Overview of the CMS Framework Review

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<u>CMS Software Scale</u>

People 3000 collaborators 128 contributors to production code since June last year

Code 2.5M LOC C++ 1.3M LOC python 670 shared libraries and 1300 shared plugins

Usage 100,000 concurrently running jobs 200M jobs per year 60B events processed (simulation and data) 40PB of MC and Data



Prompt Reconstruction

Prompt Calibration

Full Calibration and Alignment Supports iterative refinement

Simulated Event Generation

Detector Simulation Supports MC and data event mixing

Reconstruction

Analysis

Event Display Random event access Modify settings of algorithms (modules) while processing

Data File Merging Used by CMS grid tools

CMS Framework

Features and Subsystems

Python based configuration

Event processing engine State machine driven may be changed for threading extensions Runs, LuminosityBlocks, Events, open/close files

Conditions Validity interval based Manages dependencies between conditions

Plugin management

Publish/subscribe data flow

Provenance tracking Job configuration Event selection decisions

<u>Plugín Based Framework</u>

Processing Plugins Algorithms encapsulated in modules Types: Producers, Filters and Analyzers (3424)

Processing Storage Plugins Encapsulation of I/O Types: Sources (20) and OutputModules (7)

Conditions (EventSetup) Plugins Conditions/Alignment/Geometry encapsulated in modules Types: Sources (114) and Producers (357)

Miscellaneous Plugins (Services) Non-physics changing extension (80) Can monitor the state of the framework e.g. what modules are being run at the moment

Event Looping Plugins Controls repeated looping over events in job (20)

Generalized Plugins System 80 plugin types used by developers

CMS Framework



python objects are used to create a C++ tree structure edm::ParameterSet class

Module validation code can modify its part of the tree structure

Module constructors are passed their part of the tree structure Immutable in constructor

Final configuration tree stored in output files Provenance tracking Serialized as a list of (hash, string) pairs

Support tools inspect provenance in files query modules as to allowed parameters

<u>Multi-threaded Processing</u>

Present

Supports processing multiple events concurrently Supports use of Intel's Thread Building Blocks from within a module Provides mechanism to serialize thread unsafe algorithms All modules must declare what data products they will consume Provides a thread-safe message logging system

Spring

Support concurrently running modules processing same event A prototype of the code already exists

Future

Support concurrent processing of LuminosityBlocks and Runs

Modules are passed Run/Lumi/Event/EventSetup to process

Data Model Support

Producers publish products to Run/Lumi/Event/EventSetup

Data and conditions products are immutable once published const member functions must return same value given the same inputs

Data Relationships

edm::Ref<> persistent index into any container, fast

edm::Ptr<> persistent index into most containers, supports polymorphism

edm::RefToBase<> persistent index into any container, supports polymorphism extremely difficult to specify all classes it needs for storage deprecated

edm::AssociationVector<> associates data to each item in another collection edm::AssociationMap<> associate one or more data to items in a collection deprecated

edm::ValueMap<> associates data to items in multiple collections more efficient memory and I/O than edm::AssociationMap

Polymorphic and container type agnostic lookup edm::View<>

Data Passína Interface

Data is requested from a generic container passed to modules edm::Event, edm::Run, edm::LuminosityBlock and edm::EventSetup requests are done in a type safe manner

Reduced set of requests

::getByLabel<T>

pass set of strings which uniquely identify a product pass edm::InputTag which encodes the same strings as above

::getByToken<T>

pass an edm::EDGetToken which uniquely identify a product edm::EDGetToken obtained by calling consumes on module's constructor

::getManyByType<T> gets all products of that type

Data publishing

::put<T>

passed an std::auto_ptr<T>

Data 'Mixing'

Event pile-up support

Ability to take MC data products from N secondary events and accumulate them into the primary event Used by all simulation jobs to approximate multiple beam interactions per event Knows how to change timing of hits to correspond to 'bunch crossings' Re-engineered to use products from only one secondary event at a time

'Digi' mixing support

Ability to take one secondary event and mix digis with primary event Digi: data for one detector Plugin after calibration has been applied Used for embedding studies Inject a known simulation event into a real data event to study tracking efficiency

Inject a known simulation event into a real data event to study tracking efficiency Re-engineered to allow standard 'raw to digi' modules to be used internally I.e. uses a reduced version of the framework internally to run standard modules