

ELECTROMAGNETIC DESIGN

CONDUCTION COOLED SSR MAGNET ASSEMBLY FOR PIP-II (FDR – Phase I)

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- Introduction
 - BARC contribution for LINAC magnets in PIP-II technology map
- Electromagnetic Design of Conduction cooled magnet
 - Functional requirement specification
 - EM design for main solenoid
 - Corrector coil design
 - Fringe field on the cavity surface
 - Bucking coil optimization & tolerance studies on BC dimensions
 - Tolerance studies on bucking coil
 - Superconducting wire selection
 - Magnet load line & design operating margin
- Quench Studies
 - Quench initiated in main coil (variation in heat pulse, coil configuration & quench location)
 - Quench initiated in Bucking coil
 - Quench protection circuit

Magnet Contribution- PIP-II LINAC Technology map



*Warm doublets external to cryomodules

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Pre-series magnet testing

Axial Magnetic field map





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Functional Requirement Specifications (FRS)

| Primar | y Design o | objectives: |
|--------|------------|-------------|
| | | |

- High Field (focusing strength)
- Low stray field as fringe field level on the adjacent spoke cavity surface is a major concern.
- Dipole field and skew quadrupole field coils incorporated in the same magnet package.

| Parameters | SSR1/SSR2 New specification (Ver 2.) | SSR1/SSR2 New specification (Ver.3) |
|--|--------------------------------------|-------------------------------------|
| Focusing Strength | 4.5 T ² m | 4.5T ² m |
| Bending strength of Dipole correctors | 5 mT-m | ≥6.0 (5.0) mT-m |
| Beam pipe aperture | 40 mm | 40 mm |
| Uncertainty in the location of magnetic axis w.r.t Reference points (Transverse and angular alignment) | <0.1mm RMS <0.5 mrad RMS | <0.1mm RMS <0.5 mrad RMS |
| Effective length of solenoid (FWHM) | <18cm | <18.5cm |
| Active magnetic shielding requirements | ~ <10G | ~<10G |
| Maximum current in the solenoid | 100A | 90 A |
| Maximum current in the dipole correctors | 50 A | 12 A |

Arrangement of magnet assemblies in cryomodule



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Electromagnetic Design





• Peak magnetic Field is given by:-

$$B_0 = JaF(\alpha\beta)$$

Where

$$F(\alpha\beta) = \mu_0 \beta \ln \left\{ \frac{\alpha + (\alpha^2 + \beta^2)^{\frac{1}{2}}}{1 + (1 + \beta^2)^{\frac{1}{2}}} \right\} \quad and \quad \alpha = \frac{b}{a} \quad , \qquad \beta = \frac{l}{a}$$



• The magnetic field (B_w) responsible for determining critical current density is close to the winding is proportional to B_0 .

 $\mathsf{B}_{\mathsf{w}} \mathsf{=} \mathsf{c}_0 \: \mathsf{B}_0$, where c_0 is a function of shape factor α and β .

• The magnetic field on axis of the solenoid is given by:-

$$B_{z} = \frac{1}{2} Ja \{ F(\alpha, \beta_{1}) + F(\alpha, \beta_{2}) \}$$

where

$$\beta_1 = \frac{(I-z)}{a}$$
 and $\beta_2 = \frac{(I+z)}{a}$



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B_A

B_w

b

а



Focussing strength and spherical aberration

• Focussing strength:

$$k^2 = \left(\frac{q\,B}{2mc\gamma\beta}\right)^2$$

Focusing strength 4.42

• Effective length:

$$l = \frac{1}{B_0^2} \int_{-\infty}^{\infty} B^2(z) \, dz$$

• Spherical aberration:

$$C_s = \frac{1}{2} \frac{\int \left(\frac{dB_z}{dz}\right)^2 dz}{\int B_Z^2 dz}$$



Spherical coil aberration 71.15982352



Electromagnetic Design

Configuration 2: Configuration 3: Configuration 1: Good axial field uniformity Less axial field uniformity No extra benefit in spatial occupancy More longitudinal foot print Optimized axial and longitudinal footprint X X



Electromagnetic Design

| Sr. no | Parameter | Value | Unit | Operating current 78A |
|--------|--|------------|------|---|
| 1. | Length of solenoid coils in the lens | 140 | mm | |
| 2. | Main coil inner radius | 38 | mm | |
| 3. | Main coil outer radius | 75 | mm | ais to a second and a second |
| 4. | Strand diameter bare (with insulation) | 0.51(0.55) | mm | |
| 5. | Winding fill factor | 0.85 | | |
| 6. | Number of turns in the main coil | ~14554 | | |
| | | | | Objective function : |
| Sr. no | Parameter | Value | Unit | $\int B_z^2 dz \geq 4.5 \mathrm{T}^2 \mathrm{m}$ |
| 1. | Length of Bucking Coils | 64 | mm | Minimize $\int^{r=0.3} B. dl$ at z= 0.42m cavity location |

| Sr. no | Parameter | Value | Unit |
|--------|-------------------------------------|------------|------|
| 1. | Length of Bucking Coils | 64 | mm |
| 2. | Bucking coil inner radius | 100 | mm |
| 3. | Bucking Coil outer radius | 112.5 | mm |
| 4. | Strand diameter | 0.51(0.55) | mm |
| 5. | Bucking Coil Z location* | 38 | mm |
| 6. | Winding fill factor | 0.85 | |
| 7. | Number of turns in the Bucking coil | ~2247 | |
| | | | |

| Optimization Parameters: |
|--|
| N _{main} , OR _{main} , IR _{main} , IR _{BC} , OR _{BC} L _{BC} , Z _{center-BC} |

Effective length \leq 185 cm +/- 30mm ; I _{exc} < 90A

Constraints:

Electromagnetic Design... continued



B_{mod} field vs axial distance plot



Electromagnetic design ... continued





Dipole corrector design

| Sr. no | Parameter | Value | Unit |
|--------|---|-----------|-------------------|
| 1. | Straight Length of Dipole corrector coils (H1) | 10 | mm |
| 2. | Width cross-Section in radial direction | 15 | mm |
| 3. | Thickness cross-section in azimuthal direction | 35 | mm |
| 4. | Radius of the Mandrel (R1) | 80 | mm |
| 8. | Strand diameter (bare/insulated) | 0.51/0.55 | mm |
| 9. | Number of turns in the dipole corrector coil | ~1475 | |
| 10. | Operating current density at nominal bending strength | 28 | A/mm ² |
| 11. | Winding fill factor | ~0.85 | |

| Sr. no | Parameter | Value | Unit |
|--------|---|--------|------|
| 1. | Designed value of Bending strength of corrector coils | 6.3 | mT-m |
| 2. | Peak Magnetic field on the corrector coil wire strand | 2.8 | Т |
| 3. | Quadrupole Gradient in skew Quadrupole mode | 3.25 | T/m |
| 5. | Nominal current | ~10 | А |
| 6. | Transfer function of the corrector coils | 0.1525 | mT/A |

Corrector coils used in space between the main solenoid and active shielding coil to reduce the operating current requirement







Dipole corrector design ... continued



Magnetic Field plot for the dipole field (Dipole field Integral 6.3 mT-m)

Operating current ~10A

Zonal field plot of dipole field at the magnet center

Dipole Corrector design (Quadrupole mode)





Fringe field on cavity surface

Completely defined by the properties of superconducting material

| | | $\Phi_{tr} = \frac{2\mu_0 \Phi_0}{(Rs; \xi_0^2)} * \frac{f \cdot V}{(\Lambda Q_0)} * \frac{(1-\eta)}{\eta}$ |
|--------------------------|--|---|
| T-13800PSSR1and2FLCL-109 | When the focusing lenses are powered, the field should be less than 10 G at the outer surfaces of the adjacent cavity, or an imaginary circle which is centered on the beamline axis, having a diameter of 0.70m, 0.42m distance from the center of the magnet. | Acceptable deg degradation η allowed amount |
| | | trapped flux. |

Placement of a focusing lens inside the SSR cryomodule



 $\mu_0 = 4\pi \cdot 10^{-7}$ H/m; $\Phi_0 = 2 \cdot 10^{-15}$ Wb

 ξ_0 =3.9·10⁻⁸ m is the coherent length in Nb, f is the frequency of the cavity,

Cavity Specific

dearee

of

of

with

the

Rs is the surface resistance of Nb at this frequency,

V is the volume of the cavity,

 $\Lambda = \frac{\text{Magnetic energy density at the location of the quench}}{\text{Average energy density in the cavity}}$

Surface integral / line integral at the maximum magnetic energy density location needs to be minimized during the design of bucking coil



Bucking coil optimization



B field vs axial distance plot for different cases of Bucking coil dimensions



Tolerance studies on bucking coil geometrical parameters

- > Tight tolerance is required for the bucking coil winding dimensions and its placement w.r.t main coil.
- > The positional inaccuracy of the Bucking coil effects the fringe magnetic field on the cavity surface.

Effect on fringe field level at different axial position of the Bucking coil w.r.t Main coil

| | Sr. no | BC-Coil IR | BC-Coil OR | BC-Coil L | BC-Coil Z center | B max On cavity surface | Field Surface Integral at Axial distance of 0.42 m) | |
|---|--------|------------|------------|-----------|------------------|----------------------------|---|----------|
| | | mm | mm | mm | mm | Gauss | G-m ² | |
| | 1. | 100 | 112.5 | 64 | 38 | 7.33 | 2.47 | 1 |
| | 2. | 101 | 113 | 64 | 38 | 11 | 1.908 | |
| | 3. | 101 | 114 | 64 | 38 | 20 | 6.79 | |
| | 4. | 99 | 112 | 64 | 38 | 12 | 6.018 | |
| í | 5. | 100.5 | 113 | 64 | 38 | 8.89 | 2.988 | <u> </u> |
| | 6. | 102 | 115 | 64 | 38 | 25 | 8.42 | - |

Two probable cases for detailed analysis

Error Sensitivity studies – Case (a)



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Error Sensitivity studies ...continued Case (a)



Error Sensitivity studies – Case (b)



Error Sensitivity studies ... continued – Case (b)





Validation with alternate solvers



B field vs axial distance plot for +/- one layer of bucking coil



Validation with alternate solvers



Radial field plot at cavity location for case (a)





Radial field plot at cavity location for case (b)



Surface plot at Cavity location

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Combined-field-All coils-powered-on





 All conduction cooled magnets are proposed to be wound using round 0.5 bare diameter /0.54 mm insulated strand (NbTi/ copper matrix 1:2 Sc:Cu Ratio).

| Bare Wire | Filament | Cu/Sc Ratio | Filament | RRR | lc @ 3 T , | lc @ 5 T | Ic @ 7 T , | Ic @ 9 T , |
|-----------|----------|-------------|-------------|-----|------------|----------|------------|------------|
| Dia | Diameter | | twist pitch | | 4.2K | , 4.2K | 4.2K | 4.2K |
| 0.51mm | | 2:1 | | 70 | 240 A | 140A | 105A | 32A |
| | | | | | 2 | | | |

$$B_{CT} = B_{c0} \left(1 - \left(\frac{T}{T_{c0}} \right)^2 \right)$$

The ratio of the maximum current density in the superconductor at any magnetic field and temperature to that at B = 5 T and T = 4.2 K can be found using the expression given below:

 $Jc(B,T) / Jc(5 T, 4.2 K) = CO/B \cdot b^{\alpha} \cdot (1-b)^{\beta} \cdot (1-tn)^{\gamma}$

Where, $C_0 = 28.4$ T, $\alpha = 0.80$, $\beta = 0.89$, and $\gamma = 1.87$.

BARC Superconducting Wire strand material properties



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Comparing the manufacturer's data it is clear that practically there is a margin of ~ 35A @ 4.2K

BARC Magnet load line – Pre-series Magnet design (0.4mm bare dia wire)



Practically no Margin @ 4.2K ~ 30A @ 2.15K

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QUENCH STUDIES



Quench Studies (Quench initiated in main coil)





Quench Design (Variation in heat pulse)



BARC Quench Design (Variation in heat pulse)





- The amount of input heat energy does not play very significant role in determining the coil temperature
- Once the quench has been initiated, by small amount of heat dissipation, the normal zone of the magnet will grow and decay the current
- However the initial peak temperature of the hot spot (location at which quench is initiated) does depend slightly on the heat pulse.



Quench protection circuit



Quench Protection by passive diodes

Differential Voltage sensed to detect Quench

Same Quench protection circuit for Dipole corrector coils



Quench detection



Voltage taps to monitor and record any event of quench

Based on the theoretical studies and pre-series magnet quench measurement the quench detection circuit is considered to be efficinet to detect and protect the magnet in event of quench.

Fig.1 Electrical scheme showing location of the voltage taps and diodes for quench detection/protection



| | Coil1 | Coil2 | Coil3 | Coil4 |
|-------|---------|---------|---------|----------|
| Coil1 | 5.82H | 4.823H | -0.319H | -0.3191H |
| Coil2 | 4.823H | 9.297H | -0.722H | -0.722H |
| Coil3 | -0.319H | -0.722H | 1.461H | 0.521H |
| Coil4 | -0.319H | -0.722H | 0.521H | 1.461H |

Peak coil to ground voltage = 1.1kV Peak temperature in case of quench = 65K Magnet physical length = 140 mm

| Engineering current | Excitation current | Focusing strength | Solenoid |
|------------------------------------|--------------------|-----------------------|------------------|
| density ~ 382 A/mm ² | 75A | 4.57 T ² m | |
| Engineering current | Excitation current | Focusing strength | Dipole Corrector |
| density ~ 50.995 A/mm ² | 10A | 6.3 mT-m | |



| Parameters | SSR1/SSR2 New specification (Ver.3) | Achieved | Remarks |
|--|-------------------------------------|---|--------------|
| Focusing Strength | 4.5T ² m | 4.57T ² m | \checkmark |
| Bending strength of Dipole correctors | ≥6.0 (5.0) mT-m | 6.3 mT-m | \checkmark |
| Beam pipe aperture | 40 mm | 40 mm | |
| Uncertainty in the location of magnetic axis w.r.t Reference points (Transverse and angular alignment) | <0.1mm RMS <0.5 mrad RMS | Majorly from the Mechanical design of magnet former and winding accuracy | |
| Active magnetic shielding requirements | ~<10G | <10 G | \checkmark |
| Maximum current in the solenoid | 90 | 75 A | \checkmark |
| Maximum current in the dipole correctors | 12 (50) | 10 A | \checkmark |

✓ Electromagnetic design of the SSR solenoid has been carried out meet the specified requirements

 $\checkmark\,$ Predicted performance metrics and margins have been considered

In terms of (a) Operational margin (b) Manufacturing tolerance impact on performance (c) Fringe field on the cavity surface



New design considerably has higher margin compared to pre-series magnets
Dipole corrector current requirements have been reduced for reducing thermal load
Based on the magnetic measurements and design performance of pre-series magnets predicted electromagnetic design will meet the design requirements
Manufacturing tolerances has been accounted for during design and positioning accuracies of main coil and bucking coil shall be maintained to meet fringe field requirements under all conditions.

References

[1] PIP-II SSR2 CRYOMODULE FRS : ED0001829-D

[2] FOCUSING LENS FOR SSR1 AND SSR2 - Technical Requirements Specification (TRS)"

[3] BCR: SSR Solenoid design/validation test, PIP-II BCR

[4] "SSR1 Cavity Quenching in the Presence of Magnetic Field," FNAL TD note TD-12-007, June 2012, T.

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[5] "Acceptable Level of Magnetic Field on the Surface of a Superconducting RF Cavity," FNAL, TD note TD-12-008, June 2012T. Khabiboulline, T. Nicol, and I. Terechkine

[7] Electromagnetic design and performance of conduction cooled superconducting magnet for spoke resonator cryomodule for Proton Improvement Plan (PIP)-II, Kumud Singh, Janvin Itteera, Mahima, Vikas Tiwari, Himanshu Bisht, Sanjay Malhotra, R.R. Singh, Rajesh Jalan, Sanjay Howal, Rajesh Chimurkar, Sunil Kumar, S. Stoynev, M. Turenne, M. Yub, B. Hanna, J. Hayman, C. Boffo, July 2024 Elsevier, Superconductivity

Thank you for your kind attention

Back up slides



Summary of quench studies

With dump resistor in series with back to back diodes

| Sr. no. | Series dump resistor value | Peak voltage in coil 1 Peak Voltage in coil 2 | Voltage across Coil1 Voltage across Coil2 | Coil 1 temperature Coil 2 temperature |
|---------|-------------------------------|--|--|--|
| 1. | 0 Ohms | 600V 1100 V | 4V 4V | 60K 60K |
| 2. | 0.005 Ohms | 60V 200V | ~ 4.5V ~ 4.5V | 45K 38K |
| 3. | 5 Ohms | 100 V 120 V | ~ 400 V ~128 V | 38 K 27 K |

With only back to back diodes in parallel with coil

| Sr. no. | Configuration | Peak voltage in coil 1 Peak Voltage in coil 2 | Voltage across Coil1 Voltage across Coil2 | Coil 1 temperature Coil 2 temperature |
|---------|---|--|--|--|
| 1. | Radial Coil split (middle quench) No dump resistor 0.4J of energy deposition | 600V 1100 V | ~4V ~4V | 65K 60K |
| 2. | Axial Coil split (middle quench) No dump resistor 0.4J of energy deposition | ~ 850V ~850V | ~4V ~4V | 75K 75K |
| 3. | Axial Coil split (corner quench) No dump resistor 0.4J of energy deposition | ~ 850V ~850V | ~4V ~4V | 75K 75K |