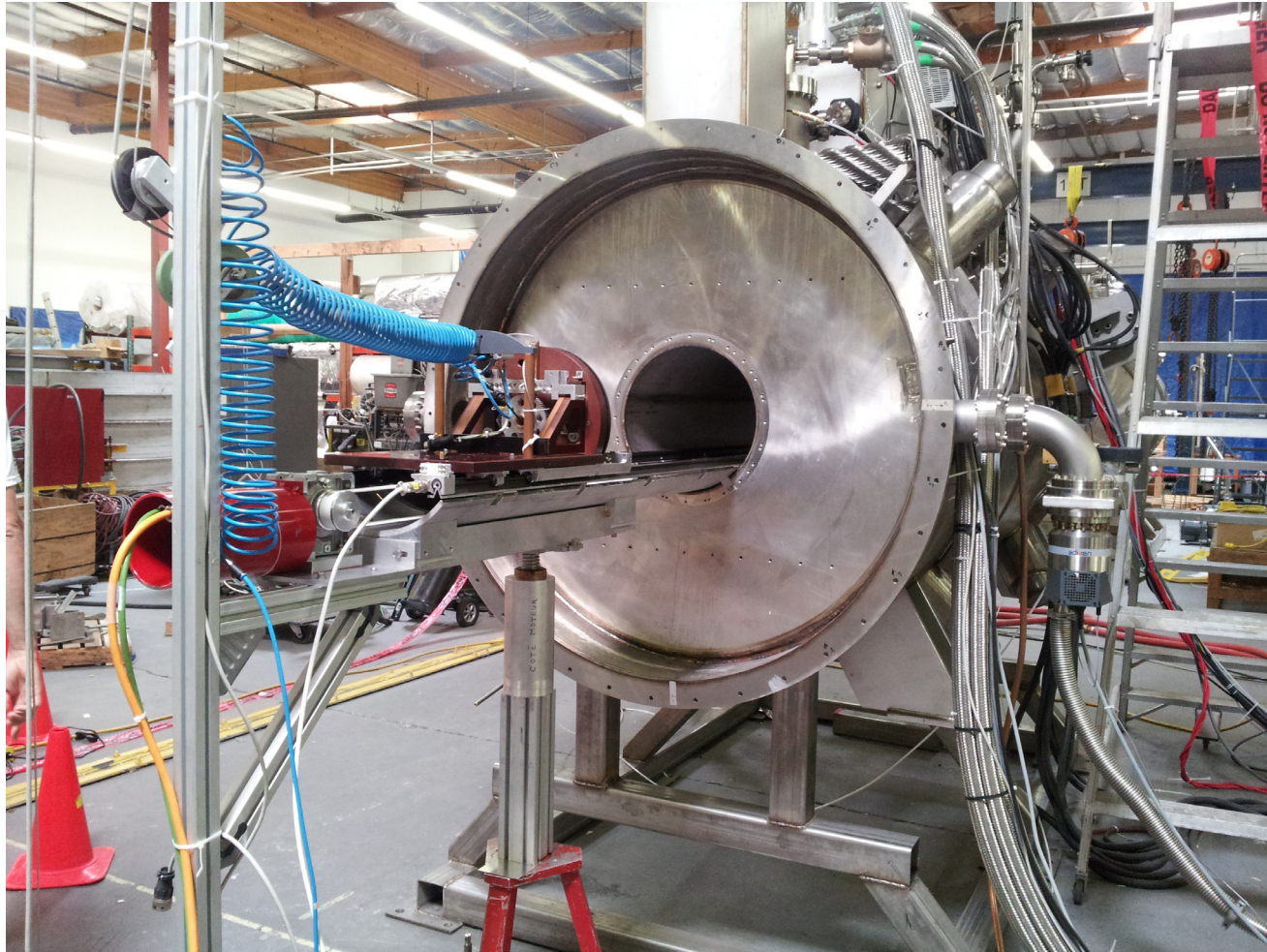
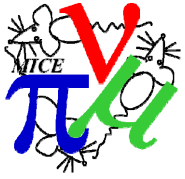


SS2 Field Measurements



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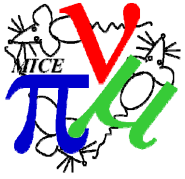


SS2 Field Measurements



Topics

- Survey
- Mapping Device Operation
- Overview of Field Measurement Studies
 - Completed Studies
 - Plan for this week



SS2 Field Measurements

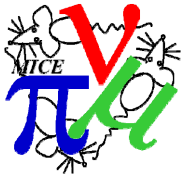


➤ Survey

5 June – without the shield plate

12 June – with the shield plate

- Surveyed of fiducial markers:
 - done from 4 stations to get the best fit
 - establish a coordinate system with
 - X axis along the cold mass axis (beam axis)
 - Z axis vertical
 - Y axis completes (x,y,z) right coordinate system
- origin at the DS end of cold mass
- Mapping Device measurements:
 - mapper axis as the disk moved through the magnet
 - both rails to get disk rotation as it moves through the magnet
- Calibration of longitudinal positions vs. encoder of the Mapping Device
 - 50 cm steps
 - 2 cm steps



SS2 Field Measurements

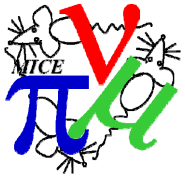


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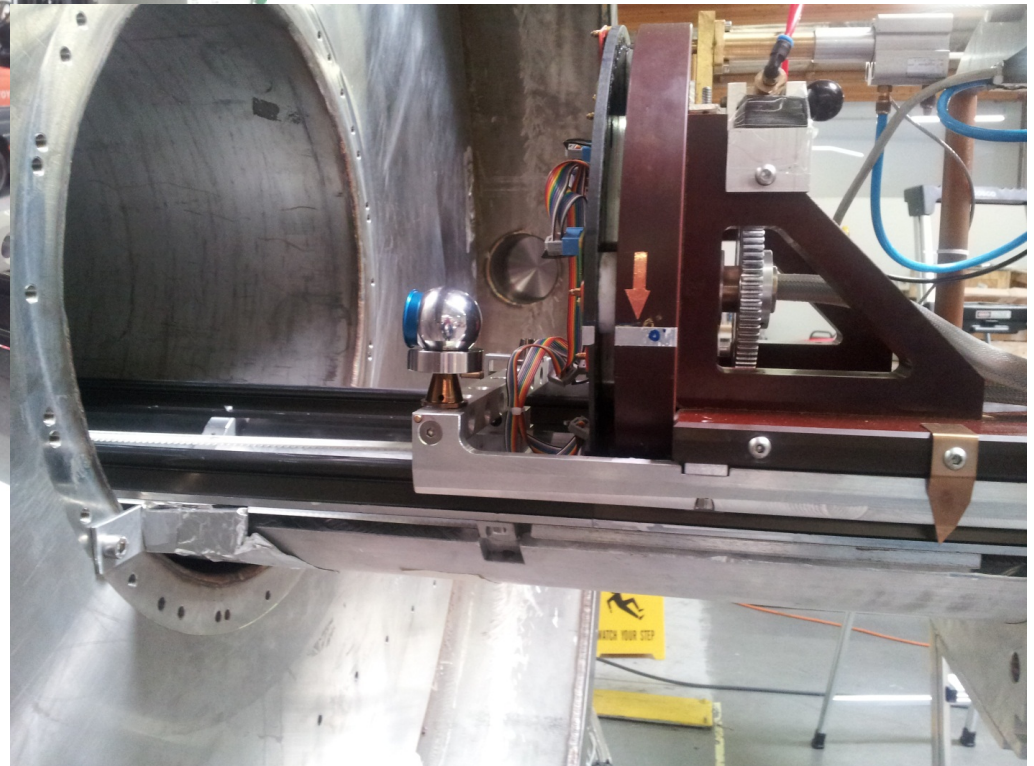
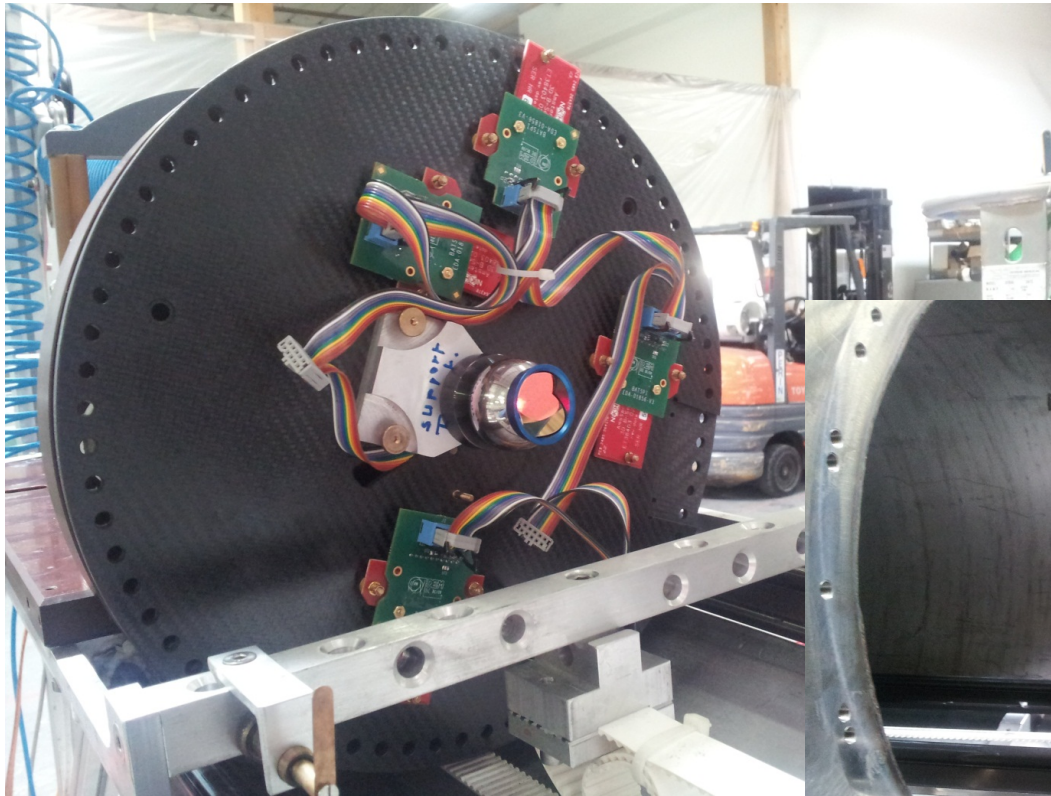
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All supports are not welded to the magn. Note the clamp being



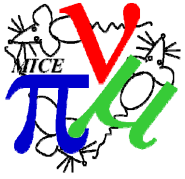
SS2 Field Measurements



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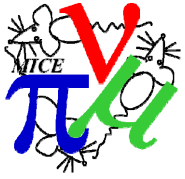
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SS2 Field Measurements



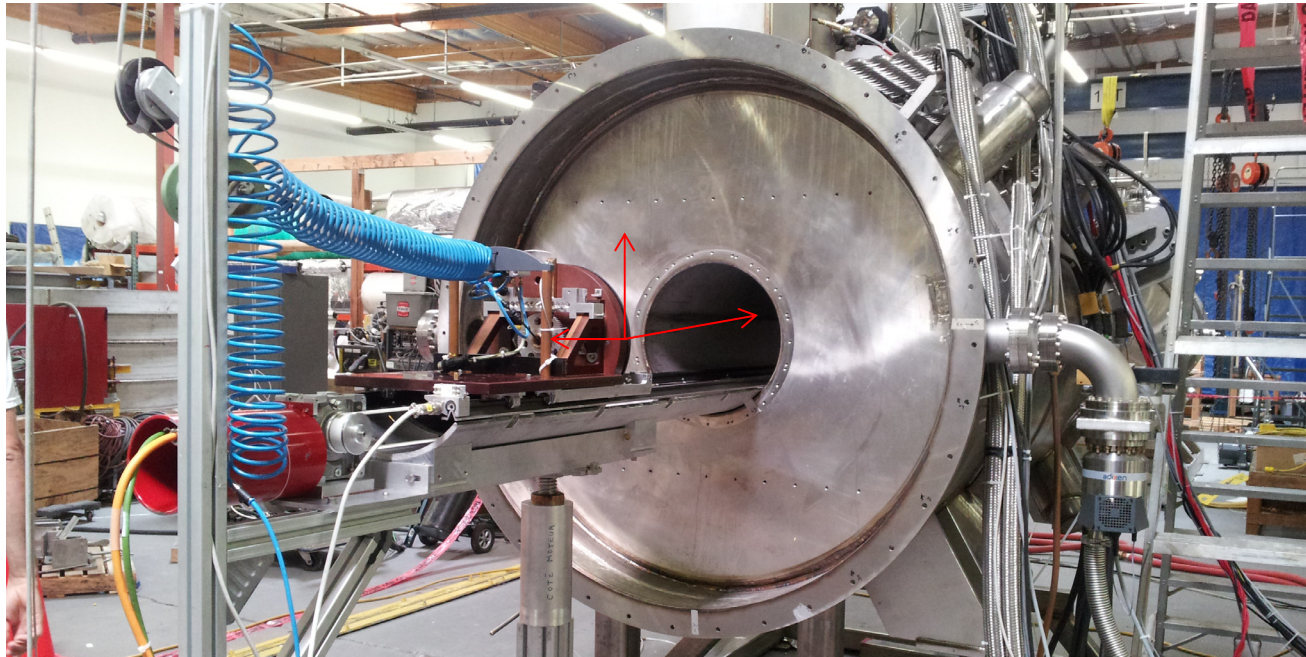
- Surveyed of fiducial markers:
 - initial measurements indicated fiducials shifted by few mm, especially on the US end of the magnet, probably due to welding done after fiducialization, magnet being under vacuum, and cold.
 - measurements after shield plate installation agreed to $\sim 10 \mu\text{m}$
- Mapping Device measurements:
 - maximum deviation of mapper axis from straight line fit was $\sim 0.5 \text{ mm}$, with rms deviation $\sim 0.3 \text{ mm}$
 - for mapping next magnet Pierre-Auge will make shims for aligning the device
 - measurement of the rails indicated they moved \sim together
- Calibration of longitudinal positions vs. encoder of the Mapping Device
 - indicated encoder calibration shift of 0.8 mm over 5 m



SS2 Field Measurements



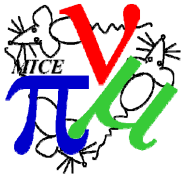
➤ Mapping Device



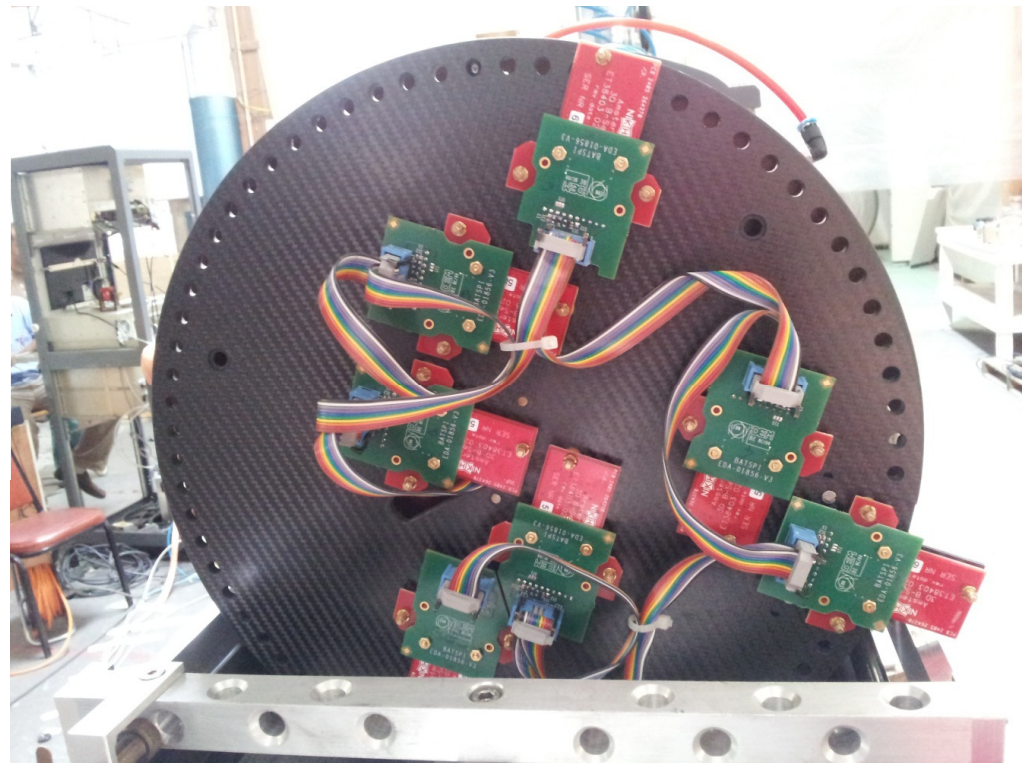
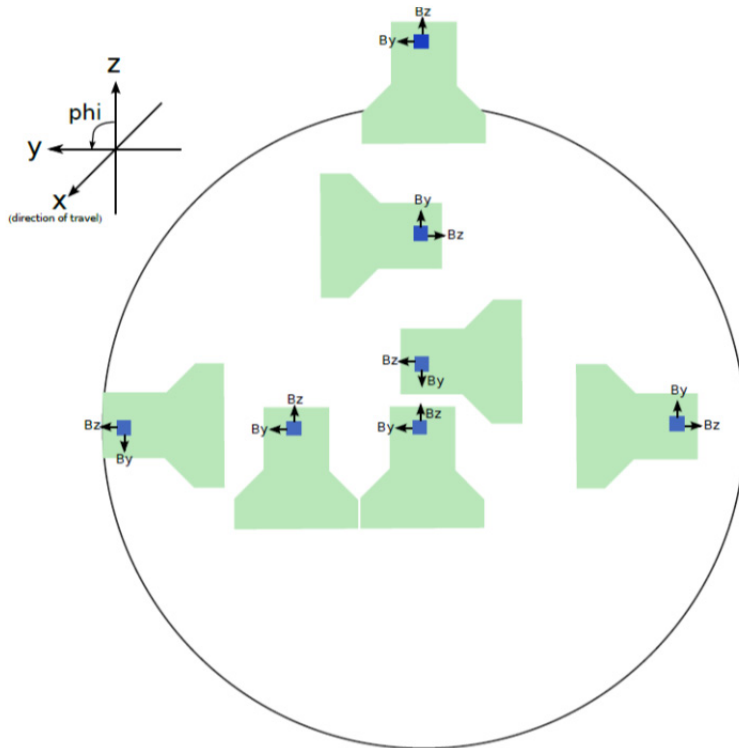
X axis along the magnet on direction opposite to beam direction

Z axis vertical

Y axis completes (x,y,z) right coordinate system



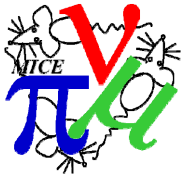
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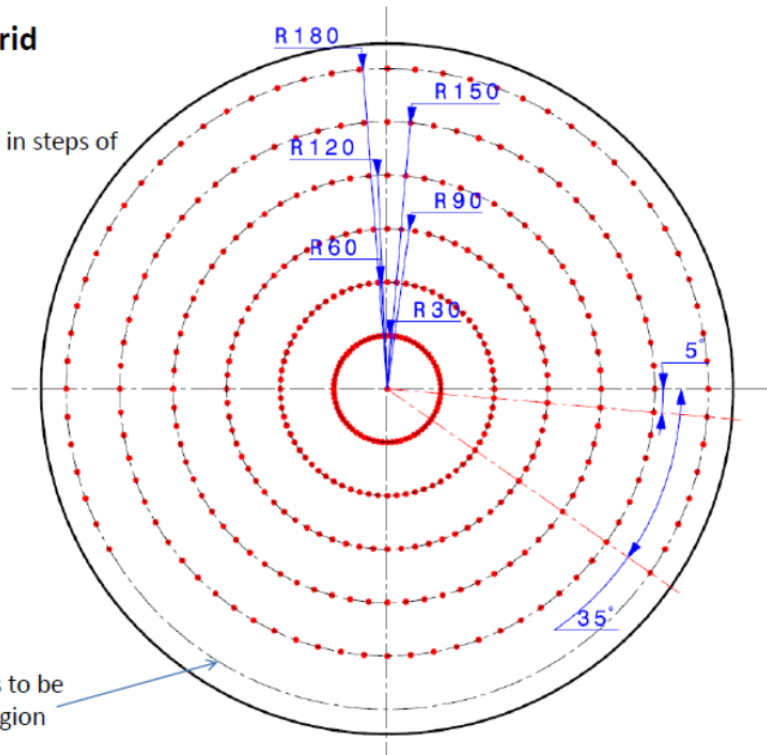


SS2 Field Measurements

Measurement grid

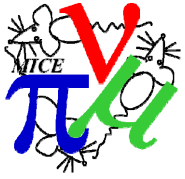
Disk can be rotated in steps of 5 degree

180 mm sensor has to be removed for this region



Two main modes of mapping:

- “fast” map:
5-cm longitudinal steps
4 disk rotation positions:
0° & 180° and 40° & 220°
- “full” map:
2-cm longitudinal steps
20° disk rotation steps



SS2 Field Measurements

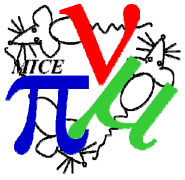
➤ Overview of Field Measurement Studies

- Completed Studies

no shield plate:	“fast” maps at	80% current (in Solenoid Mode for 240 MeV line settings)
		95% current
		80% current
		50% current
with shield plate:	“fast” maps at	50% current (in Solenoid Mode for 240 MeV line settings)
		80% current
		80% current after the magnet was at 98%
		0 current
	“full” maps at	10 A in coils
		0 current
		0 current
		100% current (in Solenoid Mode for 240 MeV line settings)
		0 current
		100% current (in Flip Mode for 240 MeV line settings)
		0 current

- Plan for this week

no shield plate:	“full” maps at	80% current (in Solenoid Mode for 240 MeV line settings)
		80% current (in Flip Mode for 240 MeV line settings)
		0 current
	“fast” maps of individual coils at ~ 30 A	

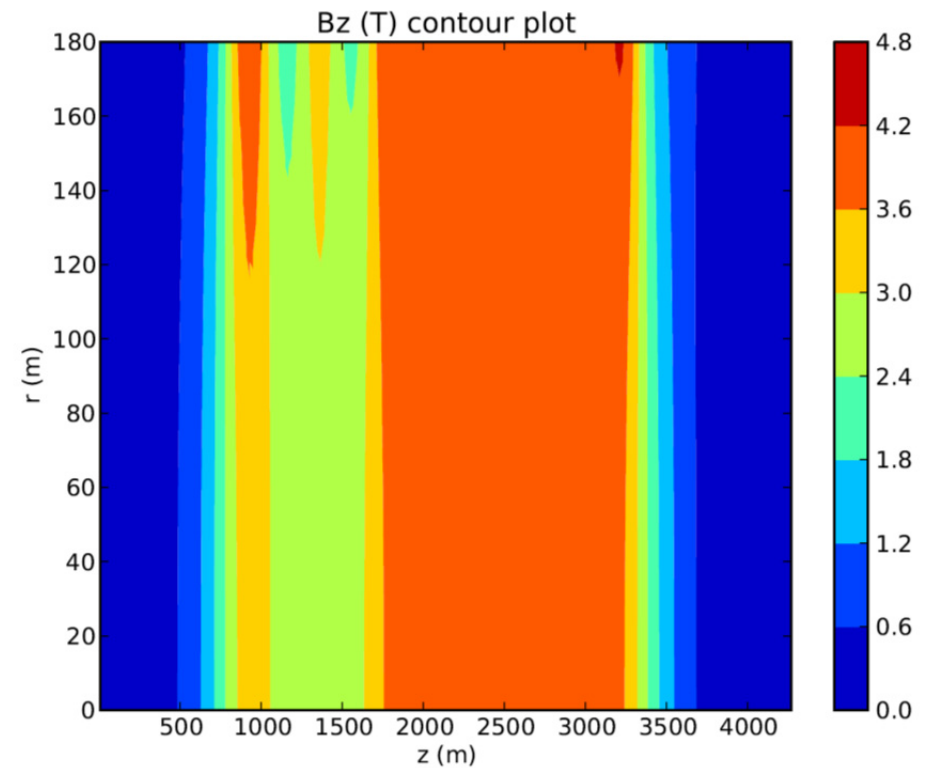
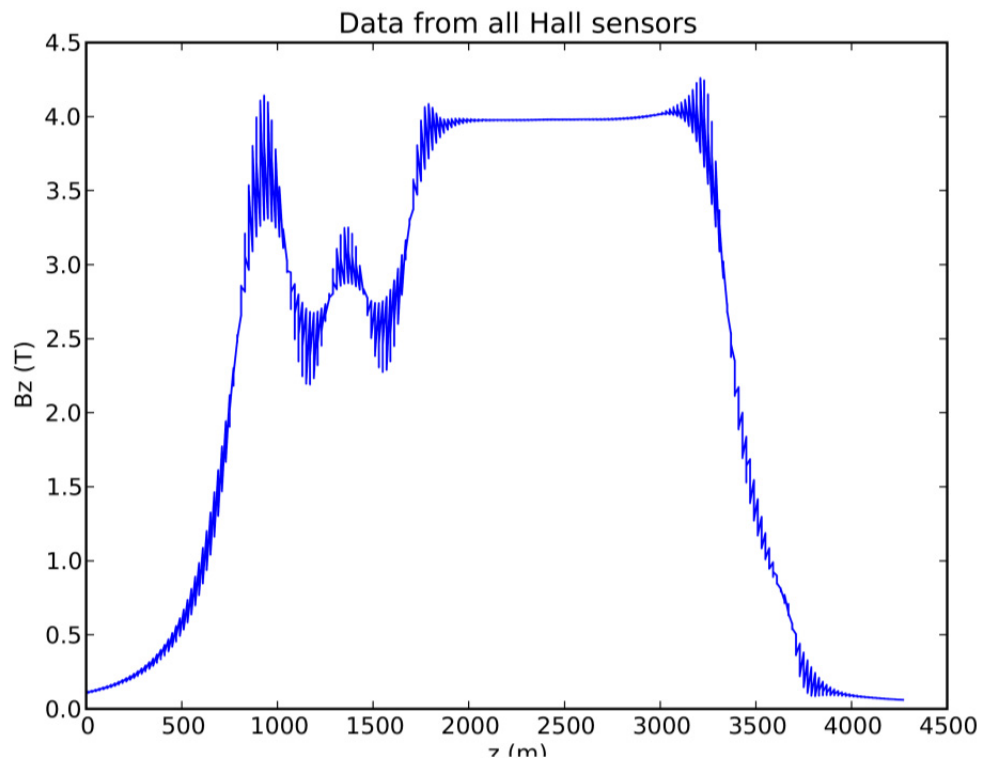


SS2 Field Measurements



Full Maps at 100% current with shield plate:

Solenoid mode



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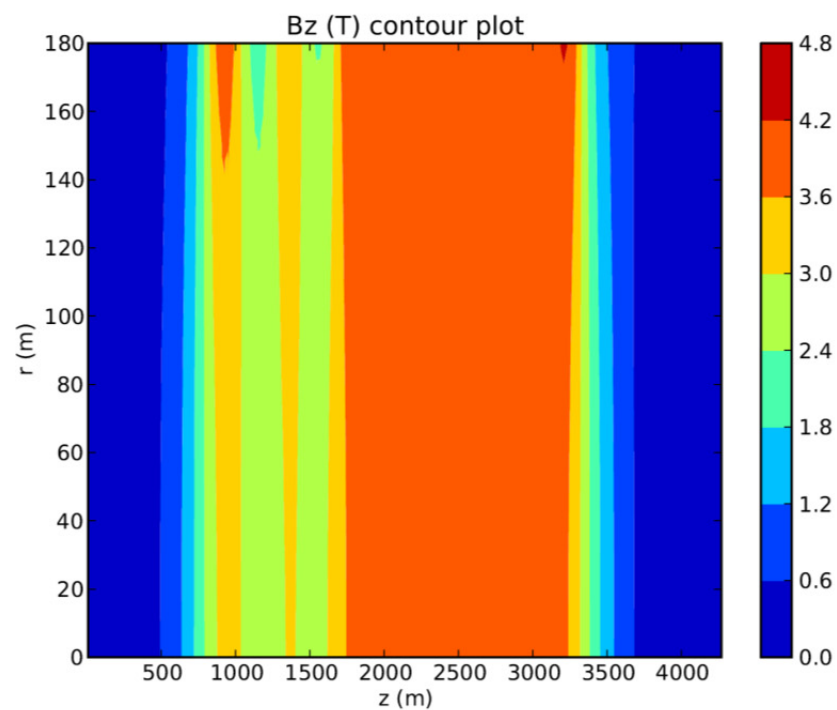
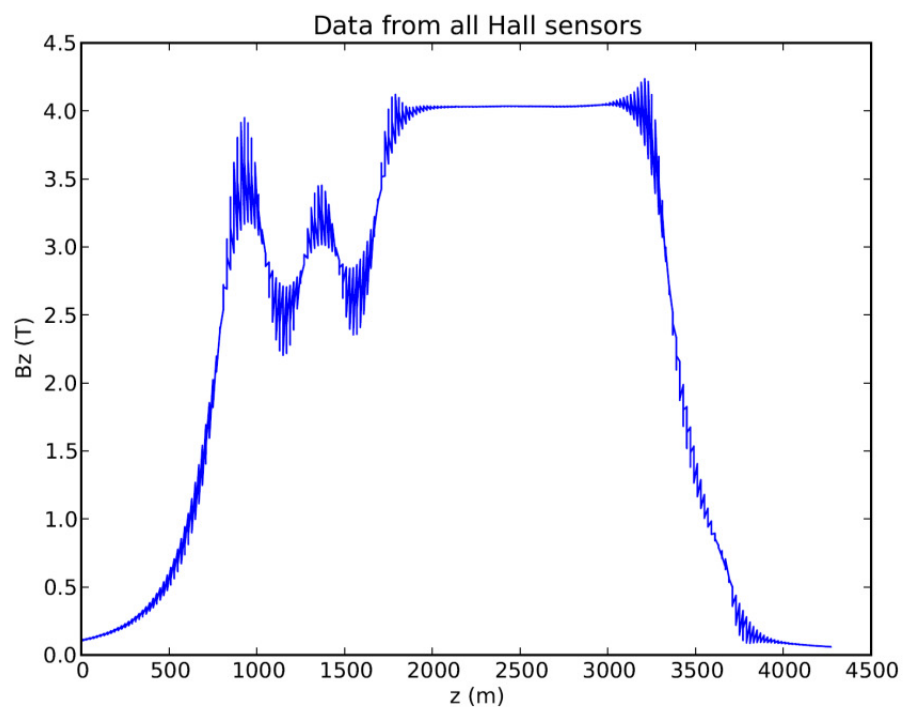


SS2 Field Measurements



Full Maps at 100% current with shield plate:

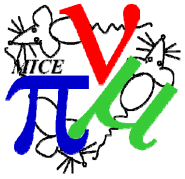
Flip mode



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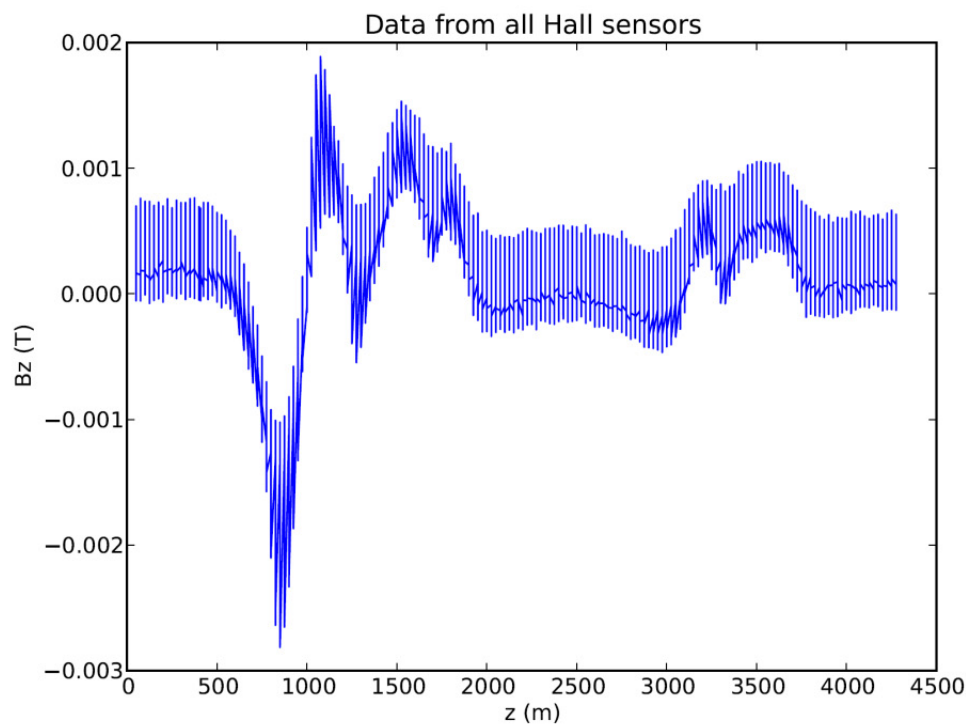


SS2 Field Measurements

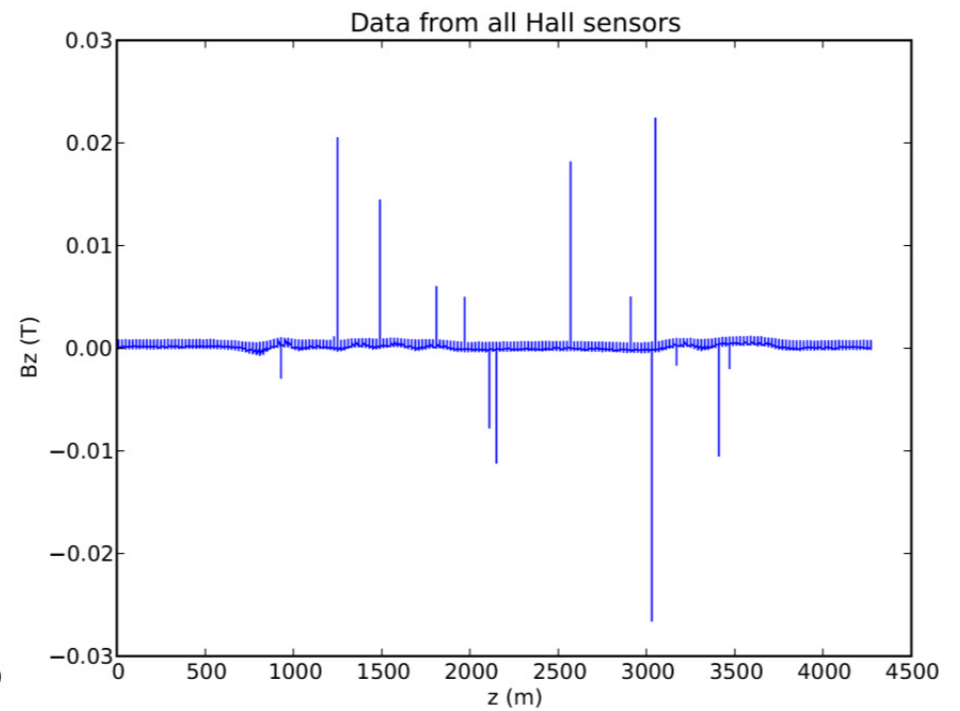


Maps at 0 current with shield plate:

10 June



14 June



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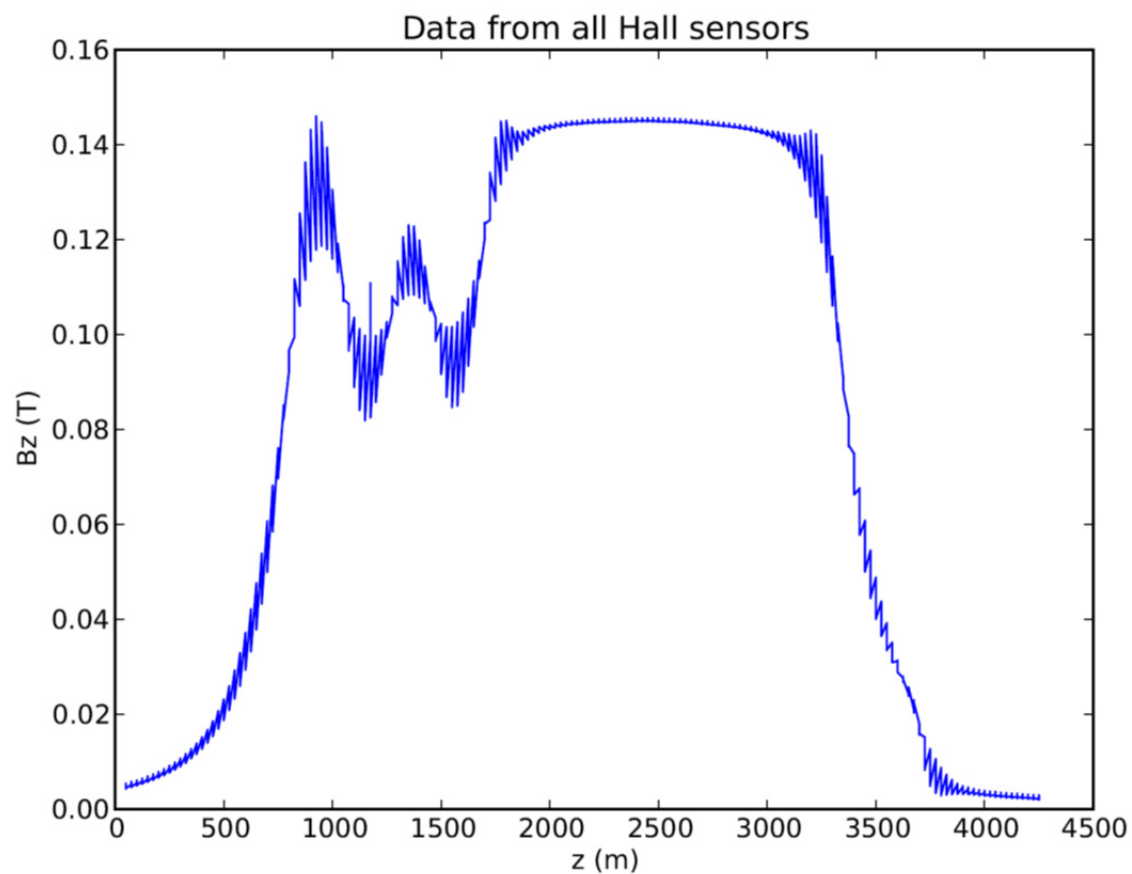
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SS2 Field Measurements

Map at 10A in M1, M2, C coils and 8A in E1, E2 coils with shield plate



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