

Charge Discrimination in Liquid Argon Time Projection Chamber (LArTPC)



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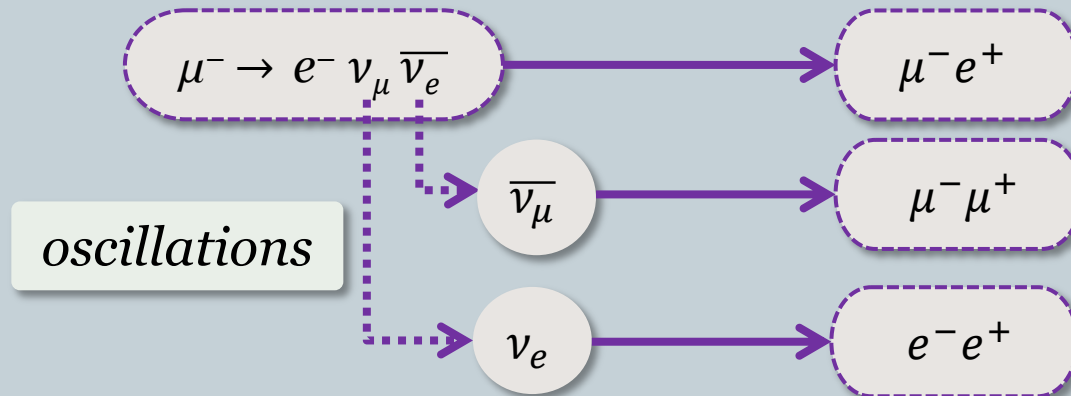
Scott Menary, Nariman Khazai, Andrea Capra



General Remarks



- Main motivation: To be able to use LArTPC
 - Charge discrimination needed for neutrino oscillation physics:



- LArSoft = Software designed for liquid argon experiments at Fermilab.

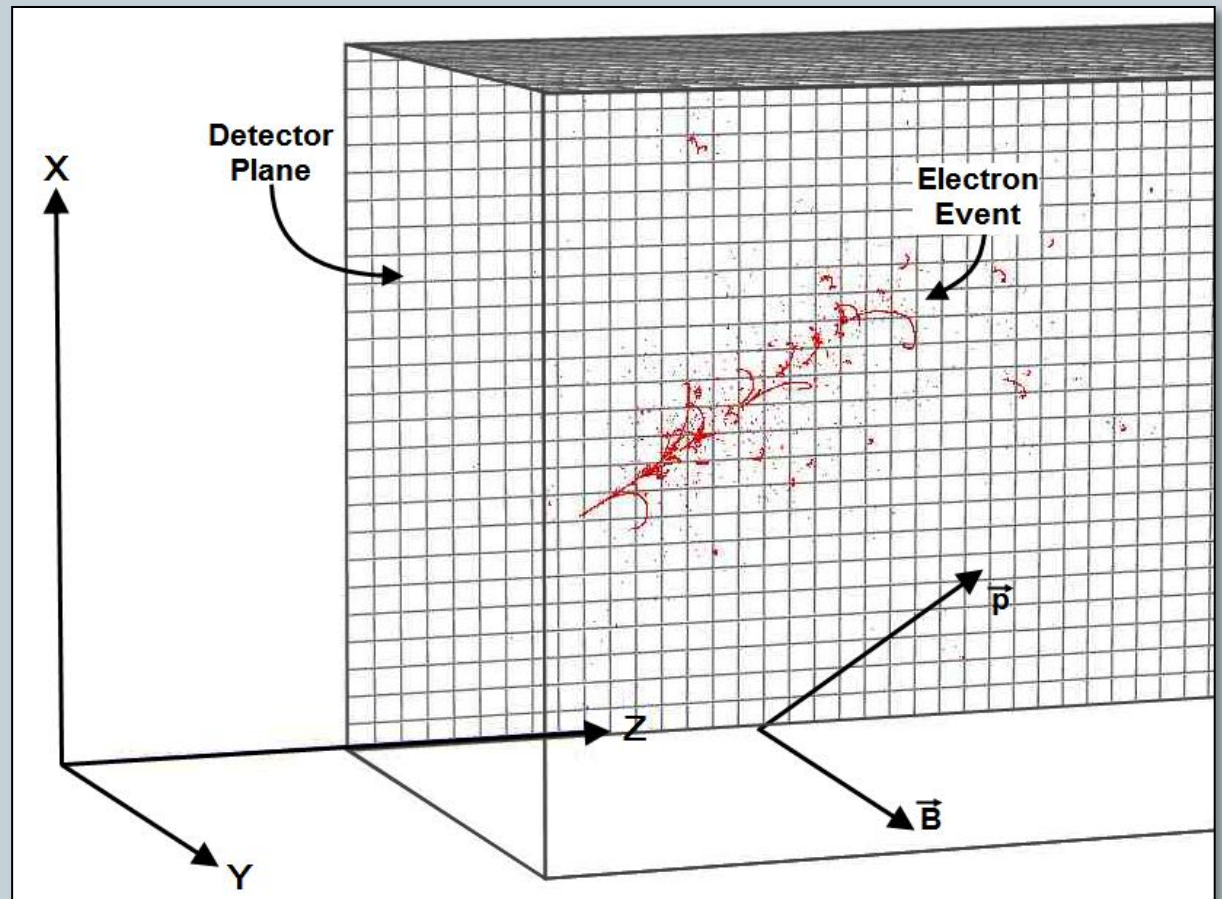
Detector in LArSoft



*MicroBooNE's
liquid Argon time
projection chamber:*

*Ideal B field
along y.*

*Detector plane
is xz.*



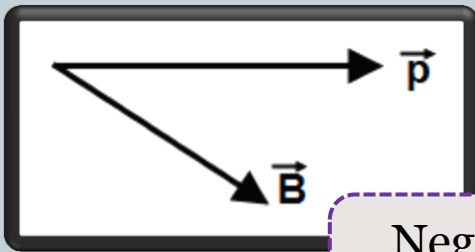
MicroBooNE Detector



Muon Events

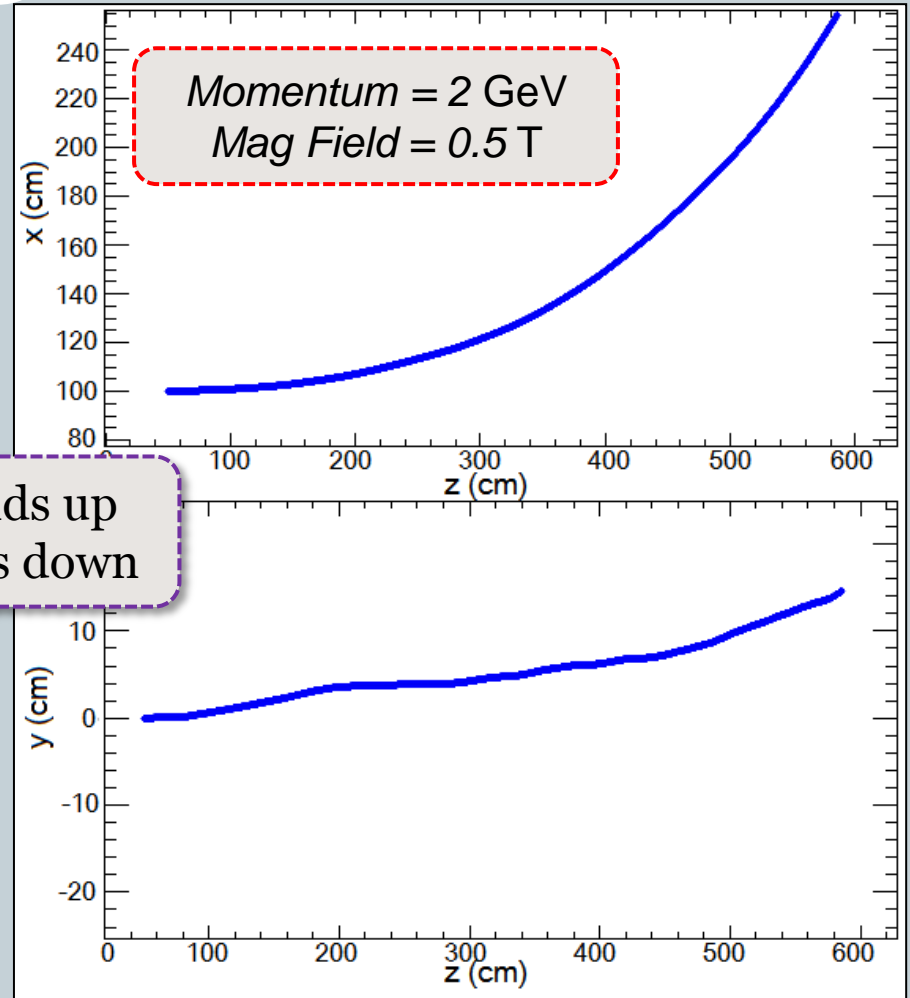


- Bending direction generally easy to identify:



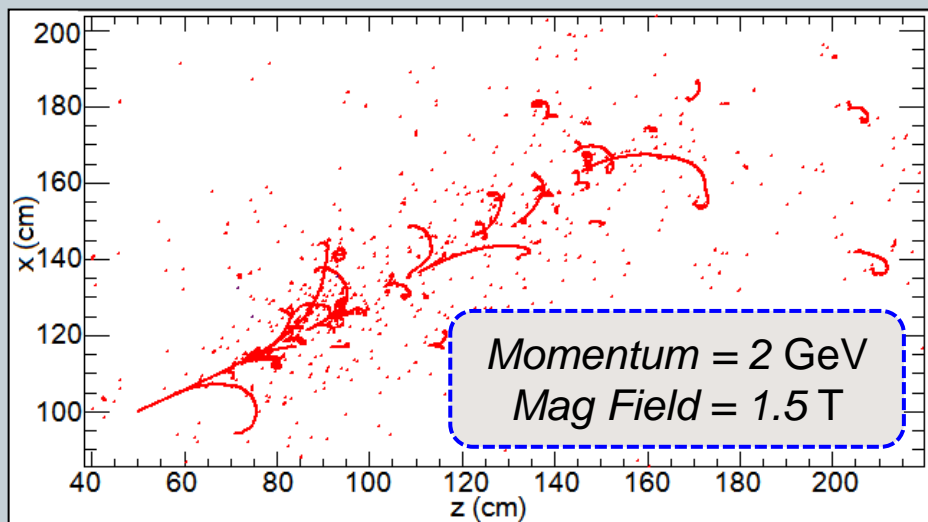
Negative charge – bends up
Positive charge – bends down

- Particles are also affected by multiple scattering, which can be significant at low momenta

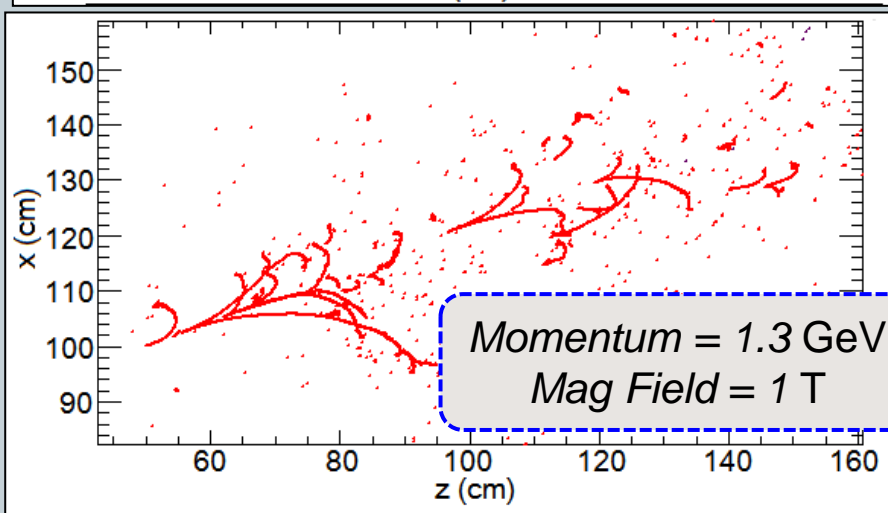
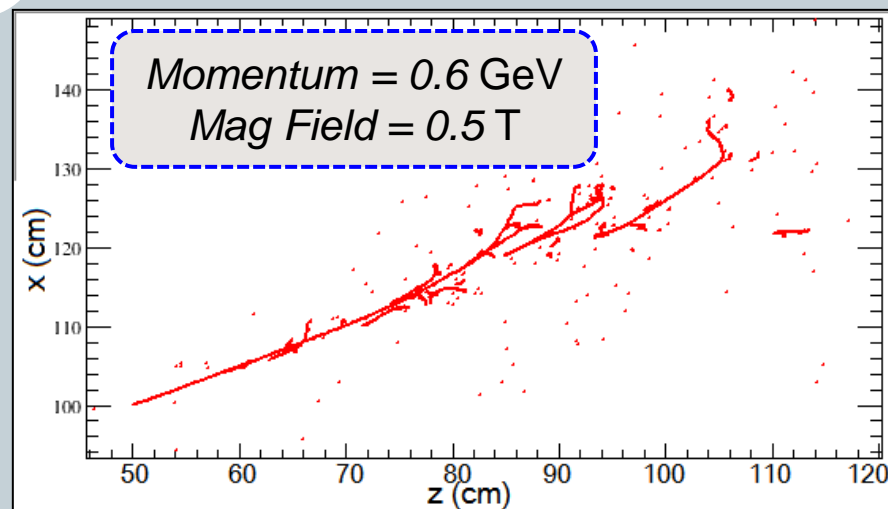


Electron/Positron Events

- Charge discrimination can be much more challenging!



- EM showers → difficult to determine bending direction
- Focus on parent particle

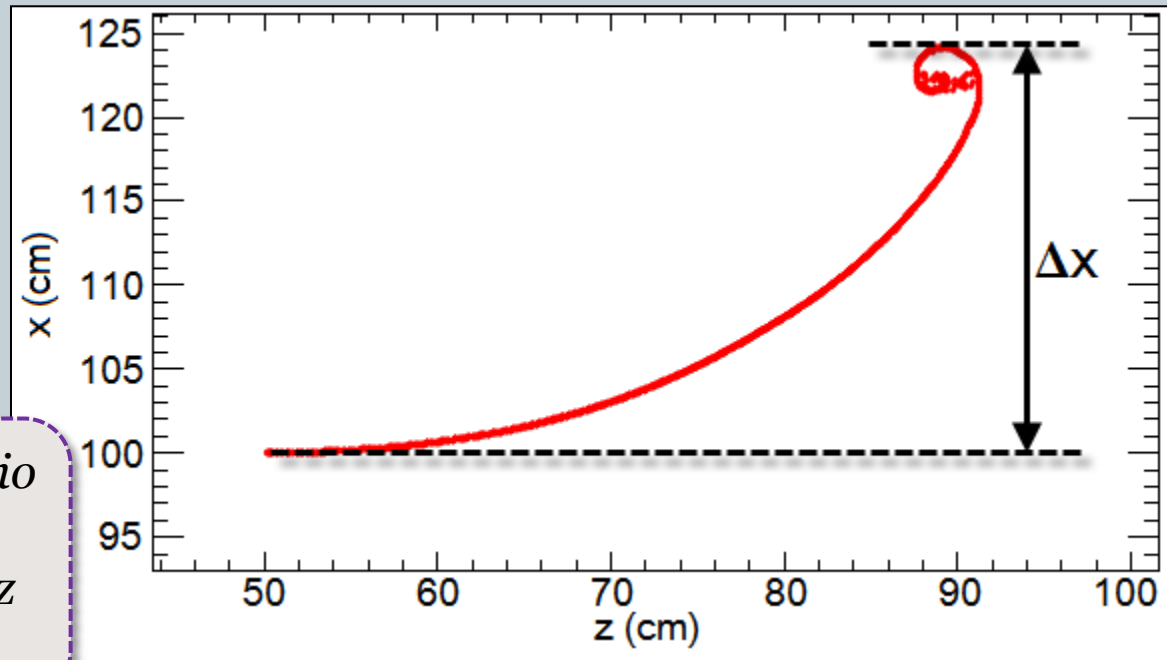


Algorithm Objective



- To determine whether parent particle bent up or down
 - Look at parent particle only
 - Determine maximum displacement along x direction

e^-	$\Delta x > 0$
e^+	$\Delta x < 0$



*Simplistic scenario
with particle
traveling along z
direction*

Algorithm Development

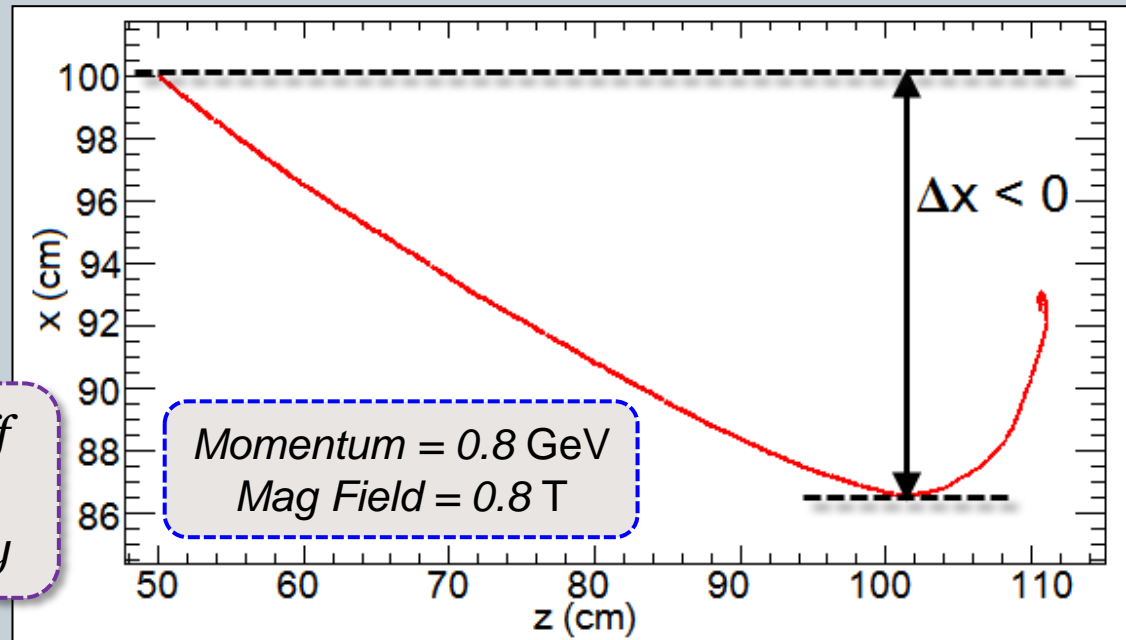


- More generalized scenario – Particle's momentum not exclusively along z direction:

e^-	$\Delta x > 0$
e^+	$\Delta x < 0$



Particle traveling off axis could be identified incorrectly



- **Solution:** Rotate coordinate system along original momentum direction

Algorithm Development



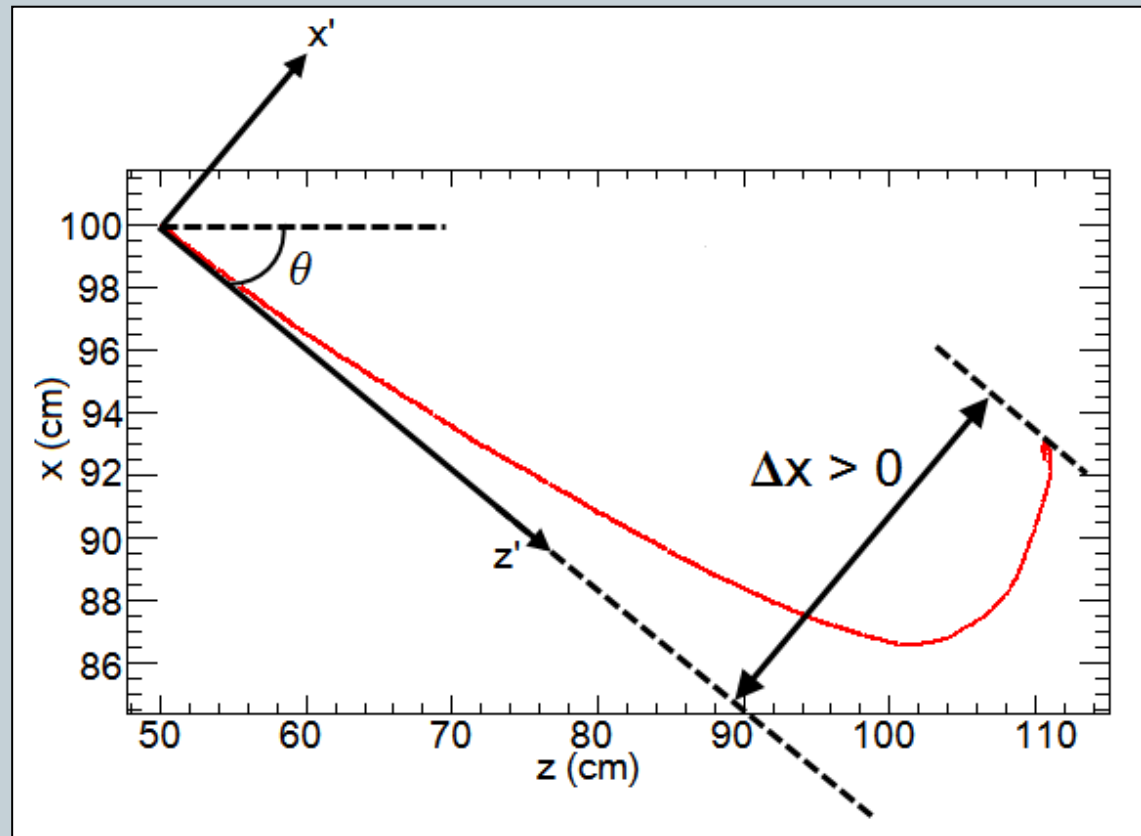
- Goal: Rotate coordinate system along original momentum direction

e^-	$\Delta x > 0$
e^+	$\Delta x < 0$



Correct particle ID obtained!

- Implementation?



Implementation

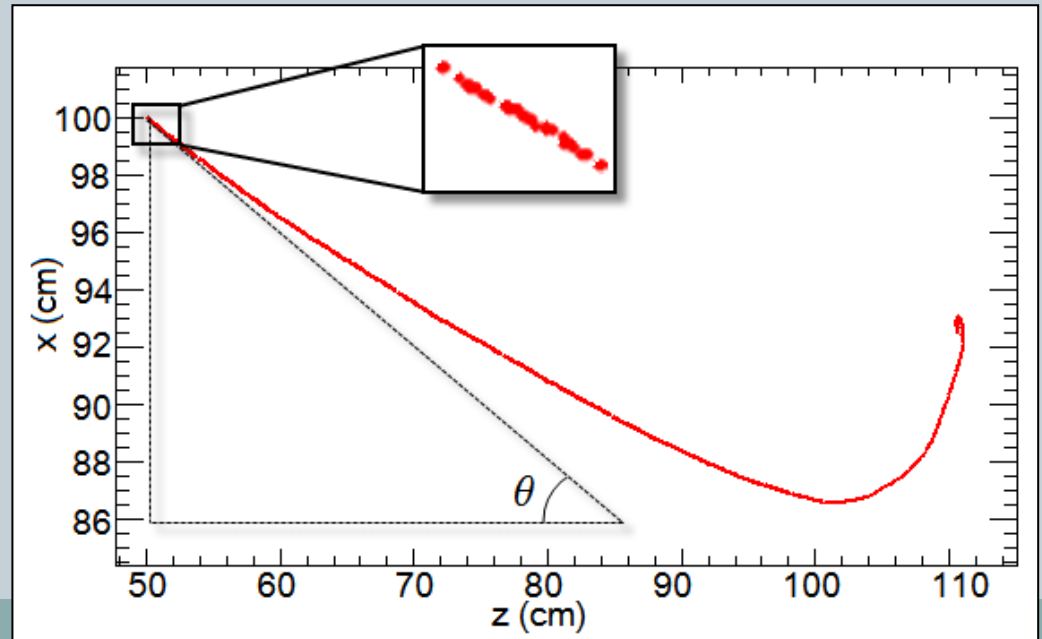


- Each point can be translated into the rotated coordinate system:

$$\begin{aligned}x' &= -\sin\theta z + \cos\theta x \\z' &= \cos\theta z + \sin\theta x\end{aligned}$$

- Must determine rotation angle, θ :
 - Perform a least-squares fit to the first few points of each track to obtain original direction

$$\text{Slope of line} = \tan\theta$$



Algorithm Development



- Structure of resulting code:

```
for (i=1, i< last_point, i++) {
```

```
  Xposition = x[i] - x[0];
```

```
  Zposition = z[i] - z[0];
```

```
  X'position = -sin( $\theta$ )*Zposition + cos( $\theta$ )*Xposition;
```

```
      if( std::abs(X'position) > std::abs(Max $\Delta$ X) ){
```

```
          Max $\Delta$ X = X'position;
```

```
      }
```

```
  }
```

```
if(Max $\Delta$ X > 0 ){
```

```
    Number_electrons = Number_electrons + 1;
```

```
} else {
```

```
    Number_positrons = Number_positrons + 1;
```

```
}
```

Loops through all the points in each event

*Obtains the X coordinate
for each point after
rotation*

*Checks for maximum
displacement along X*

*Adds to electron/positron
counter based on the sign of
 ΔX*

Optimizing the Fit



- Must determine number of points to fit through, N
 - More points = generally more accurate, but particle bends
- Use two parameters to determine quality of fit:
 - RMS Residual:

$$RMSResidual = \frac{\sqrt{\sum_{i=1}^N (X_{position}(i) - X_{fit}(i))^2}}{N}$$

- Angle Discrepancy:

$$Angle\ Discrepancy = Angle\ from\ Fit - Angle\ from\ Simulation$$

Optimizing the Fit



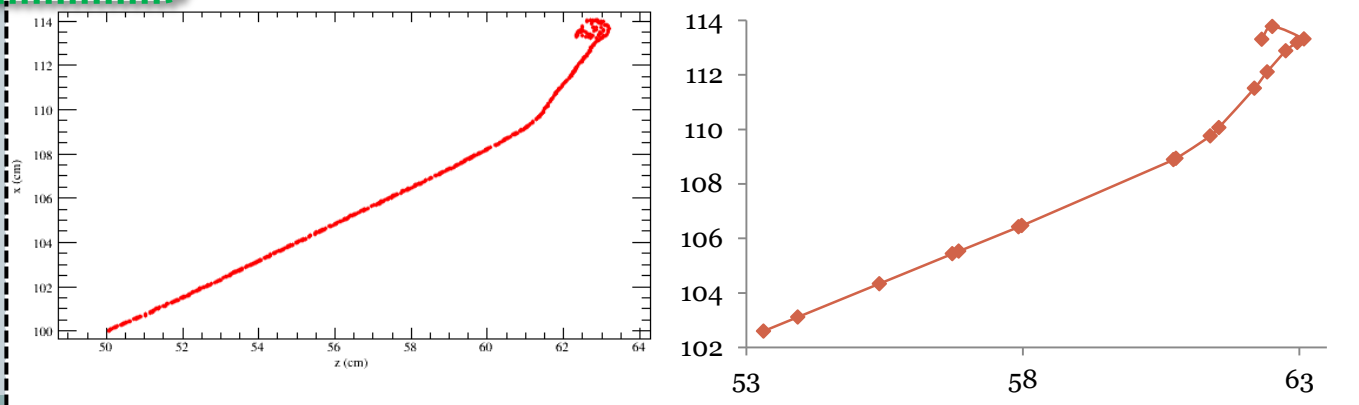
- Sample results for 50 positrons:

Positrons
Momentum = 0.4 GeV
Mag Field = 1 T

*The 3-point fit
gives best
results!*

*Data used is
not ideal:*

Number of Points	RMS Residual	Angle Discrepancy (degrees)
3	0.00097	-0.46
4	0.00192	-0.77
5	0.00283	-0.99
6	0.00484	-1.37



Algorithm Performance

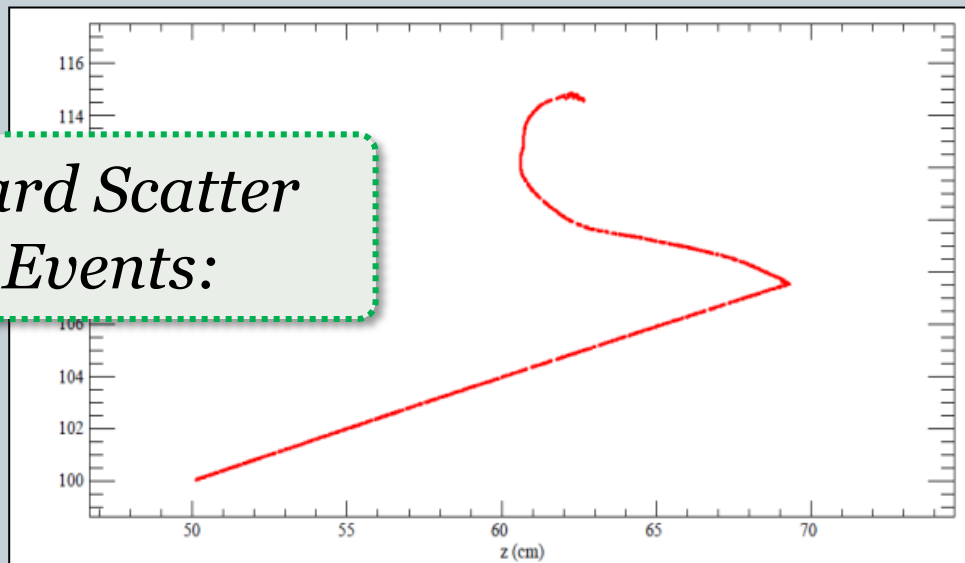


- Mistag rate was obtained for 250 electrons (per $|\vec{p}|$ bin):

$ \vec{B} $	$ \vec{p} $ (GeV)					Total
	0.2 – 0.6	0.6 – 1.0	1.0 – 1.4	1.4 – 1.8	1.8 – 2.2	
0.8 T	1.6%	0.4%	1.2%	1.6%	0.8%	1.1%
1.0 T	0%	0.4%	0%	0%	0.8%	0.2%

Algorithm needs to be precise to 10^{-4} so results are not good enough, but data is not ideal

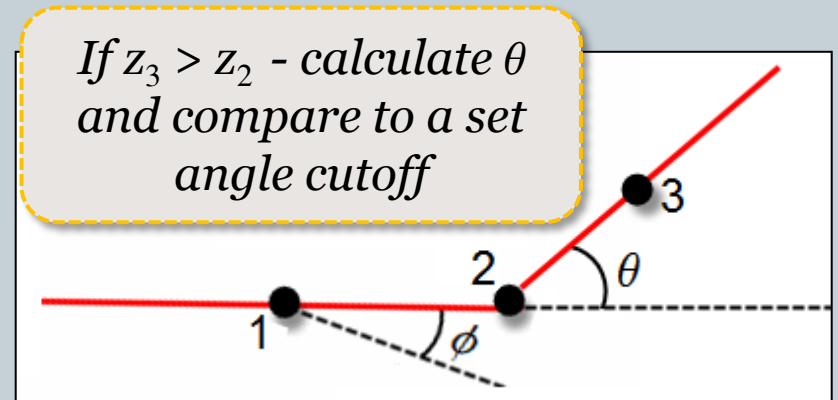
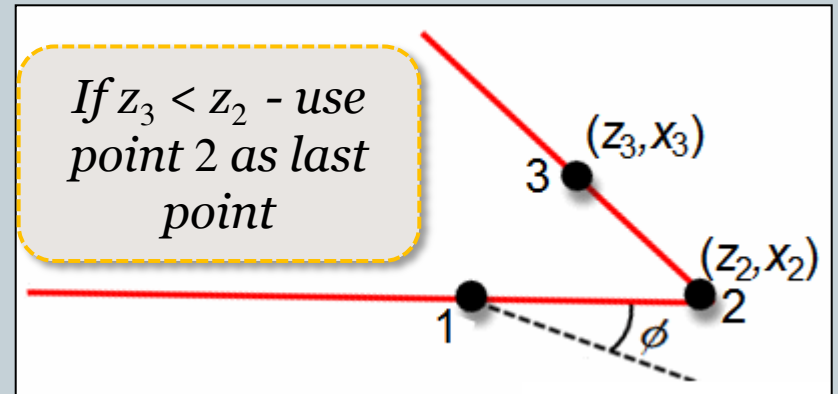
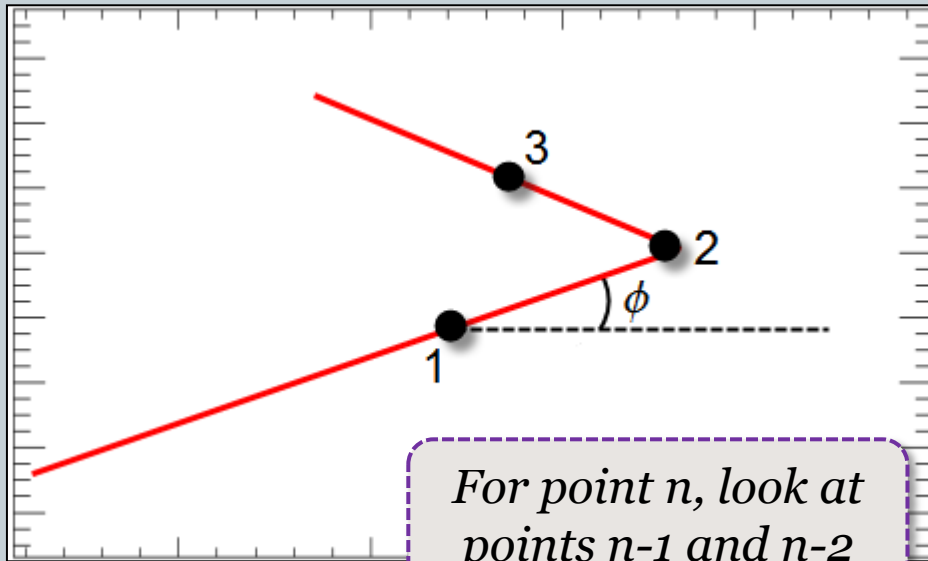
Hard Scatter Events:



Hard Scattering Events



- Main Idea: To determine point at which hard scatter occurs and discard the remaining portion of track



Next Steps and Conclusions



Next Steps:

- Test the algorithm on correct points
- Re-optimize the initial fit (direction of travel)
- Optimize cutoff angle to remove hard scatter events

Conclusions:

- Current results not good enough, but definite possibility for major improvement
- Magnetic fields smaller than 1.0 T seem possible