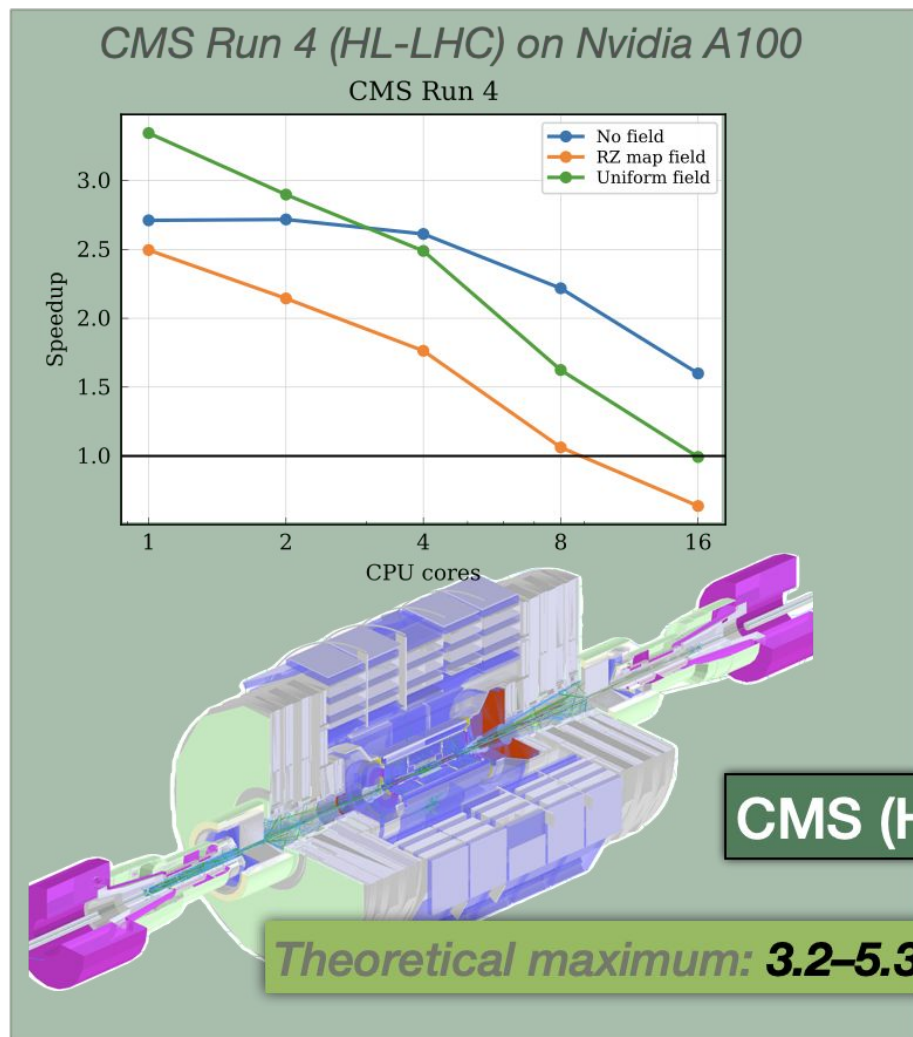
Initial targeted geometry

- ATLAS TileCal
- CMS HGCal
- ATLAS EMEC



GPU ORANGE ray trace of ATLAS tile calorimeter

Full physics performance coupling to Geant4 (VecGeom)



ATLAS Tile Calorimeter

Full physics GPU speedup: 2.6–2.8x
Theoretical maximum: 3.0–3.3x

