

Graph Neural Networks for pion event classification

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ProtoDUNE-SP Hadron Analysis

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Context - what processes?

- 3GeV ProtoDUNE-SP pion beam data
- Measuring π^+ - Ar cross-sections
- We consider 4 possible interaction channels
 - Absorption: $\pi^+ + \text{Ar} \rightarrow X$
 - Charge exchange: $\pi^+ + \text{Ar} \rightarrow \pi^0 + X$
 - Single pion production: $\pi^+ + \text{Ar} \rightarrow \pi^\pm + X$
 - Multiple pion production: $\pi^+ + \text{Ar} \rightarrow A \pi^\pm + B \pi^0 + X$,
 $A+B \geq 2$

	π^\pm s	π^0 s
Abs.	0	0
CEx.	0	1
1 pi	1	0
Multi.	otherwise	

Note this combines:

Quasi elastic scattering: $\pi^+ + \text{Ar} \rightarrow \pi^+ + X$

Double charge exchange: $\pi^+ + \text{Ar} \rightarrow \pi^- + X$

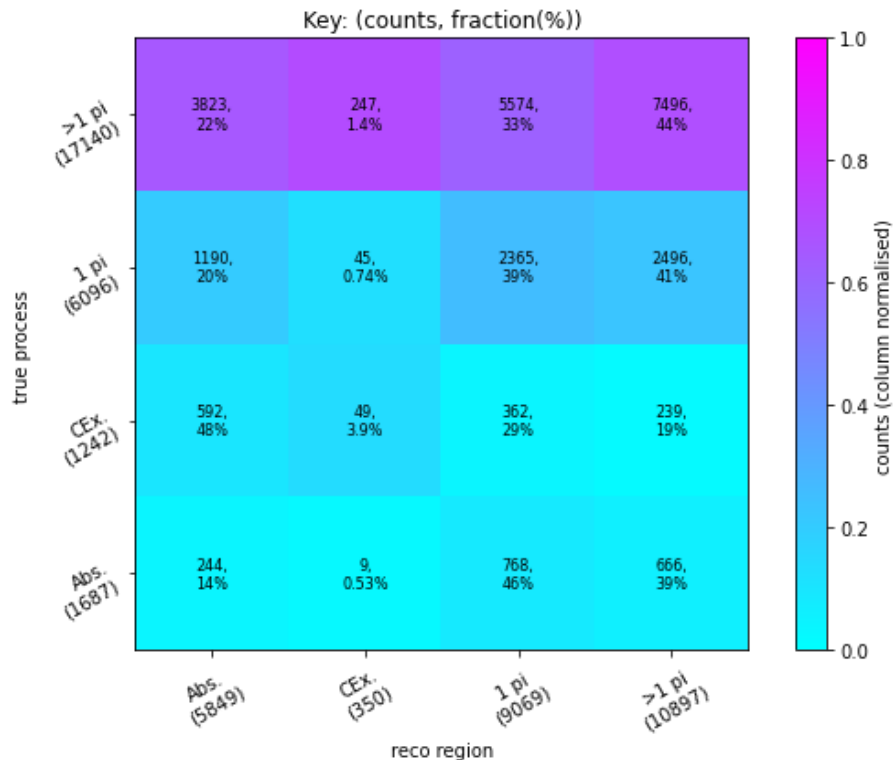
(can't distinguish π^+ / π^-)

Context - previous work

- Using analysis framework developed by Shyam Bhuller in Bristol.
 - Find his most recent talk here: [ProtoDUNE-SP Hadron Analysis Bi-Weekly Meeting \(May 1, 2024\) · INDICO-FNAL \(Indico\)](#)
 - This work – use a **GNN to perform process selection**.
 - Other aspects **unchanged** (selection, energy slice, unfolding, etc.).
- Copies the beam selection used by Shyam, not yet done any 3GeV optimisation.
 - Not yet implemented the fiducial cut on first 30cm.
 - Not yet made a cut on low energy pions.

Context - why graphs?

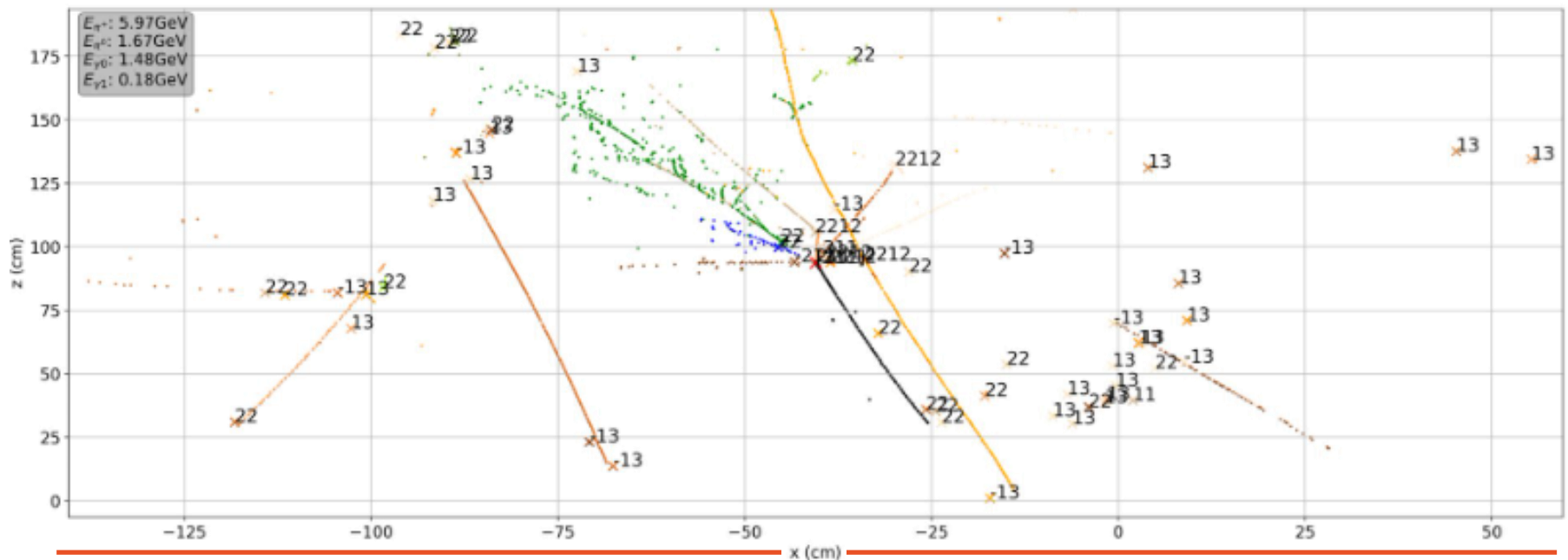
- Simple cuts-based method performs poorly.
- Identify PFOs as particles using cuts on the PFO properties.
- Count the identified PFOs to classify the event.



- x-axis is classification **predicted** by a method
- y-axis is the **true** classification (label)
- Colour shows **purity**:
 $n_{\text{cell}} / \text{sum_column}$
- Percentage shows **efficiency**:
 $n_{\text{cell}} / \text{sum_row}$

Context - why graphs?

- We don't know how many particles will appear in an event!
- A strategy is required to deal with an unknown number of inputs.
- **Graph Neural Networks** apply the same function all connected points, then perform *aggregation* to reduce to a known size.

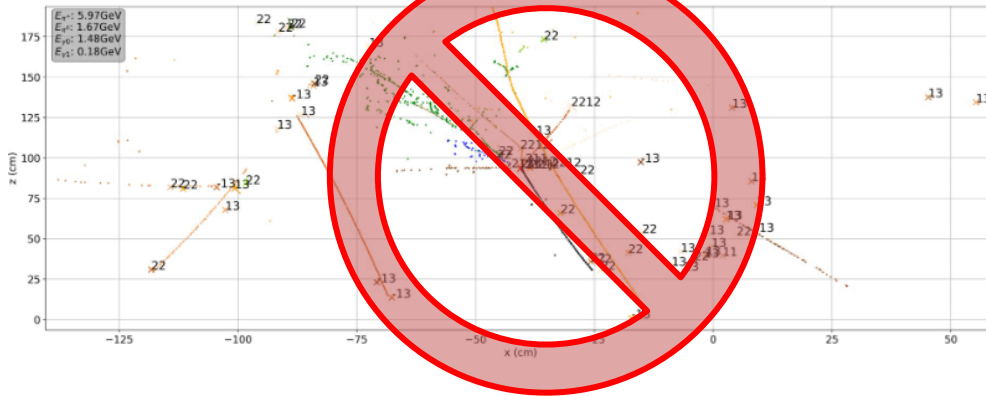


ProtoDUNE events as graphs

- Convert events to heterogeneous, undirected graph

Multiple types
of vertex

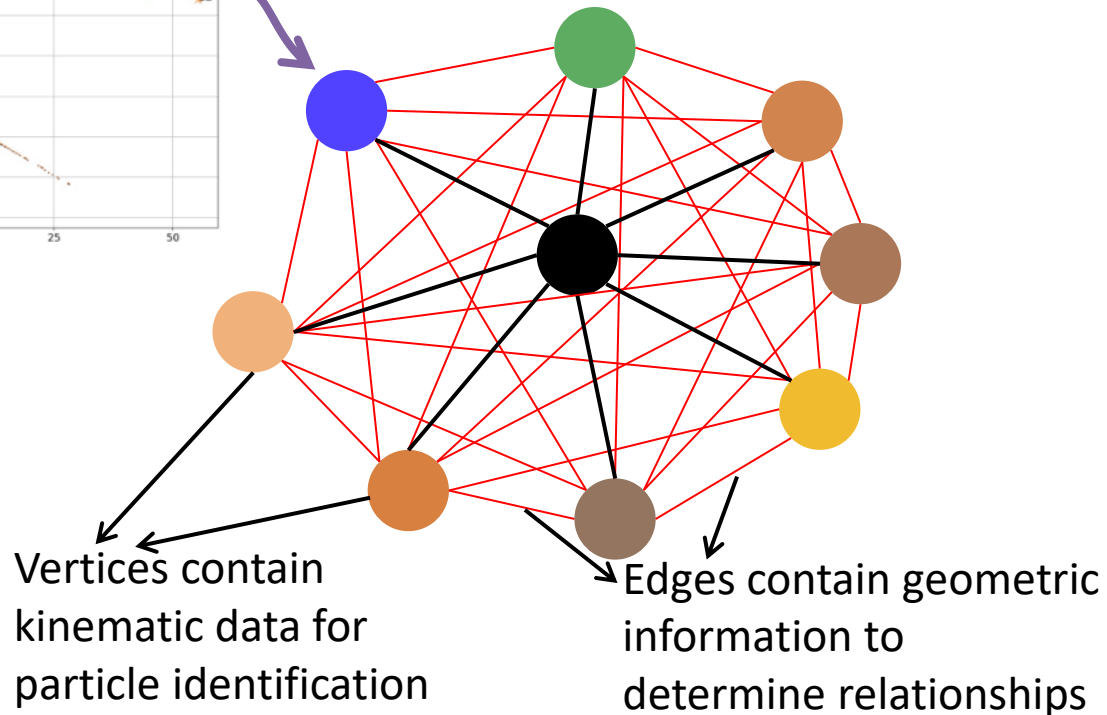
Edges are the same
in both directions



Not looking at hits

Instead, properties calculated post-reconstruction

- Track score
- Pion/proton χ^2 fits
- Etc.



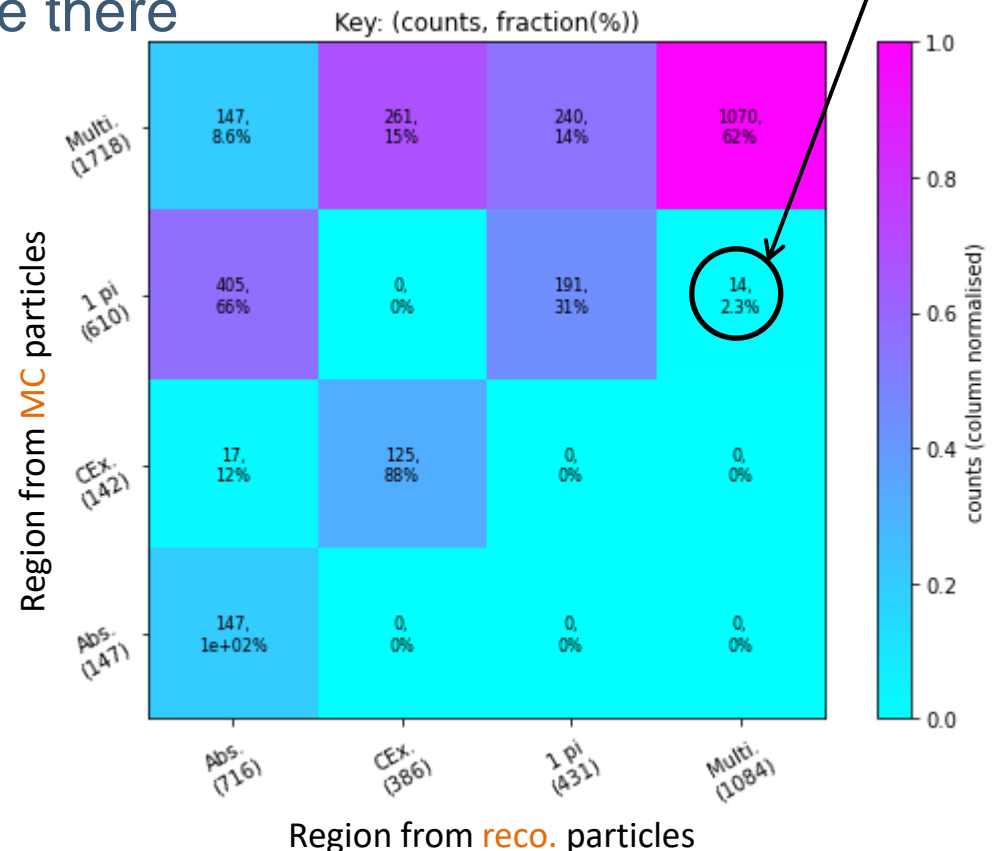
What data?

- Three levels of data used to test performance:
 1. **Monte-Carlo (MC)**:
 - Contains all particles from the Geant4 generator.
 - Takes truth values (i.e. particle relations, particle species) from Geant4 particles.
 - GNN achieves **perfect performance**.
 2. **Back-tracked (BT)** (aka. cheated):
 - Contains only reconstructed objects (generated by pandora clustering).
 - Relates reco. PFOs to MC particles by tracking the proportion deposited energy, take truth information from the related MC particles
 3. **Reconstructed data (reco.)**:
 - Reconstructed objects with reconstructed properties

Reconstruction effects

- Back-tracked data is affected by reconstruction efficiency.
- PFOs are only created where there is **energy deposition** in the detector *AND* the PFO **clustering** algorithms find this energy.
 - One of the failure modes is clustering hits from multiple particles as a single PFO.
 - Fewer PFOs per event than Monte-Carlo truth.

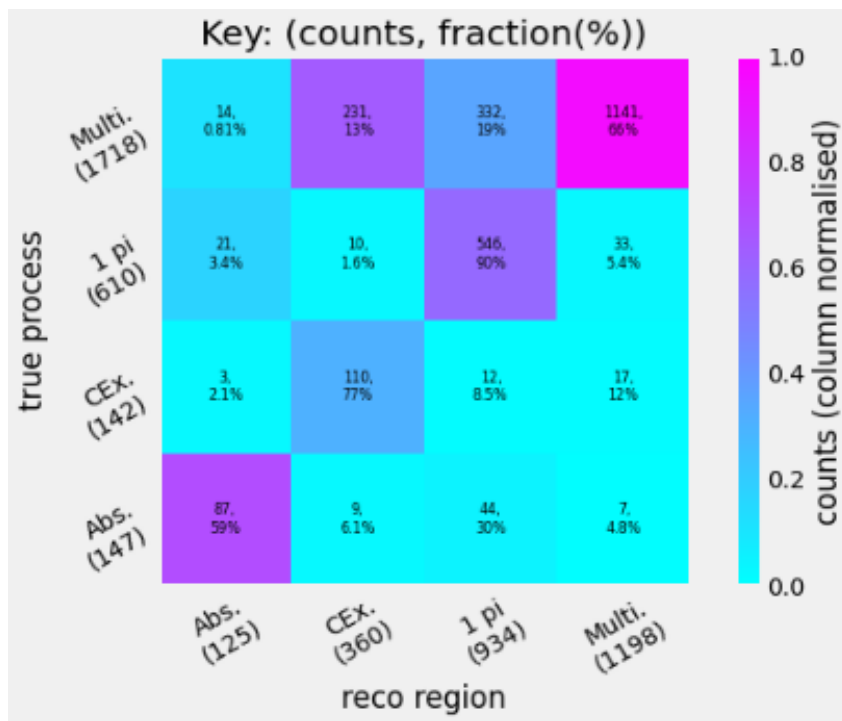
1 π^\pm incorrectly split into multiple PFOs



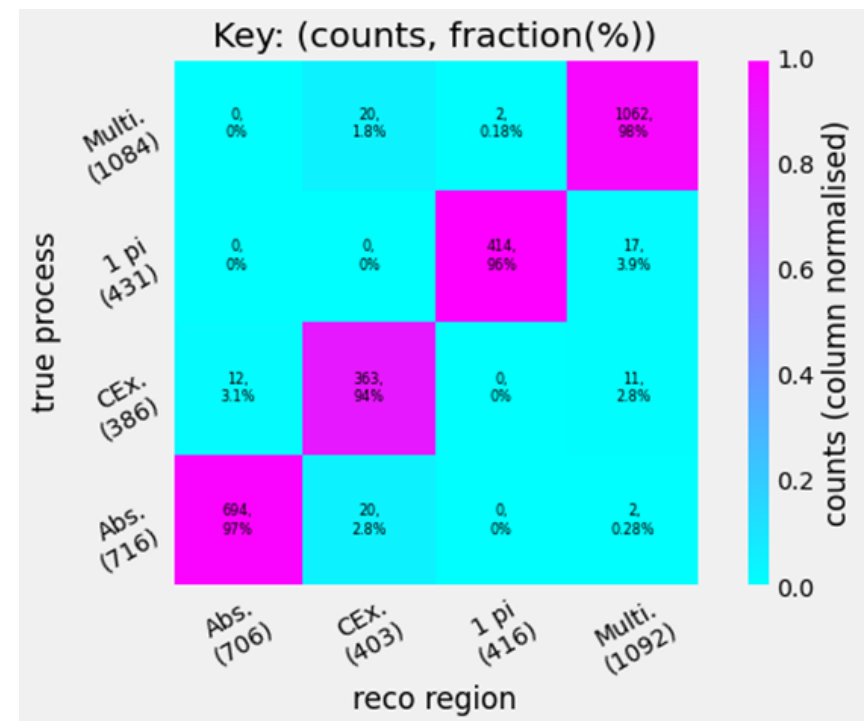
Back-tracked performance

- Can apply weightings to prefer efficiency over purity
 - Real test – which will produce lower uncertainty in the analysis

MC classified regions as true process



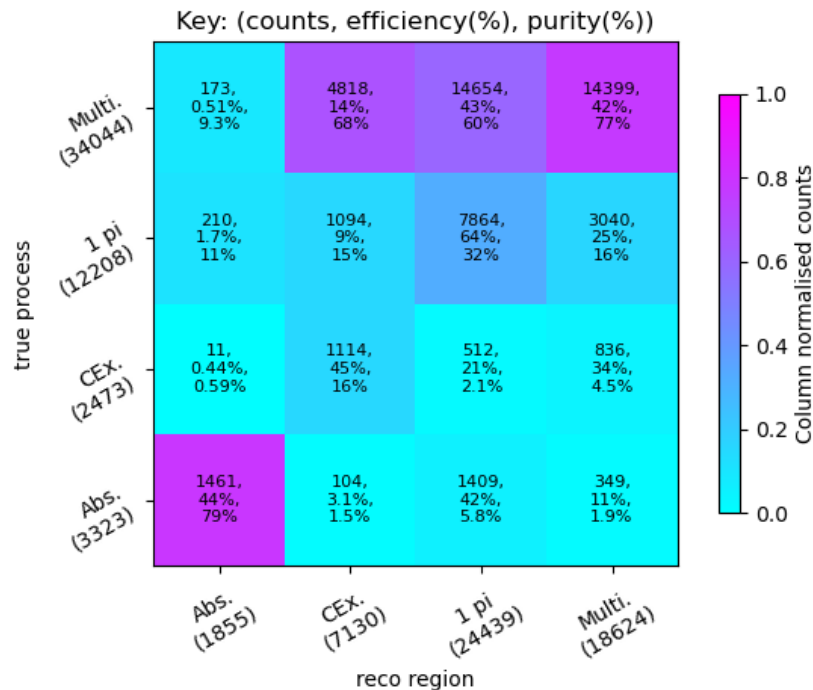
Reco. classified regions as true process



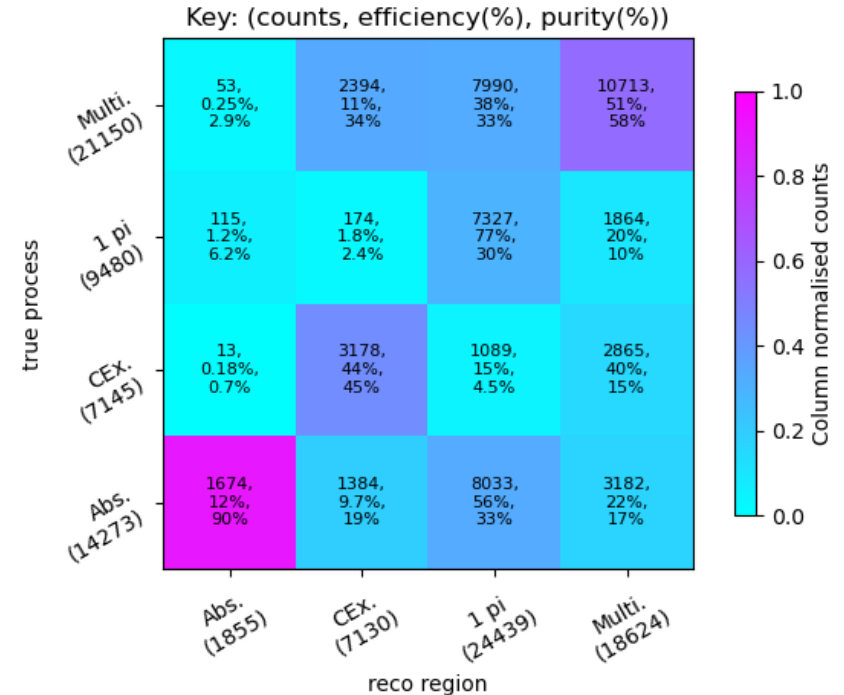
Reconstructed performance

- Performance further diminished using reconstructed properties
 - Biggest culprit seems to be π^\pm identification.

MC classified regions as true process



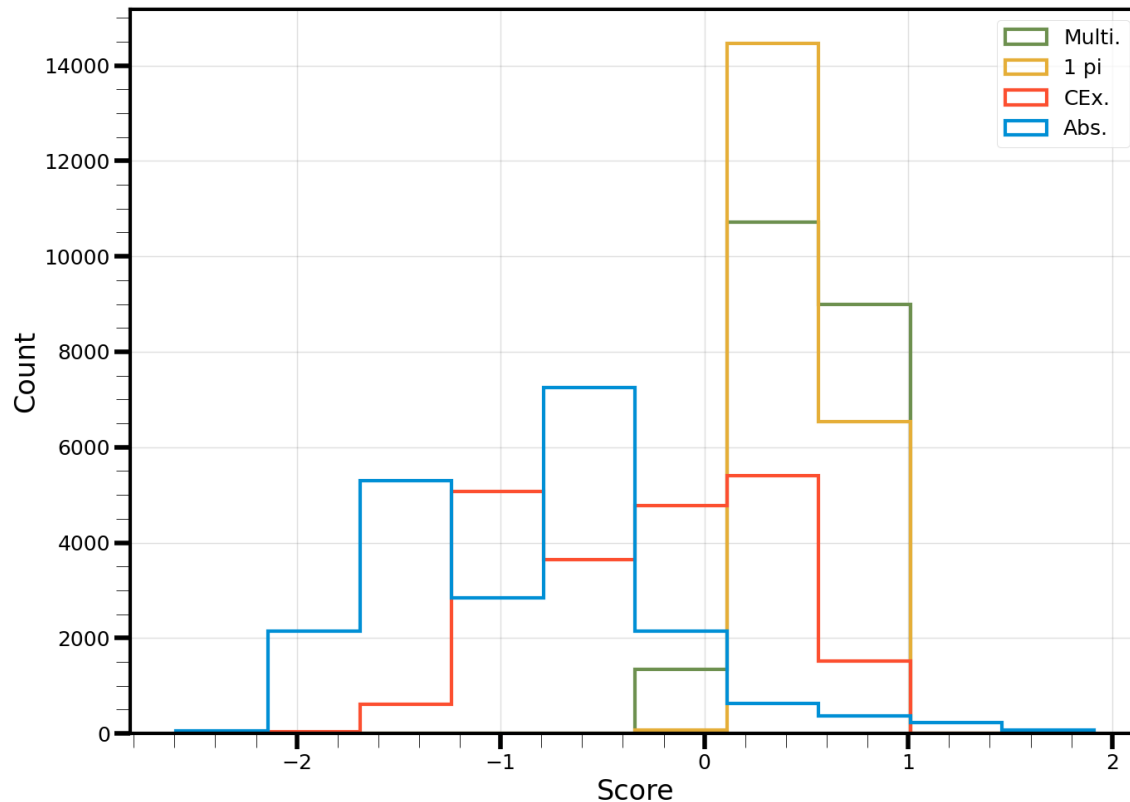
Reco. classified regions as true process



Use in analysis

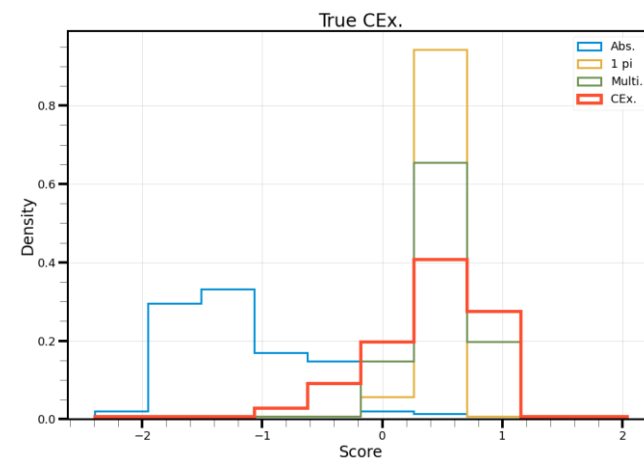
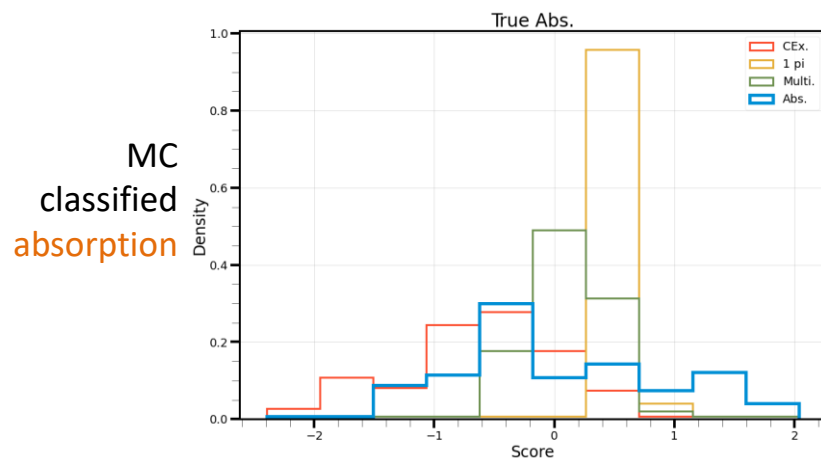
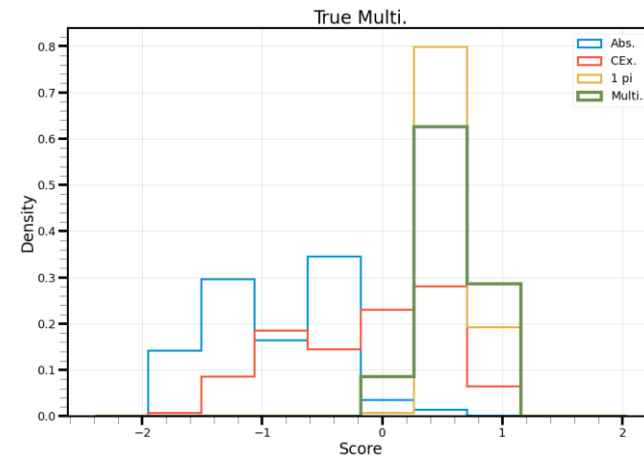
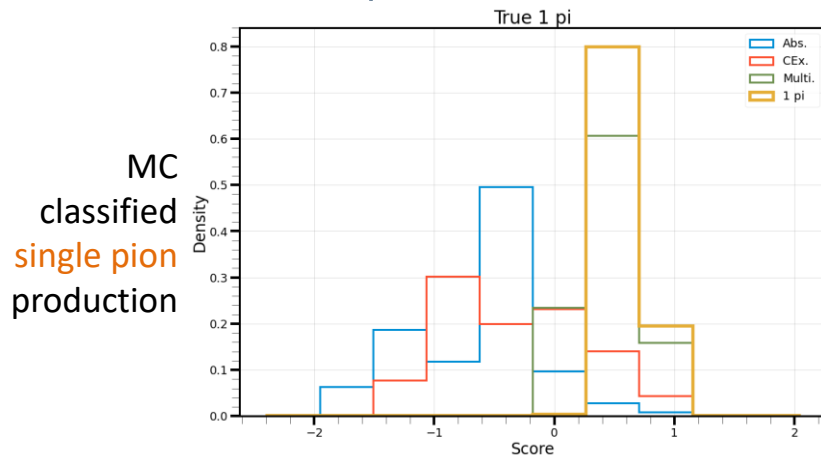
- Instead of classifying individual events, fit the **measured score** distributions with true classification **MC template** distributions.

Distribution of **GNN scores** per channel across all test events



Fit - templates

- Split half the MC data as a template (actual template have 4D correlation)



Fit – Minuit template fit

- The fit uses (python) [Minuit's template fit](#), using [Dembinski and Abdelmotteleb](#) method.
- Data, D_{c_i} : count in bin i of channel c
 - $c \in$ GNN score channels (abs., CEx., single pion, multi. pion)
 - $i \in$ bin indices
- Template, $t_{c_i,r}$: count in bin c_i given true event region r
 - $r \in$ Regions (abs., CEx., single pion, multi. pion)
- A full template, $T_{c_i}(\mu_r)$ is constructed as:
 - $$T_{c_i}(\mu_r) = \sum_r \mu_r \frac{t_{c_i,r}}{\sum_{c_i} t_{c_i,r}}$$
 - With μ_r is parameter to be fit, the actual count of each region.
- The fit maximises the binned likelihood $\mathcal{L}(D_{c_i} | T_{c_i}(\mu_r))$, accounting for the template nature of the fit to find μ_r .

Fit – Minuit template fit

- Use Minuit to fit the remaining MC from the templates

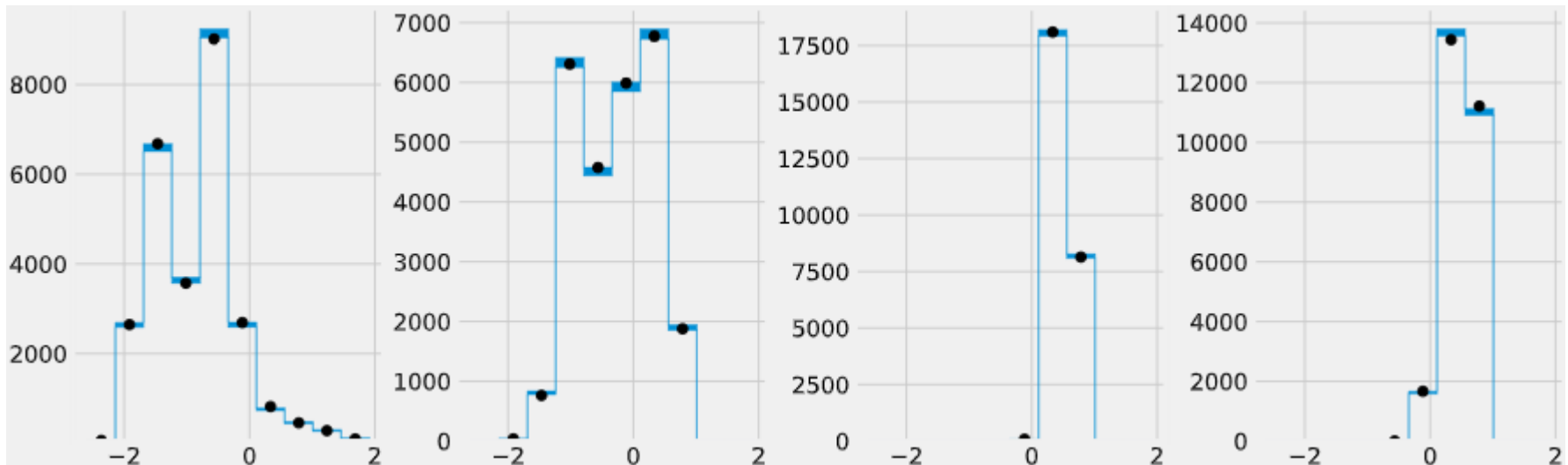
	Absorption	Charge exchange	Single pion production	Multiple pion production
True count	1652	1244	6120	17305
Fit count	1602.14	1166.81	6325.83	17225.99
Fit error	73.10	170.20	369.92	449.06

Absorption scores

Charge exchange scores

Single pion scores

Multi. pion scores

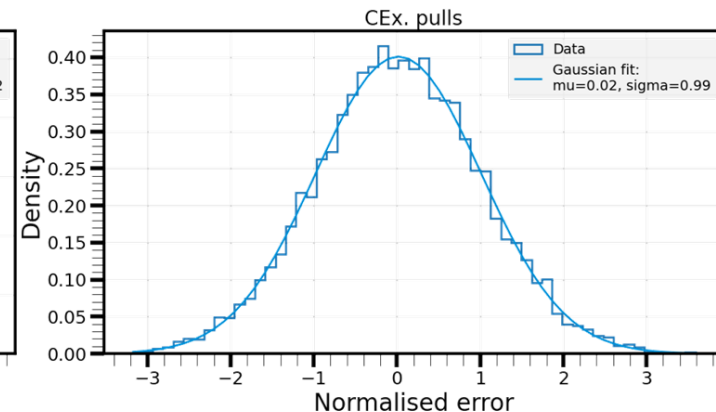
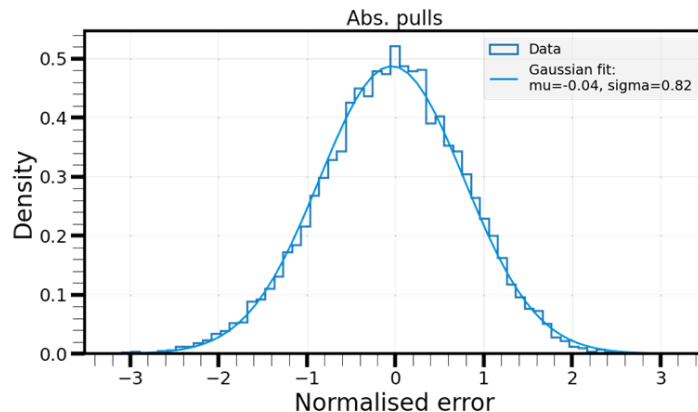
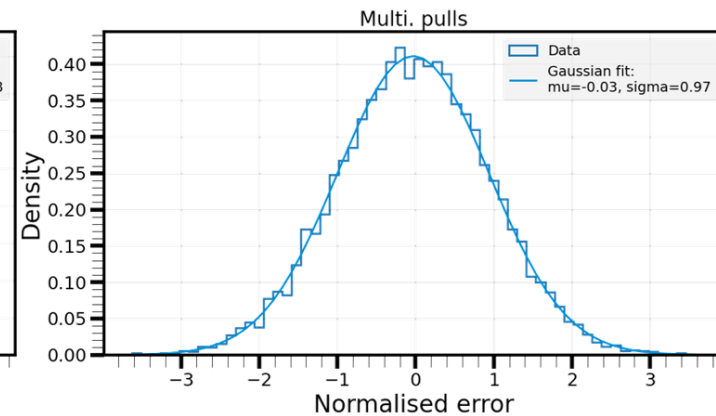
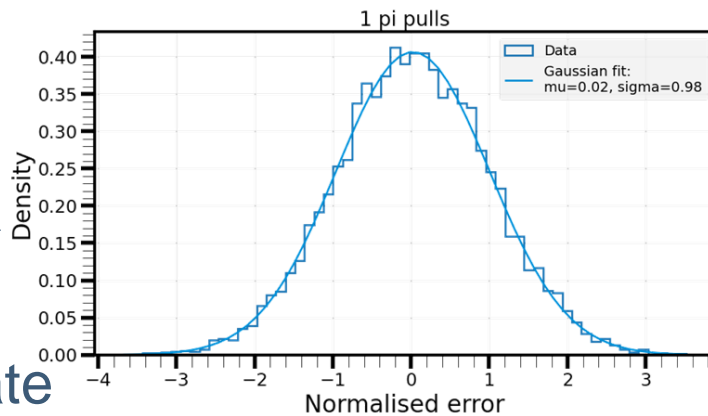


Checks – Pulls

$$\text{pull} = \frac{\text{fit pred.} - \text{true count}}{\text{fit uncertainty}}$$

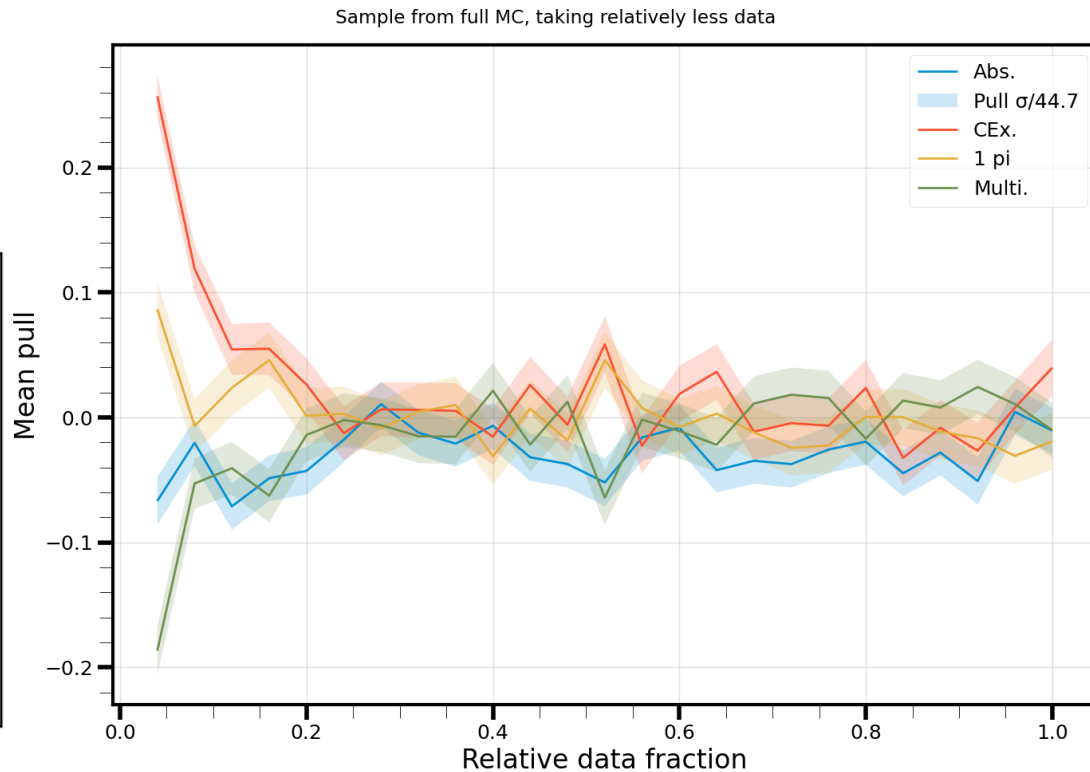
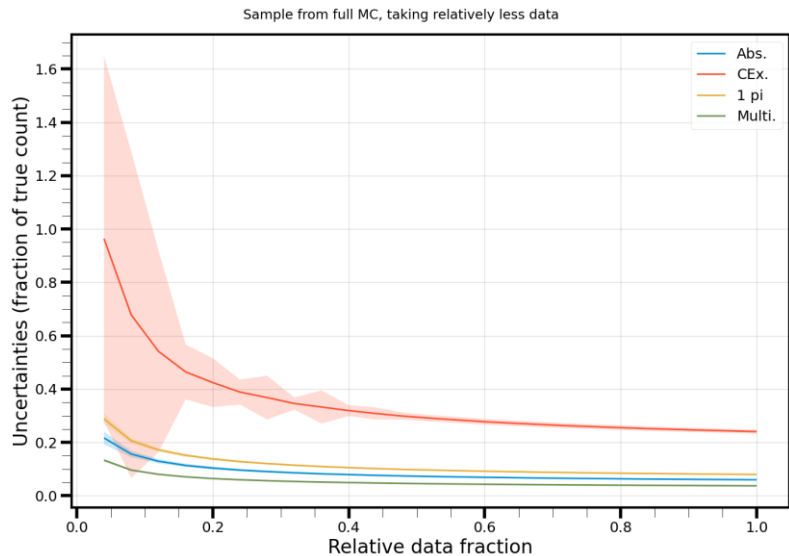
- Want to check the robustness of the fit:
 - Can it recover the actual “data” process fractions, even when the templates are mismodelled?

- The MC data is shuffled, split into data /templates
- Some template property may be edited.
- Shown: 10,000 pulls



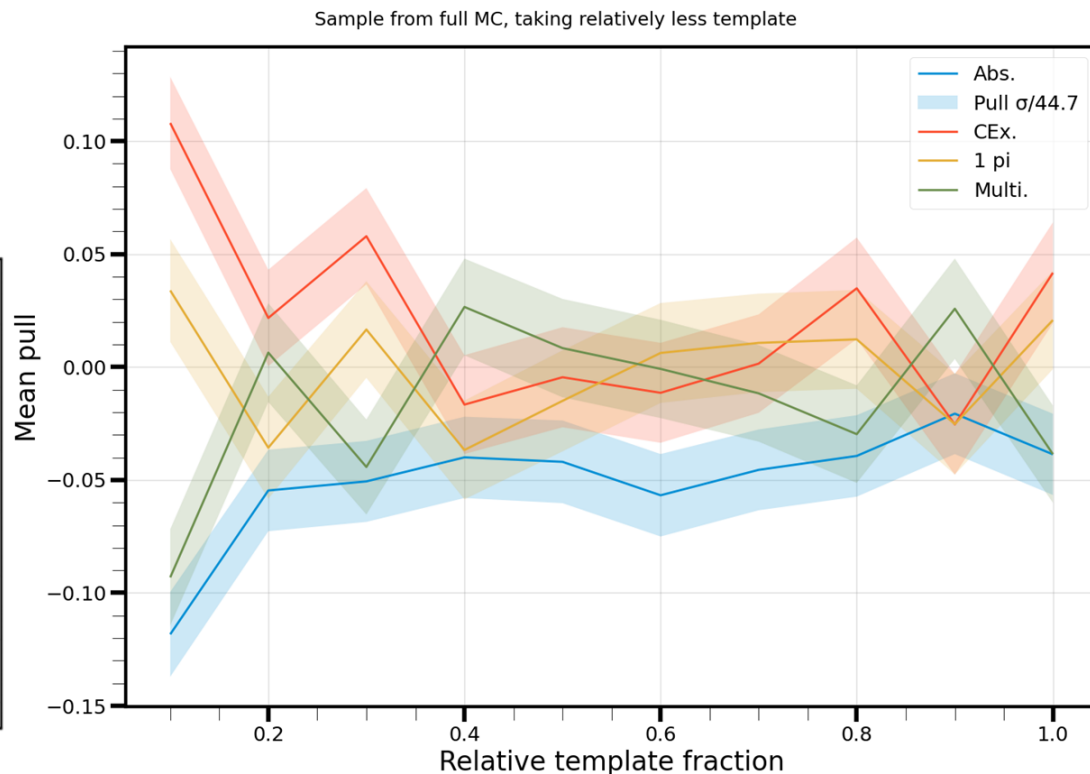
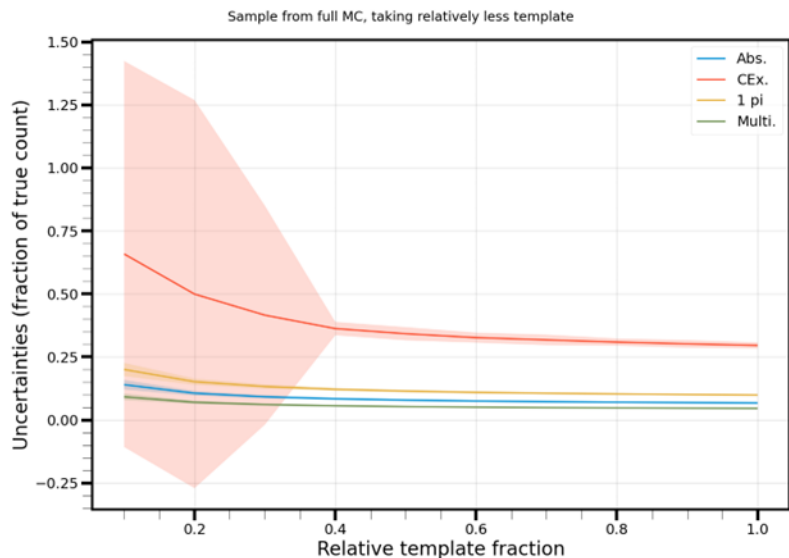
Checks – Data statistics

- Are the pulls consistent as the number of events in the data changes?
- “Relative data fraction” runs from 500 at 0.04 to 25,000 at 1.0
- For each test: 2,000 pulls



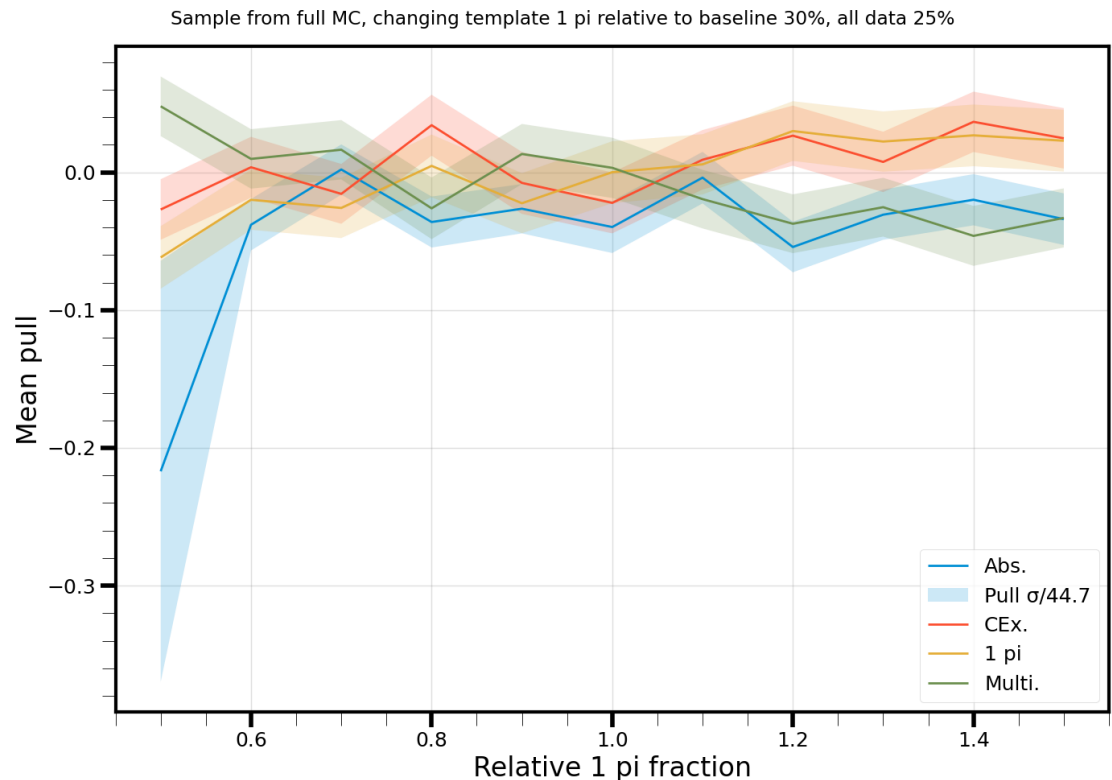
Checks – Template statistics

- Are the pulls consistent as the number of events in the template changes?
- “Relative data fraction” runs from 2,500 at 0.1 to 25,000 at 1.0
- For each test: 2,000 pulls



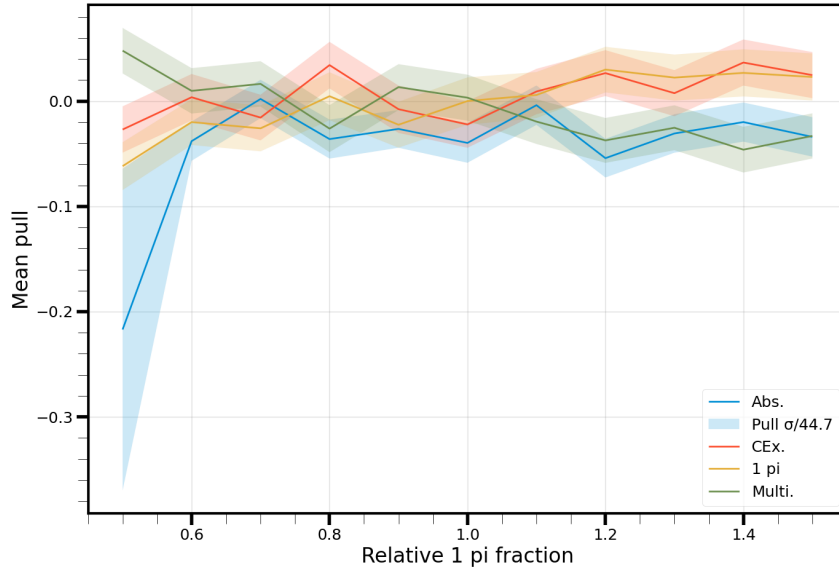
Checks – Template process fracs.

- If the fraction of processes (abs., cex. etc.) change in the template, does the fit still follow the data.
- 12,500 data, 15,000 baseline template, weighted 7,500 - 22,500
- A bad method would show a positive gradient (under-estimate when template has a deficit)

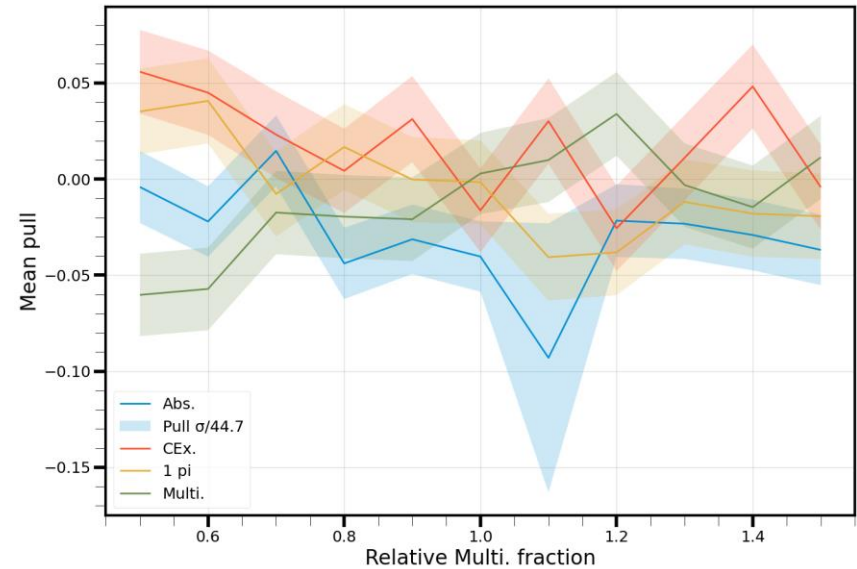


Checks – Template process fracs.

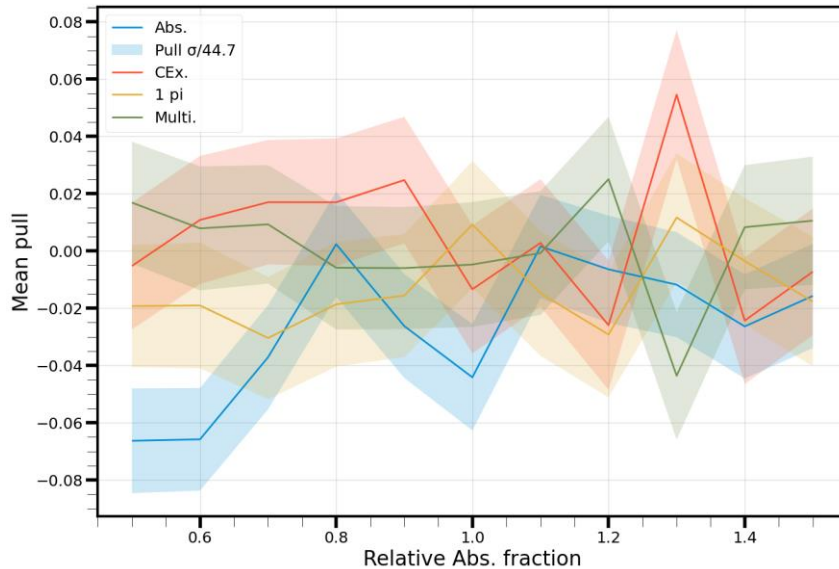
Sample from full MC, changing template 1 pi relative to baseline 30%, all data 25%



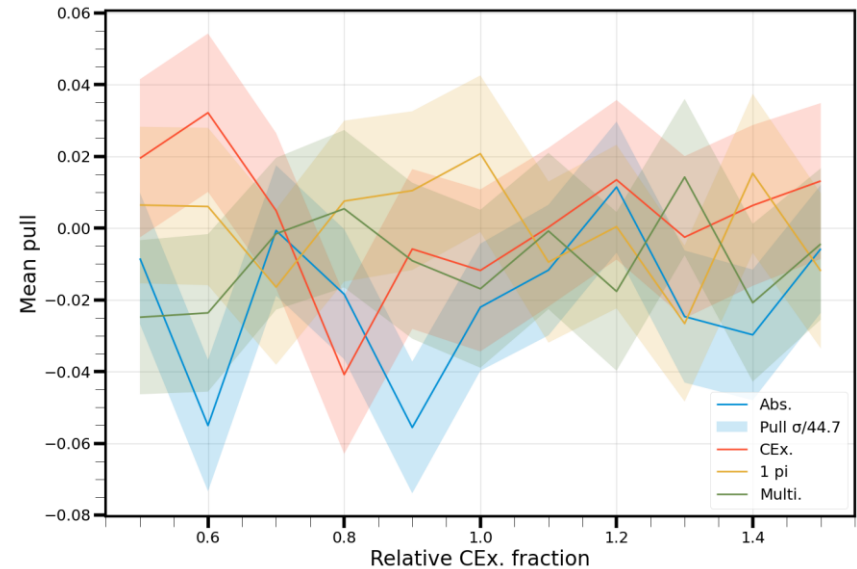
Sample from full MC, changing template Multi. relative to baseline 30%, all data 25%



Sample from full MC, changing template Abs. relative to baseline 30%, all data 25%



Sample from full MC, changing template CEx. relative to baseline 30%, all data 25%

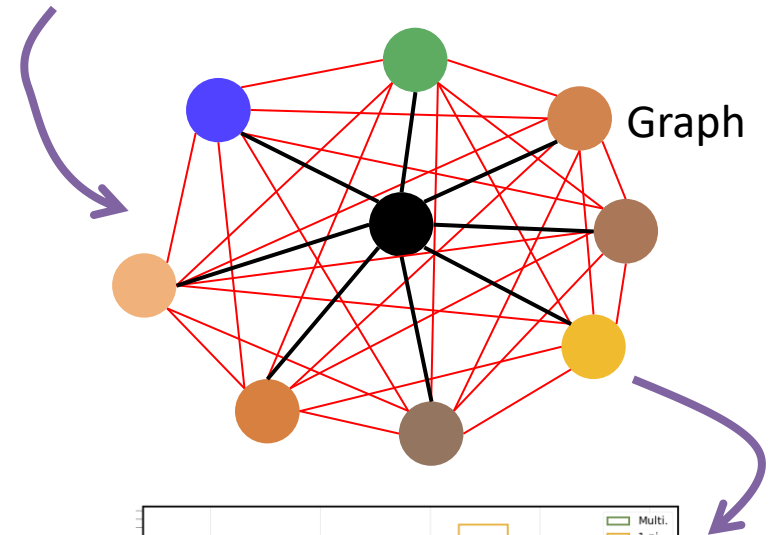
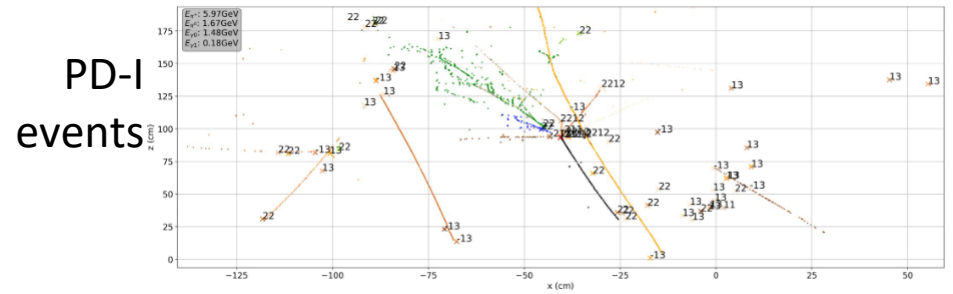


Checks – Comments

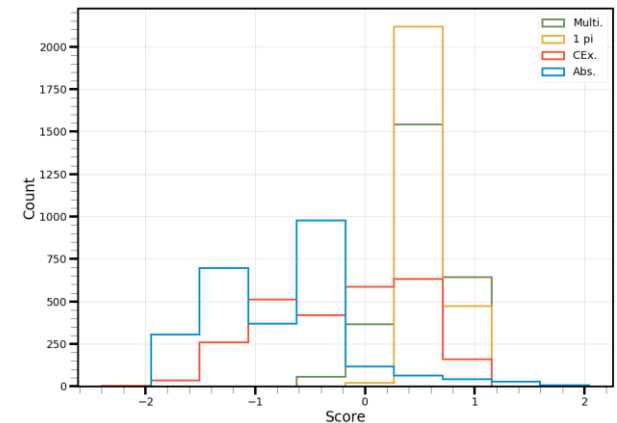
- The single/multiple pion production channels appear to have slight dependency on the template fractions.
- Charge exchange struggles with low statistics.
- Check still to do:
 - “Smearing” the templates (shuffling the template bin occupancies)
 - Reweight the template as a function of:
 - Beam particle energy (energy correlations)
 - Number of PFOs in event (reconstruction effects)
 - Make tweaks to the MC before running the GNN.

Summary

- Graph neural networks are appropriate for data with an unknown number of inputs.
- **Extra losses** give extra handles to understand GNN performance.
- Per event classification is mediocre.
- **Fitting** score distributions looks promising for improving accuracy.



Distribution fits

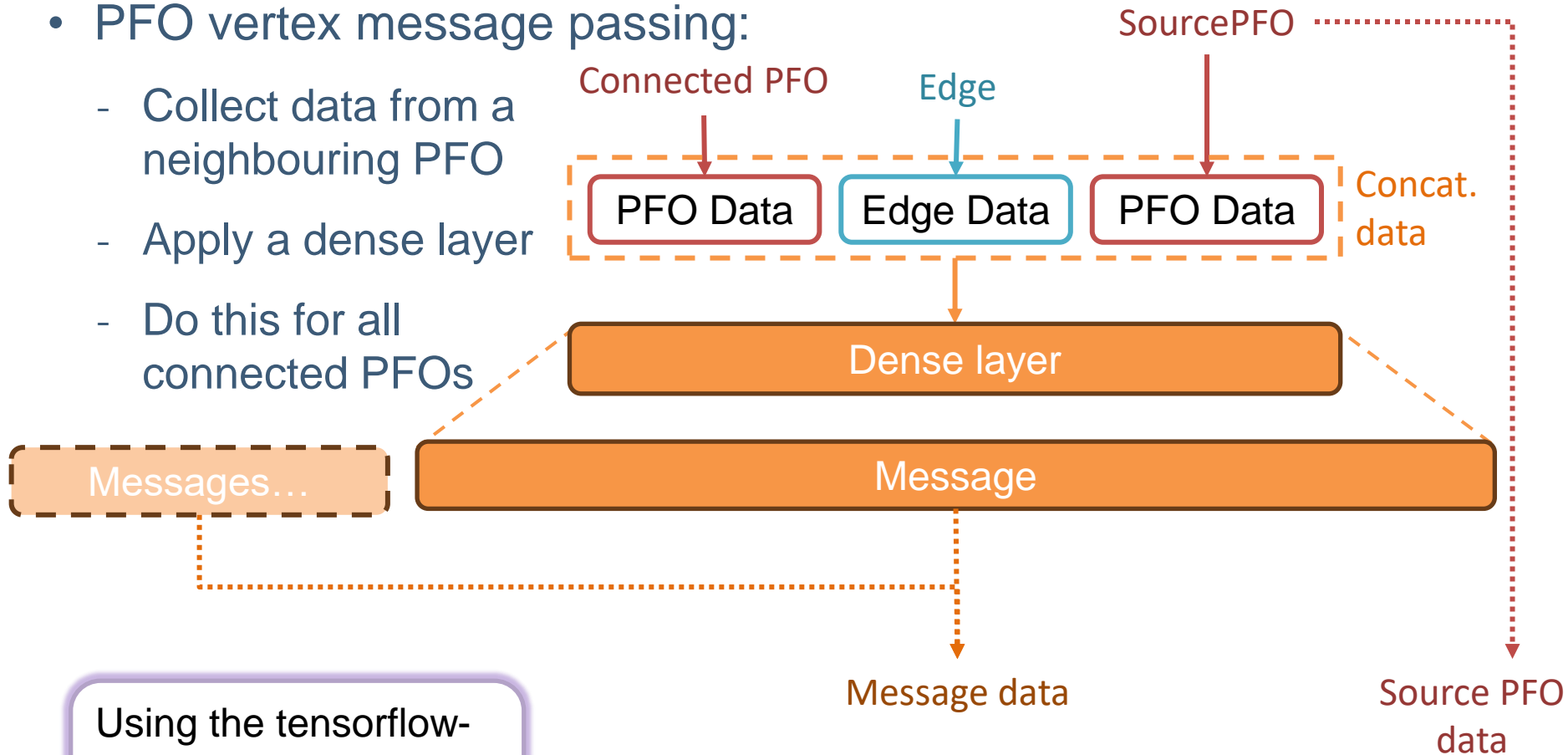


Back-up

Graph Neural Networks

- PFO vertex message passing:

- Collect data from a neighbouring PFO
- Apply a dense layer
- Do this for all connected PFOs

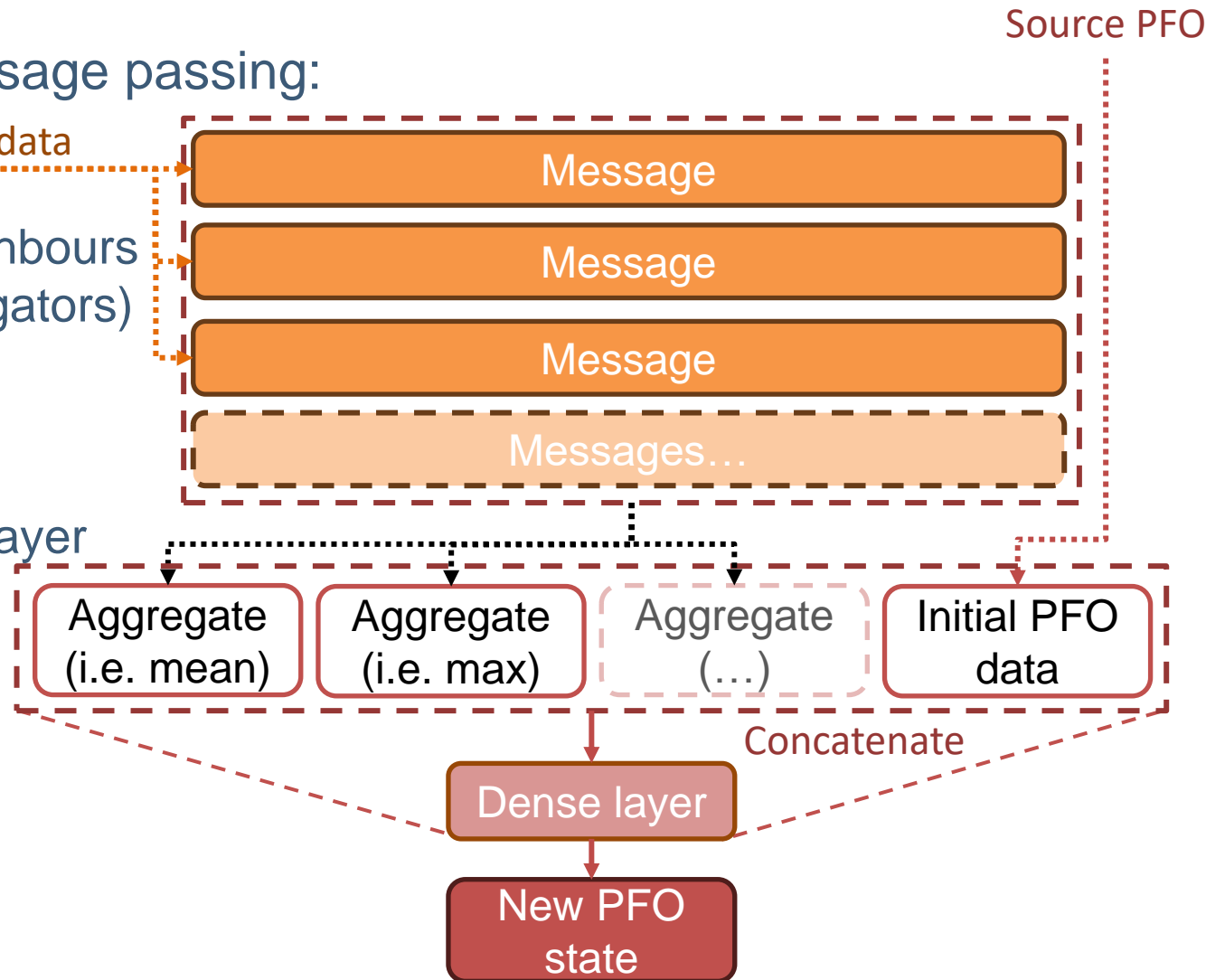


Using the tensorflow-gnn python package.
[arXiv:2207.03522](https://arxiv.org/abs/2207.03522)

Graph Neural Networks

- PFO vertex message passing:

- ... Message data
- Aggregate neighbours (multiple aggregators)
- Concatenate aggregations
- Apply a dense layer
- Update state



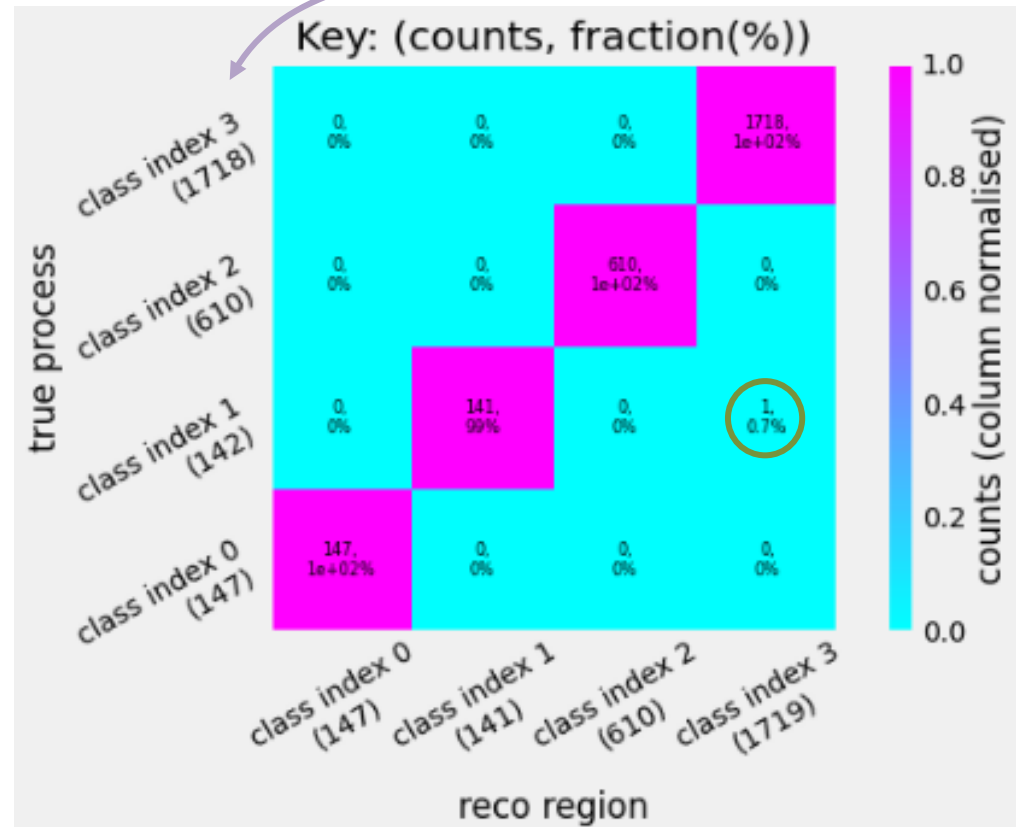
Principle Neighbour Aggregation:

[arXiv:2004.05718](https://arxiv.org/abs/2004.05718)

Monte-Carlo performance

- Perfect (MC) information can achieve perfect classification (1 misclassification here).
- With MC data, this can even be achieved without any message passing steps.
 - Look once at the PFOs surrounding the beam.
 - Don't have to infer any information.

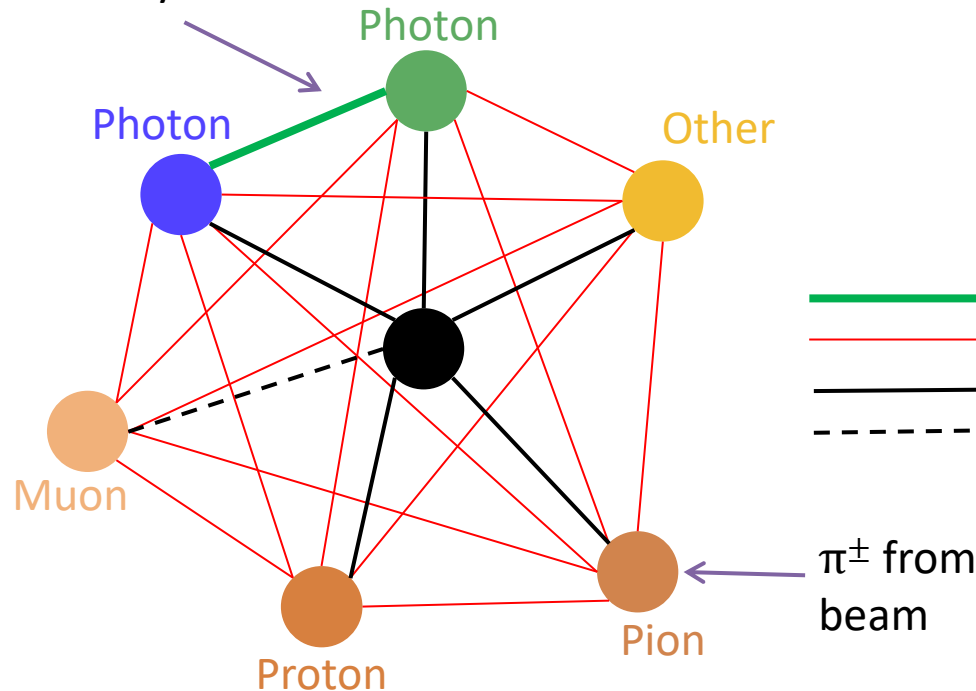
- 3: Multi-pion production
- 2: Single pion production
- 1: Charge exchange
- 0: Absorption



Example graph

- Example Monte-Carlo event graph.
- Can we determine the classification?

Probably a π^0



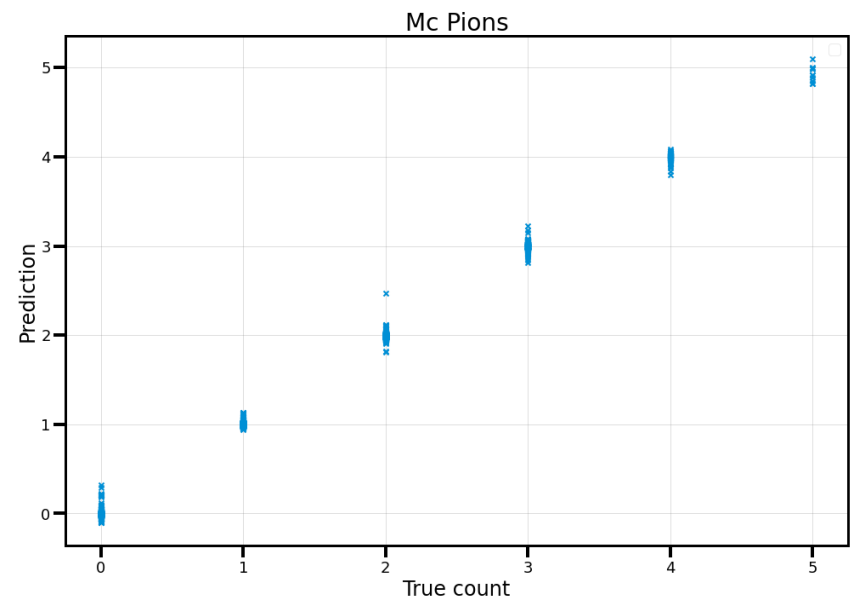
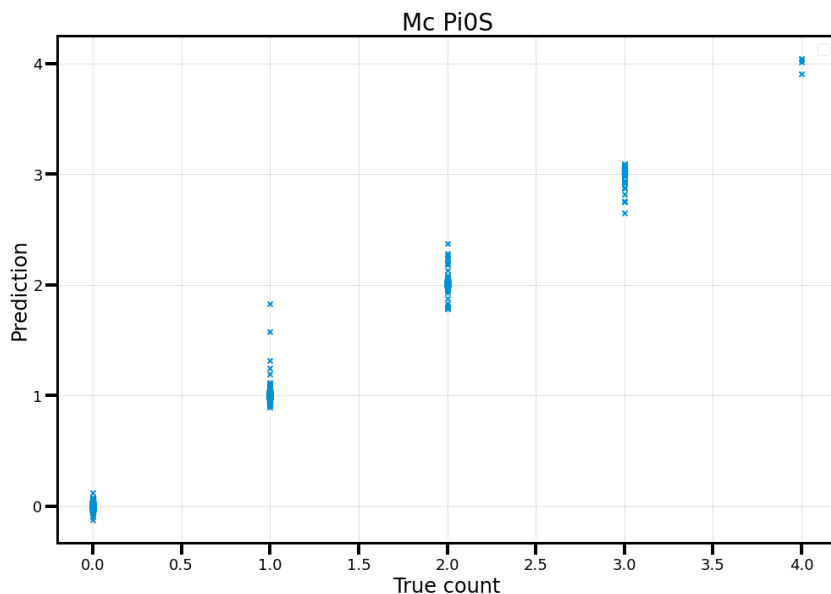
- Share a mother particle
- No shared mother
- Beam related
- - - Not beam related

	π^\pm s	π^0 s
Abs.	0	0
CEx.	0	1
1 pi	1	0
Multi.	otherwise	

1 π^0 and 1 π^\pm :
This is multiple
pion production

Interpretability

- Add an output to the network which aims to count the π^\pm/π^0 s.
- These are trained with a regression loss (mean absolute error) against the true π^\pm/π^0 count in the event.
- Can this help us understand the network's weaknesses

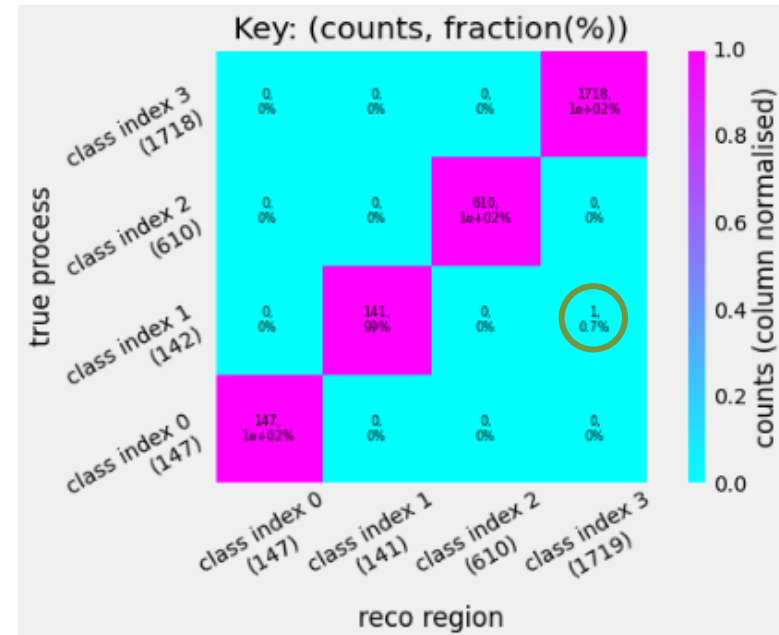
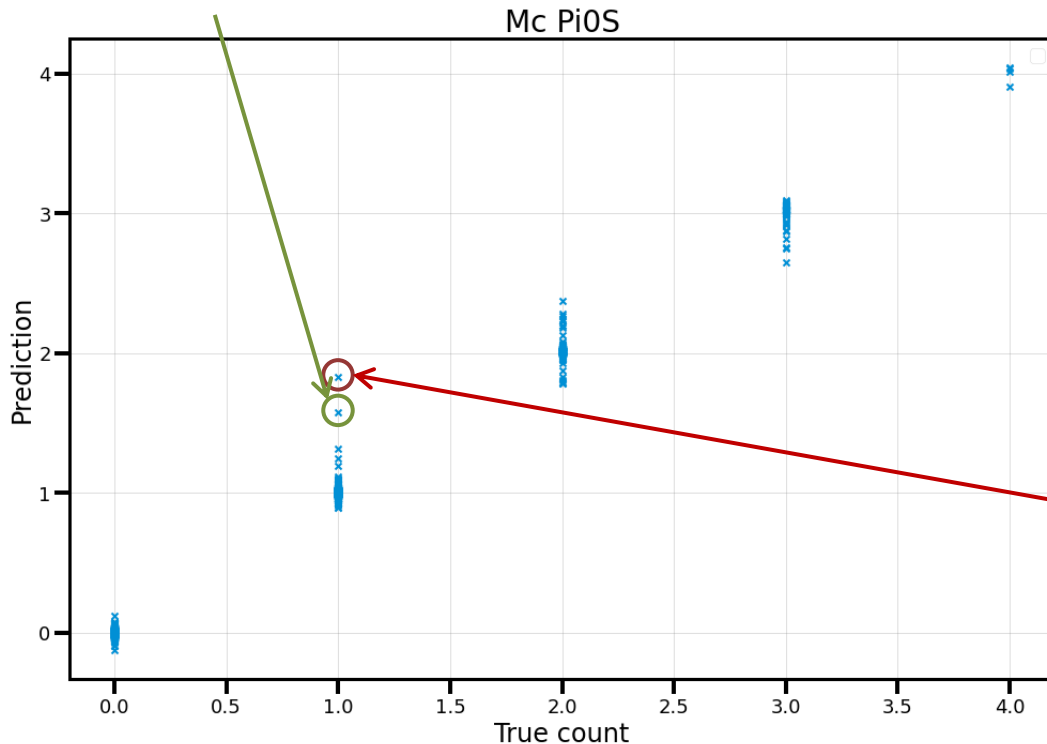


Interpretability

- 3: Multi-pion production
- 2: Single pion production
- 1: Charge exchange
- 0: Absorption

- Recall the trained model had a misclassified event.
- Which event is this in the particle counts?

This is the misclassified event!



This event was already multiple pion production (the number of pions is already >2, so an additional pion doesn't change region)

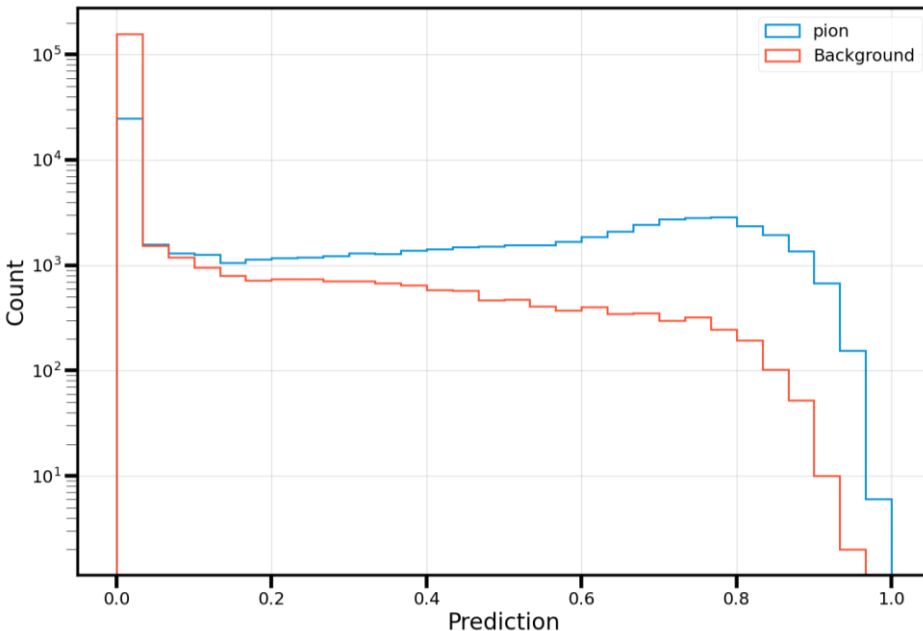
Network structure

- Message passing step:
 1. PFO update (update PFO states from neighbour PFOs)
 2. Neighbour update (update edges based on connected PFOs)
 3. **Beam collection** (update the beam vertex with PFO information)
- 1. Set initial state (apply a dense layer to input features)
- 2. **Beam collection**
- 3. Message passing (x2)
- 4. Readout **beam state** (get the data in the beam vertex)
- 5. **Classifier** layers (dense layers to make a 4-component output)
 - Loss: focal categorical crossentropy

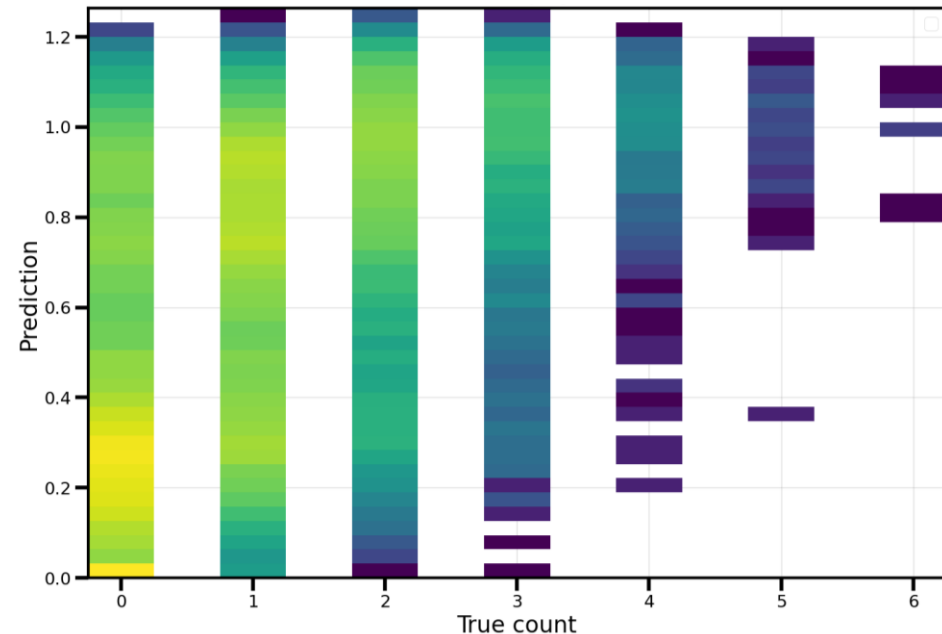
Reconstructed performance

- Primary failure modes seem to be:
 - Bad π^\pm classification
 - Distinguishing 1 and >1 particles present

Pion identification on graph nodes

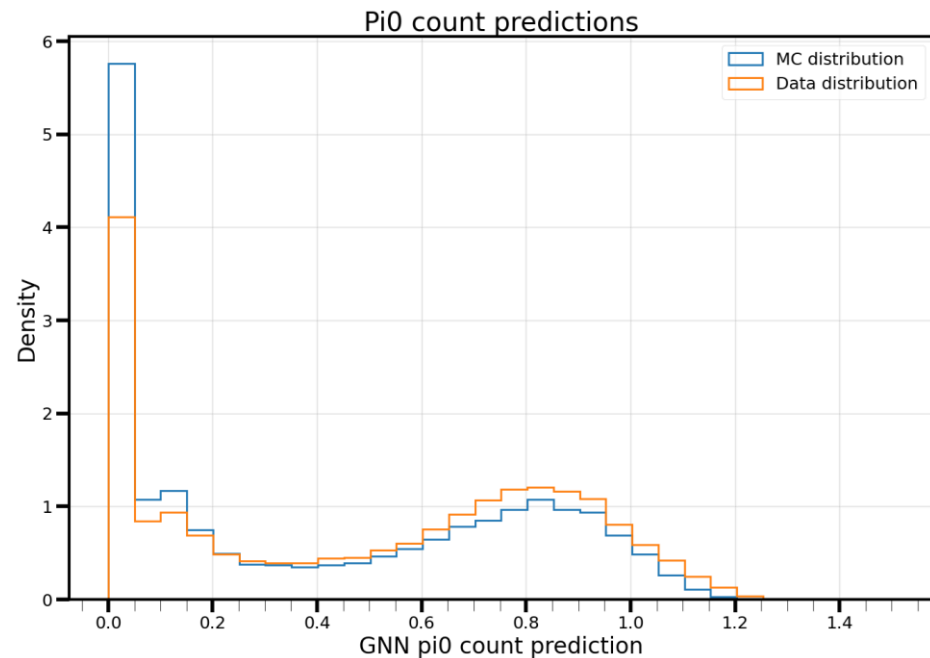
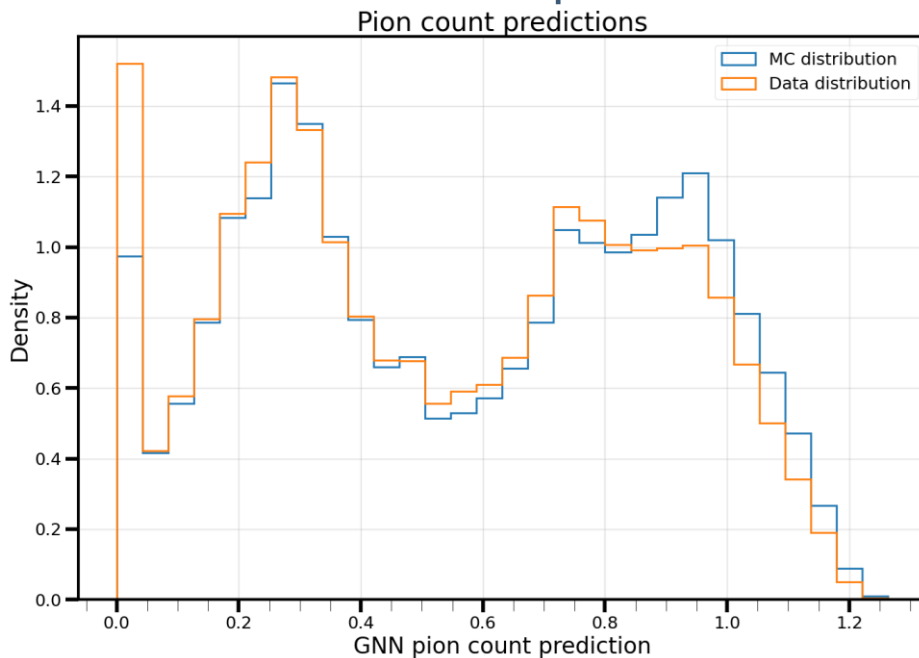


Reconstructed pion count predicted per event



Checks - data

- The predictions of π^\pm / π^0 counts are separate outputs from the same GNN which performs classification.
- Can investigate similarity by comparing these outputs in data and MC – **will the templates be valid?**
 - Want to find a quantitative test...



Checks - energy dependance

- The templates should **not depend** on the energy of the interaction.

