

STATUS OF ANALYSIS & SIMULATION

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IIT, Chicago

MAP Spring Meeting
30 May 2014

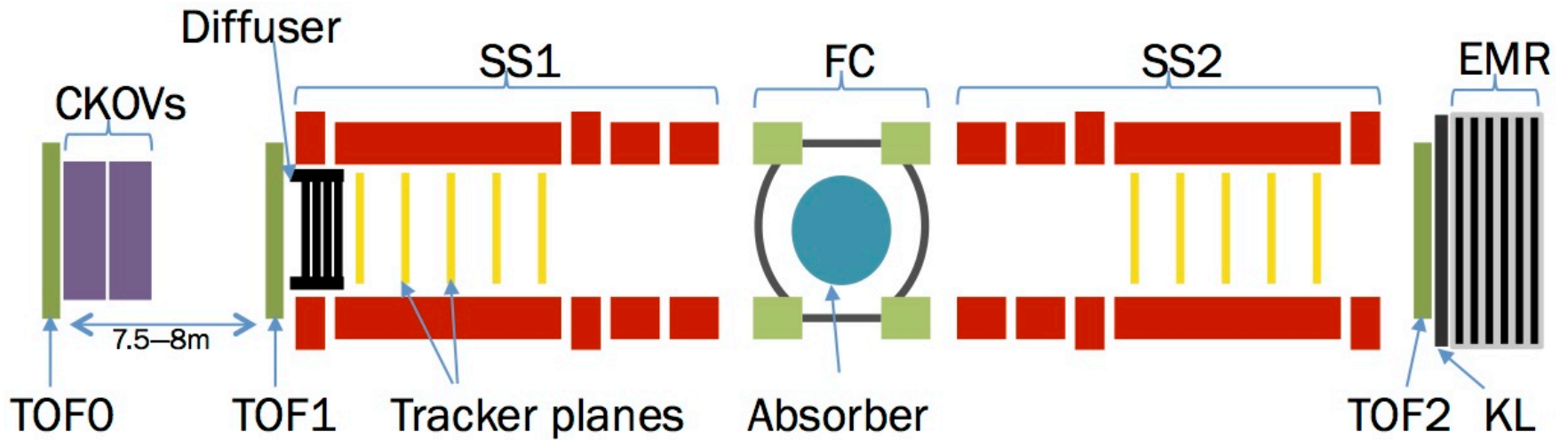
OVERVIEW

- Deliverables
- Organization
- Status
 - What's available, what's missing
 - Detectors, MC, Batch, CDB, API, Online
- CM38 report summaries
- Work plan
- Risks & Priorities

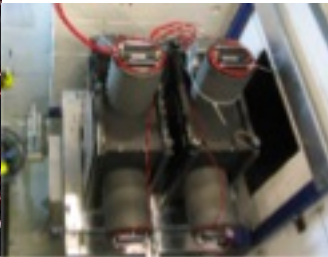
DELIVERABLES

- Reconstruction
 - Detectors
 - Global Tracks & Particle ID
- Simulation
 - Beam + Geometry description + Fields + Detectors
- Online
 - Detector-level monitoring
- Data validation & quality checks
- Analysis tools
- Single-event display

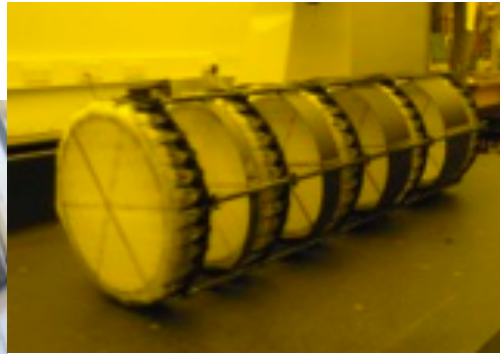
MICE DETECTORS



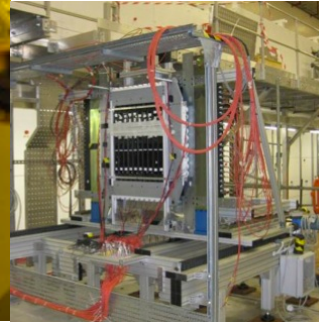
TOF



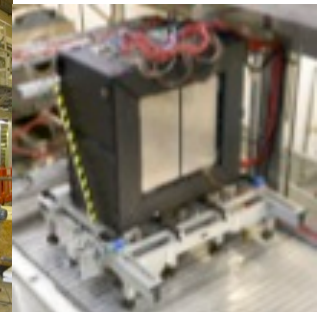
Ckov



Tracker

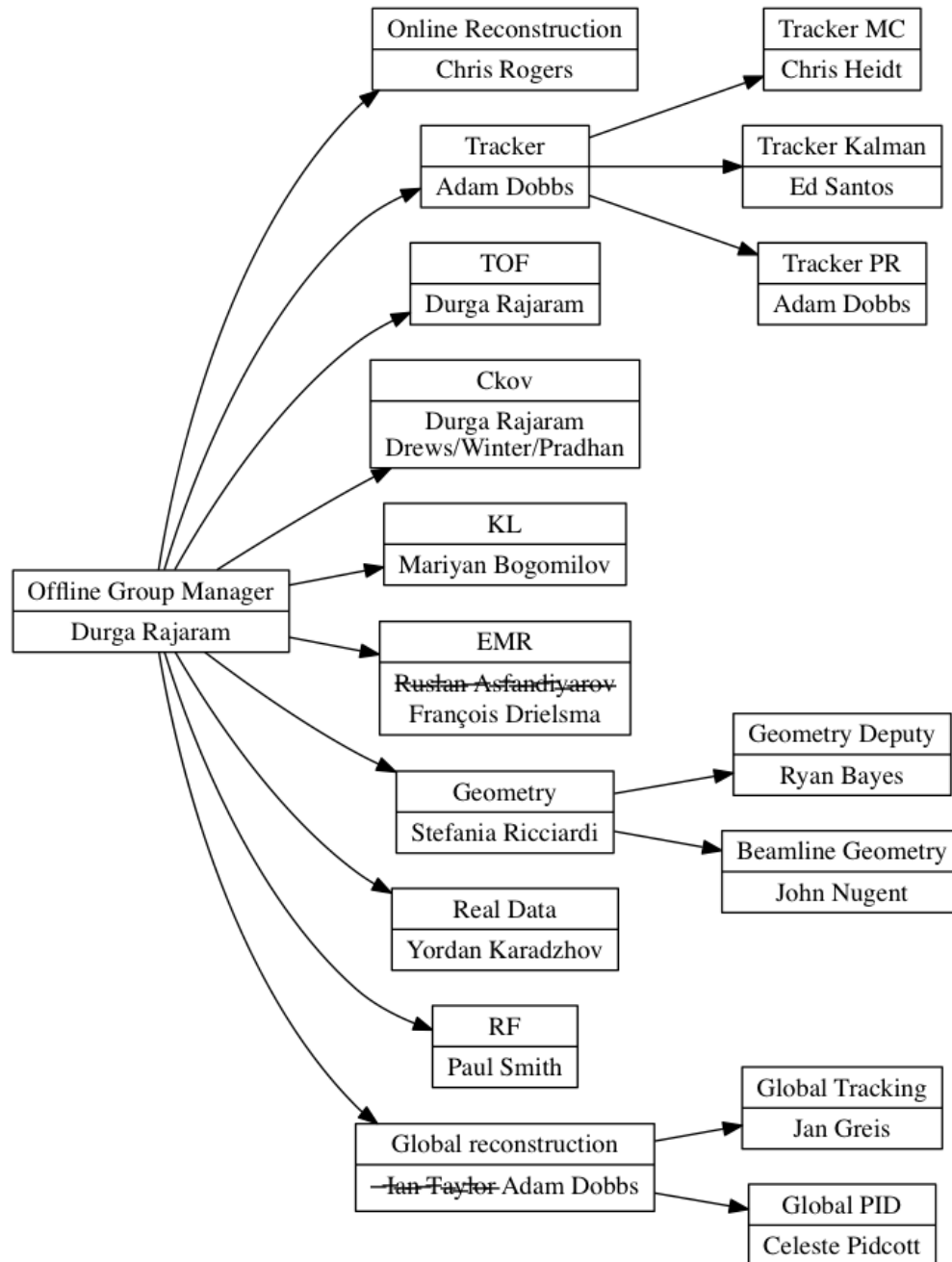


KL



EMR

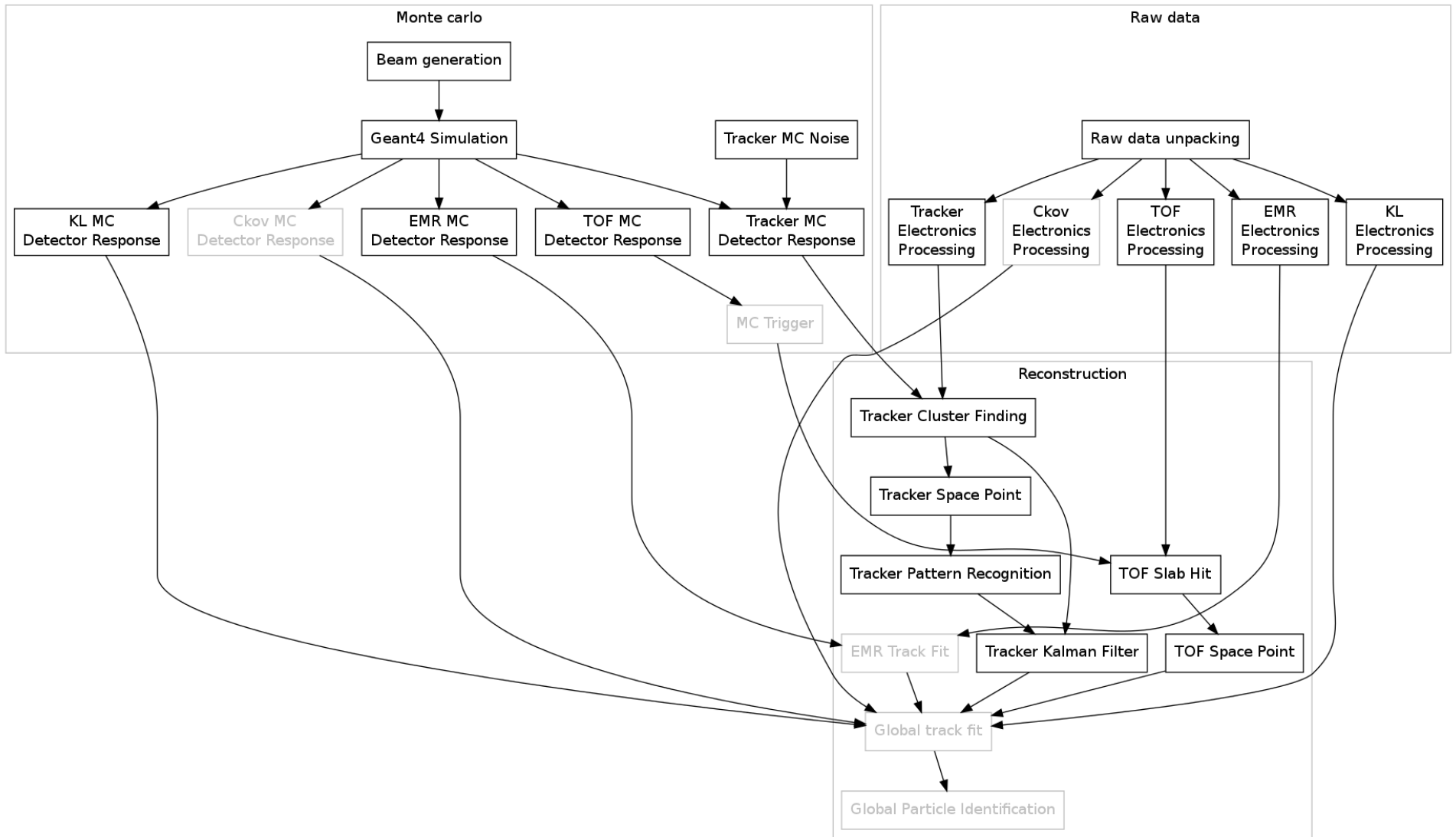
ORGANIZATION



Changes:

- EMR
 - Student taking over from Asfandiyarov
- Ckov
 - New Undergraduate students at IIT and UMiss
- Global
 - Jan Greis replaced Lane
 - Adam Dobbs replaced Ian Taylor

OFFLINE DATA FLOW

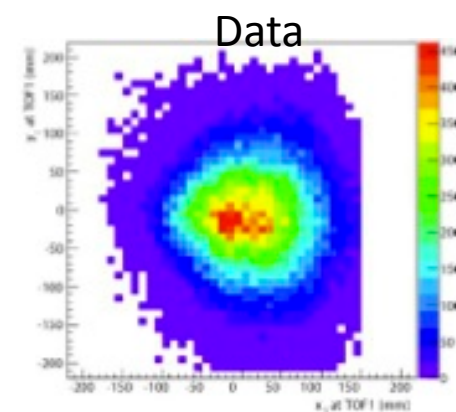
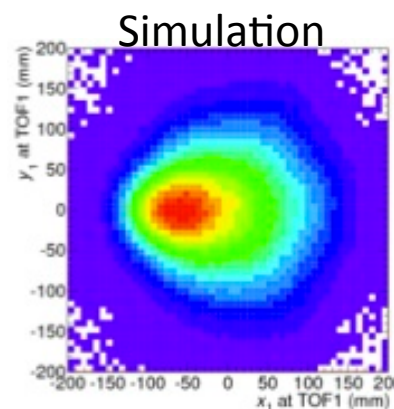
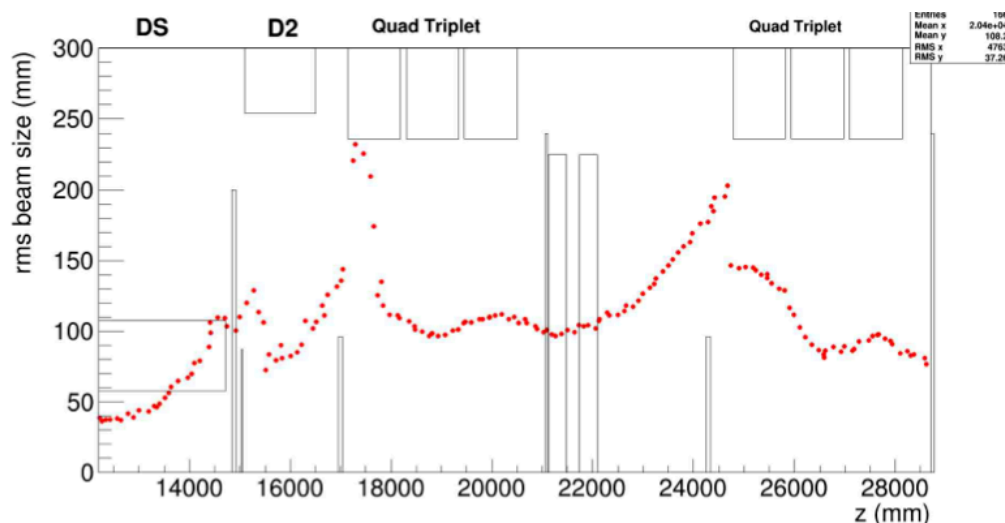


MONTE CARLO

- Beam
- Geometry
- Particle tracking
- Detector response

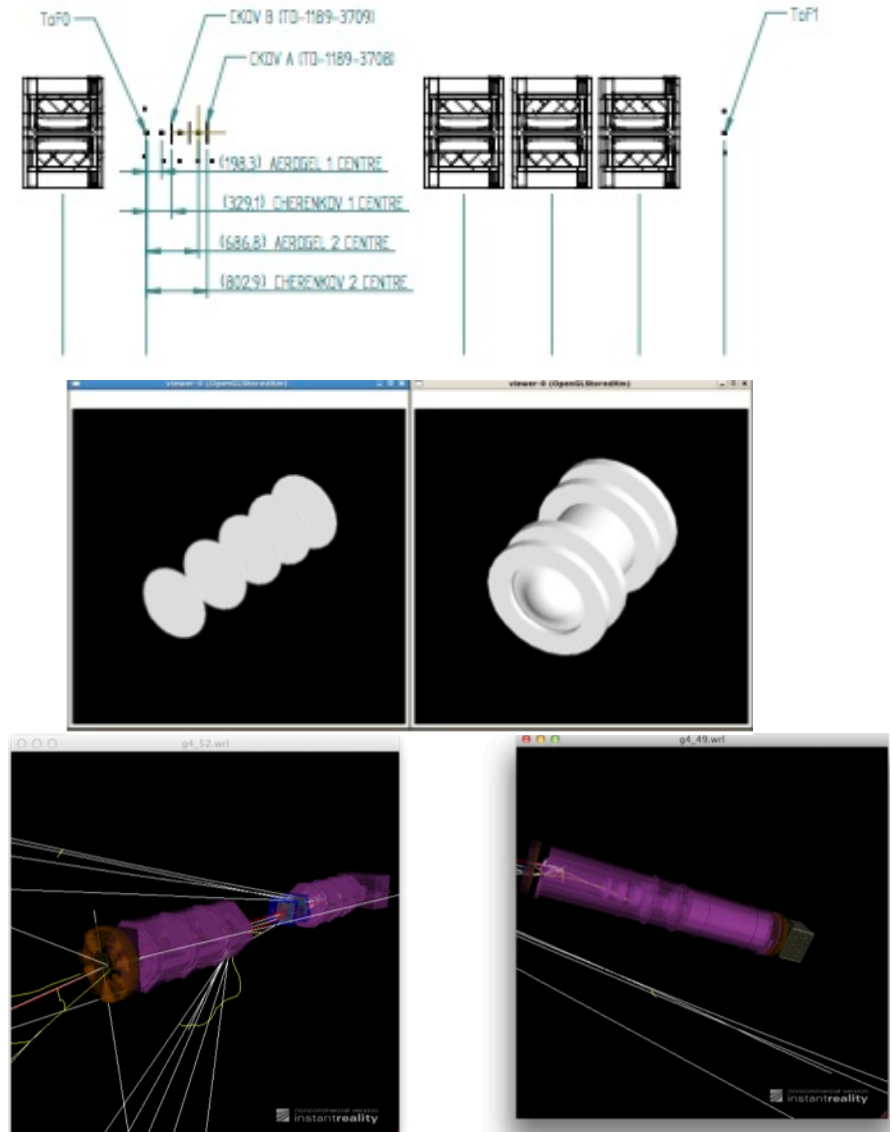
BEAM GENERATION

- Previously:
 - Generate pencil beam, or sample from a user-defined gaussian, or read in from a file
- Now added G4Beamline as a generator
 - Updated survey, geometries and currents
 - Generates beam upto D2
 - More realistic beam, better agreement with data (Step I)
 - *cf. Analysis presentation*
 - Ability to generate beam based on data-run currents



GEOMETRY

- Default geometry description has been through flat text files
 - no surveying or versioning information
 - Prone to errors and outdatedness
- It was decided to have a CAD-based geometry description that is stored in the database
 - Significant progress
 - CAD models converted to GDML descriptions and stored in CDB
 - Realistic Step I & Idealistic Step IV geometries now available
 - *Except Ckov which is being finalized*
 - Requires validation and shakedown
 - Geometry loading time is an issue especially for user-testing, tuning, studies, etc
 - This is a new system, so there is risk associated with its deployment and usability
 - “Legacy” geometry continues to be supported and will be until the new geometry is proven

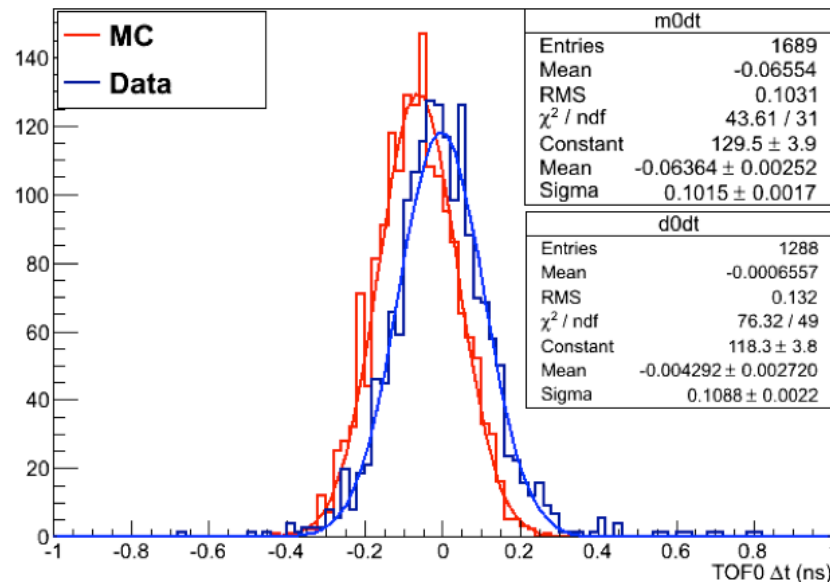


SIMULATION

- Particle tracking, energy loss, and scattering are done through GEANT
 - Upgraded to GEANT 4.9.6 – better handling of tessellated solids in geometry
- Custom field map models, or read in maps from file
- Two steps to simulating detector response
 1. Collect hits in each sensitive volume – volume ID, energy deposit, hit position, momentum, time...
 2. Electronics response aka digitization – mock DAQ readout – volume ID to cable map, energy to ADC...

DETECTOR RESPONSE (TOF)

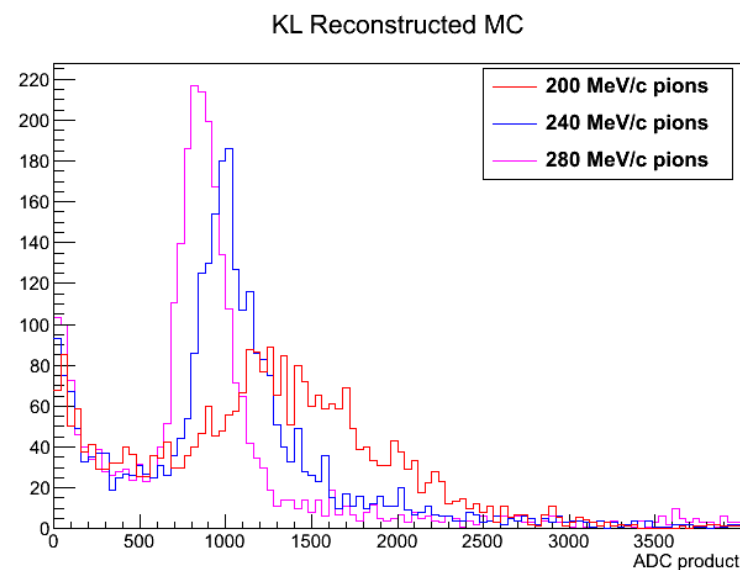
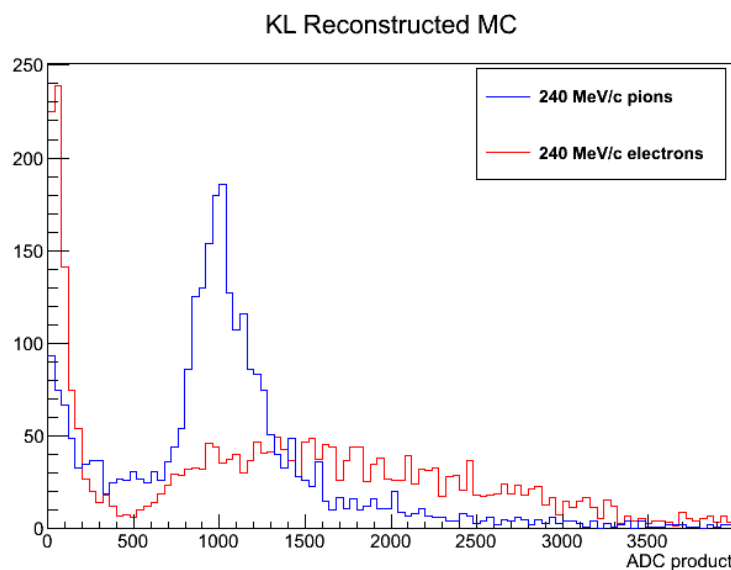
- Stable
 - Energy deposited is first converted to photoelectrons and then to an ADC count
 - Time of the hit is propagated to PMTs and converted to a TDC count
 - Calibration corrections are *added* in so that they can be taken out at reconstruction stage as is done with data



- Potential restructuring for trigger simulation (TOF is experiment's trigger)

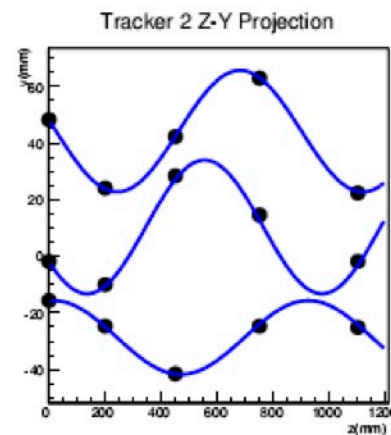
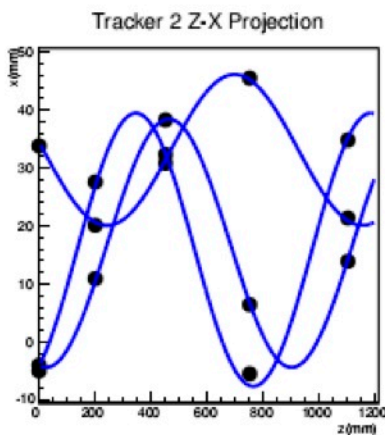
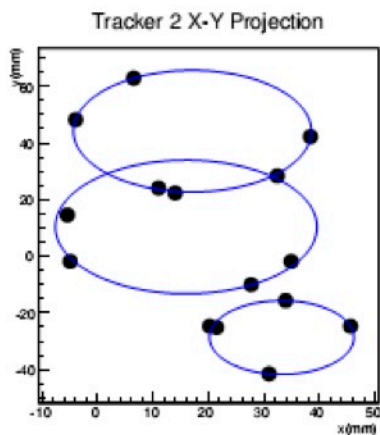
DETECTOR RESPONSE (KL)

- **New:** Digitizer added along with updated geometry, and software to store hits in sensitive volumes
 - Outputs are ADC counts converted from energy deposits
 - Conversion factors are preliminary and likely require tuning
 - Needs validation against Step I data
 - Step I PID analysis can now use digitized and reconstructed KL



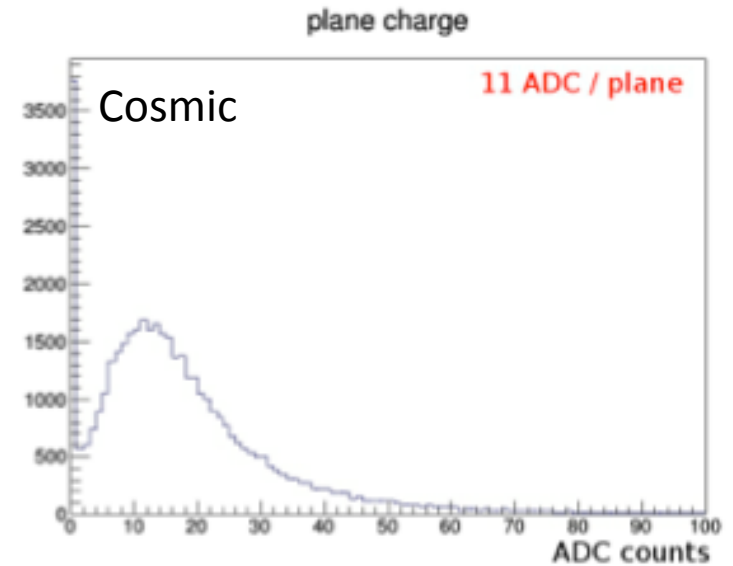
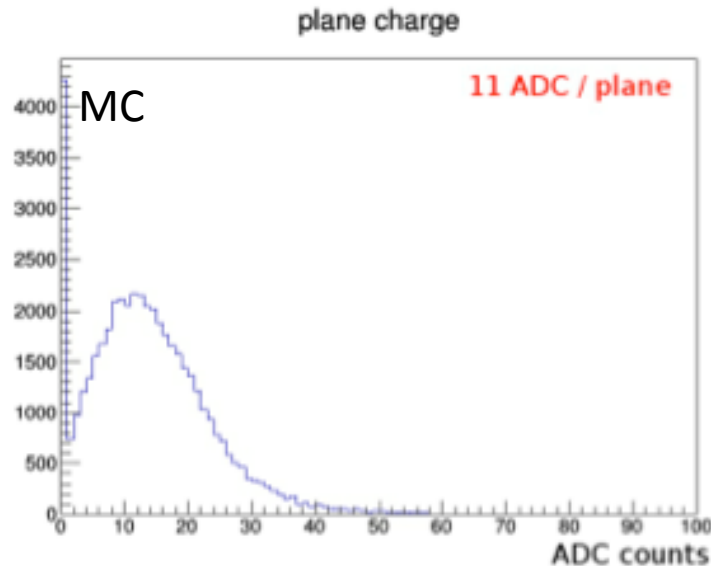
DETECTOR RESPONSE (TRACKER)

- Stable
 - Energy deposited is converted to photoelectrons, photoelectrons from a fiber channel are then summed and converted to an ADC
- New
 - Added Poisson noise to simulate VLPC dark current



DETECTOR RESPONSE (IN PROGRESS)

- The Ckov and EMR digitizations are not yet in the production release of MAUS
- Ckov:
 - digitization depends on finalizing geometry (Cremaldi and student), simulating optical photons and collecting hits and digitizing (Rajaram and students).
 - Possible refactoring, or rewrite
 - Risk: undergraduate students who are new to this and have to balance effort with coursework
- EMR:
 - The final geometry and hit collection are now complete and in MAUS
 - Digitization is being developed



RECONSTRUCTION

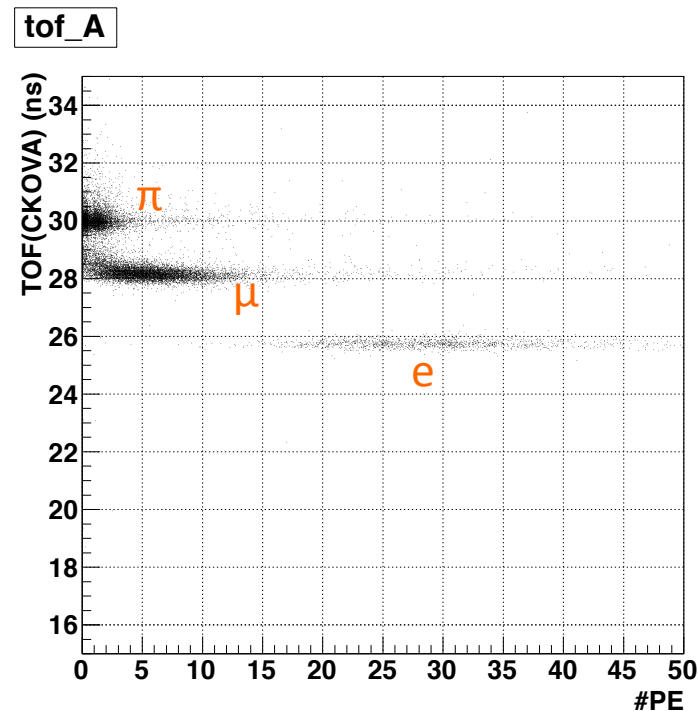
- For any given detector, the reconstruction algorithm is required to be agnostic about input – should not distinguish data from MC
- At the moment, MAUS can reconstruct every single Step IV detector
 - TOF, Ckov, KL, Tracker, EMR
 - Some are mature, some functional with optimizations and tuning in progress, some preliminary
- The final Global reconstruction (in progress) will take the individual detector reconstructions and provide a global track and an associated particle identification hypothesis

RECONSTRUCTION (TOF)

- Stable
 - Digits (MC or DAQ) are converted to slab hits.
 - x-y slab combinations are then used to form space-points
 - Space-point times are corrected for time-walk and trigger offsets based on calibrations stored in the DB
- **RFI**: Calibration algorithm needs some optimization to cover slabs/pixels with lower statistics
 - Reconstruction discards uncalibrated pixels resulting in a loss in acceptance

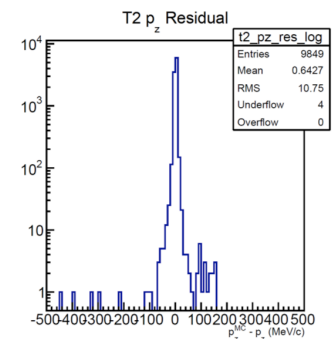
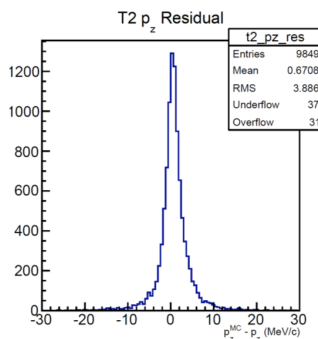
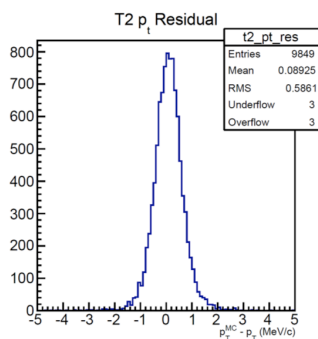
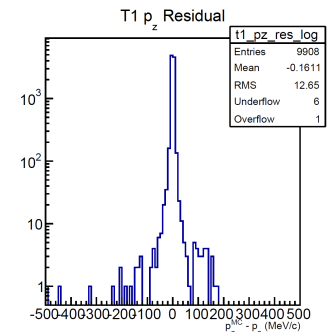
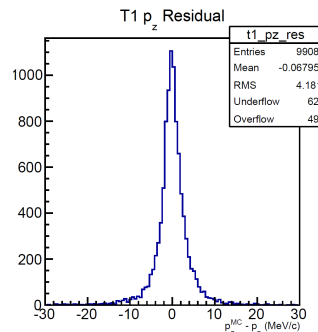
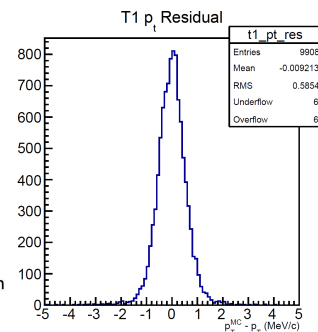
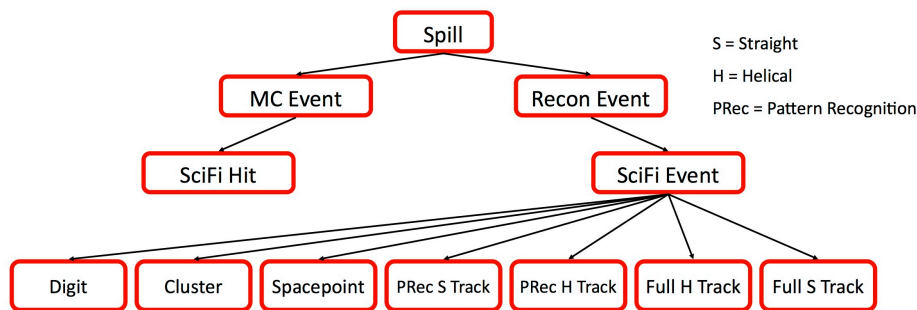
RECONSTRUCTION (CKOV)

- Functional
 - Flash ADC samples integrated and converted to number of photoelectrons
 - Conversion factor requires tuning based on single-photoelectron fits and should be stored in DB (hard-coded now)
 - Charge integration window may need to be optimized
 - Add multi-peak reconstruction



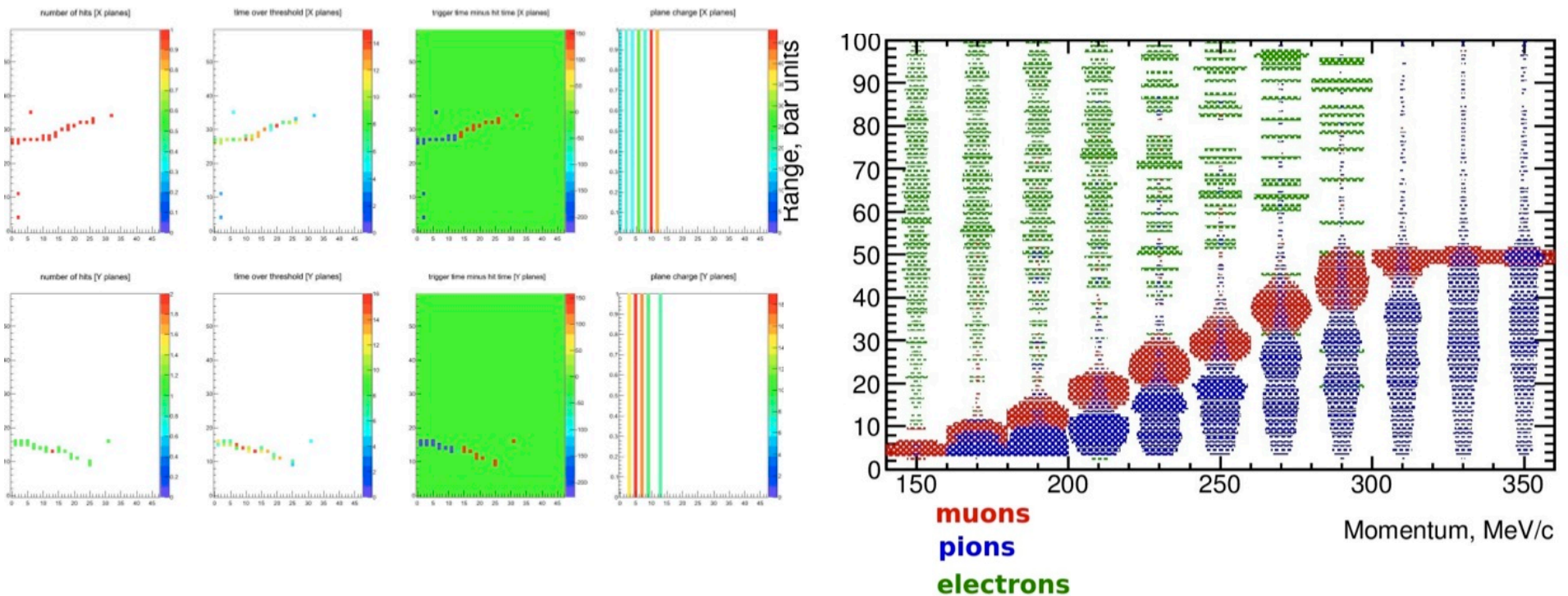
RECONSTRUCTION (TRACKER)

- Functional
 - Space-point reconstruction, Pattern Recognition, Kalman tracking complete
 - Optimization underway
 - Efficiency studies in progress using MC
 - Calibration interface needs to be added
- Much improved documentation



RECONSTRUCTION (EMR)

- **New:** Reconstruction of plane hits complete
- Higher level reconstruction (tracks, charge ratios, range) are being developed – to be integrated
- Asfandiyarov is moving on, and Drielsma is taking over, so there is some learning curve & risk

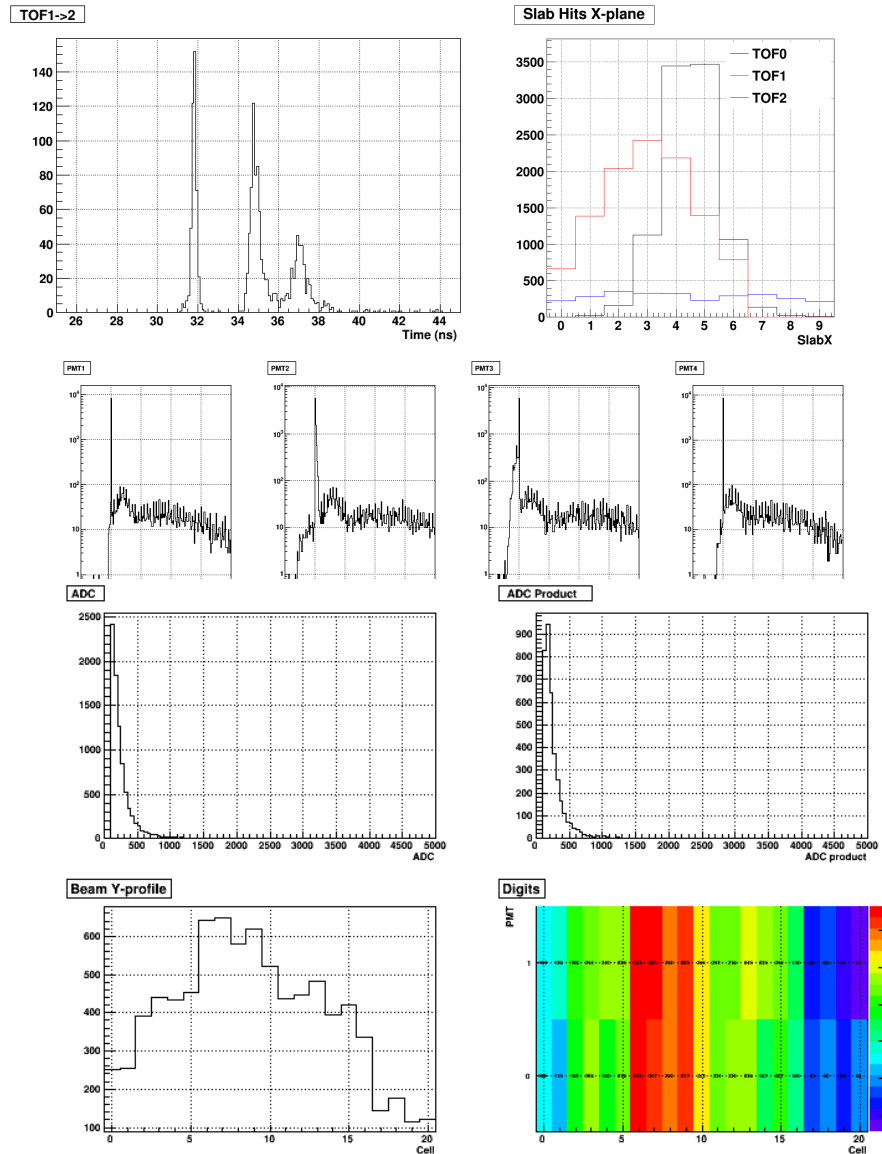


RECONSTRUCTION (GLOBAL)

- Global track fitting and particle ID are critical items
 - Tracking suffered from lack of experienced hand and grad student working on it has moved on.
 - A grad student (Jan Greis) has taken over and is getting up to speed
 - PID: framework developed & tested for TOF
 - In development: PID using TOF (time) + Tracker (momentum)
 - PID needs integration with the global tracking as that develops
- Adam Dobbs is now the head of Globals, taken over from IJT
- 9 months should be enough time, but requires fine breakdown to allow monitoring and catching risks early

ONLINE RECONSTRUCTION

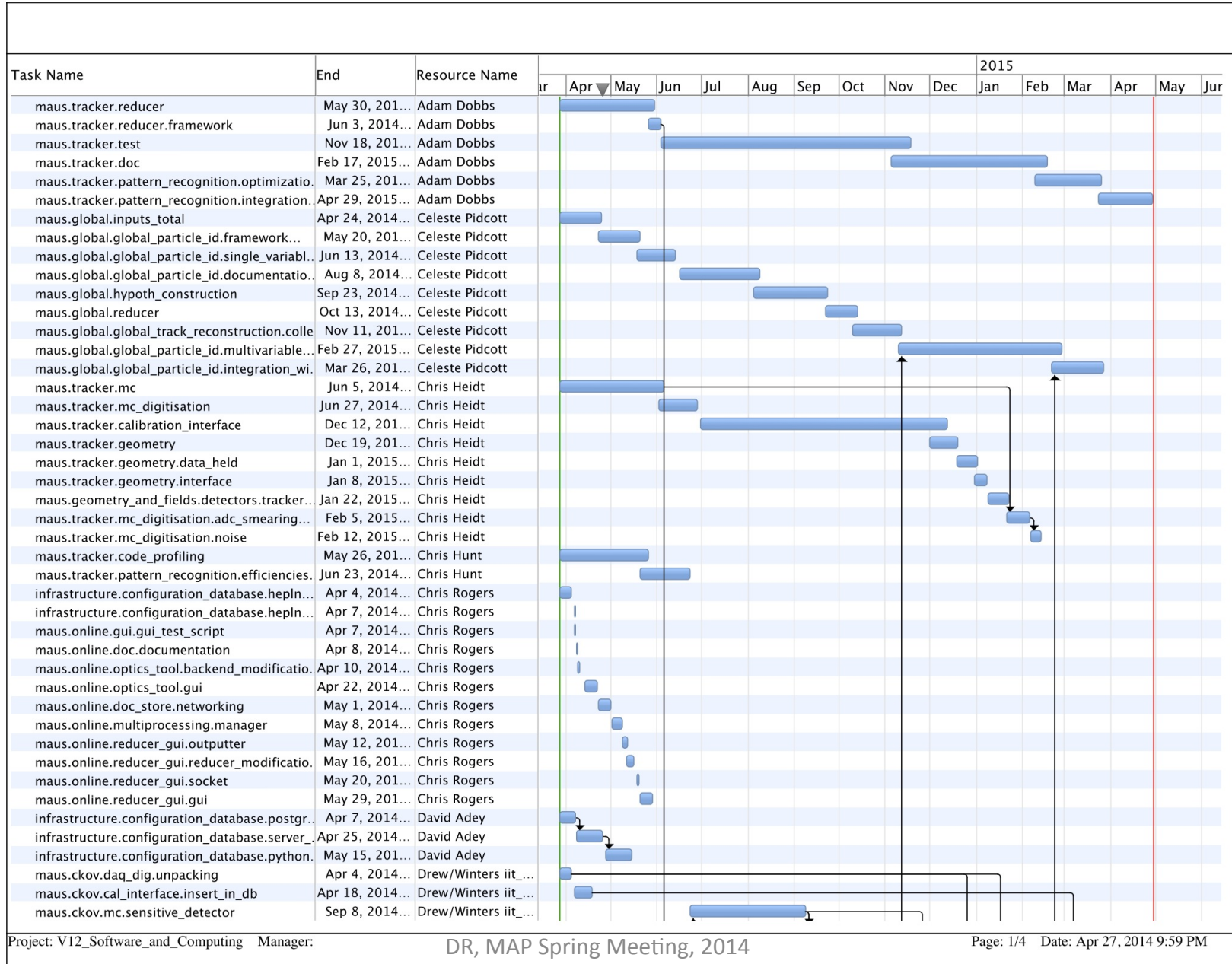
- Reconstruction software is same as for offline
- Distributed processing over worker nodes
- Summary and monitoring histograms visualized in MLCR as images via web interface
 - Plots intended to provide summary view of reconstruction quality
 - Lower level reconstruction plots serve to identify problems with detectors – e.g. inefficient tubes, dead channels...
 - Changes being made to visualization infrastructure (ROOT objects instead of raw images)
- Online reconstruction is available for TOF, Ckov, KL
 - Preliminary EMR display is available stand-alone, to be integrated with MAUS



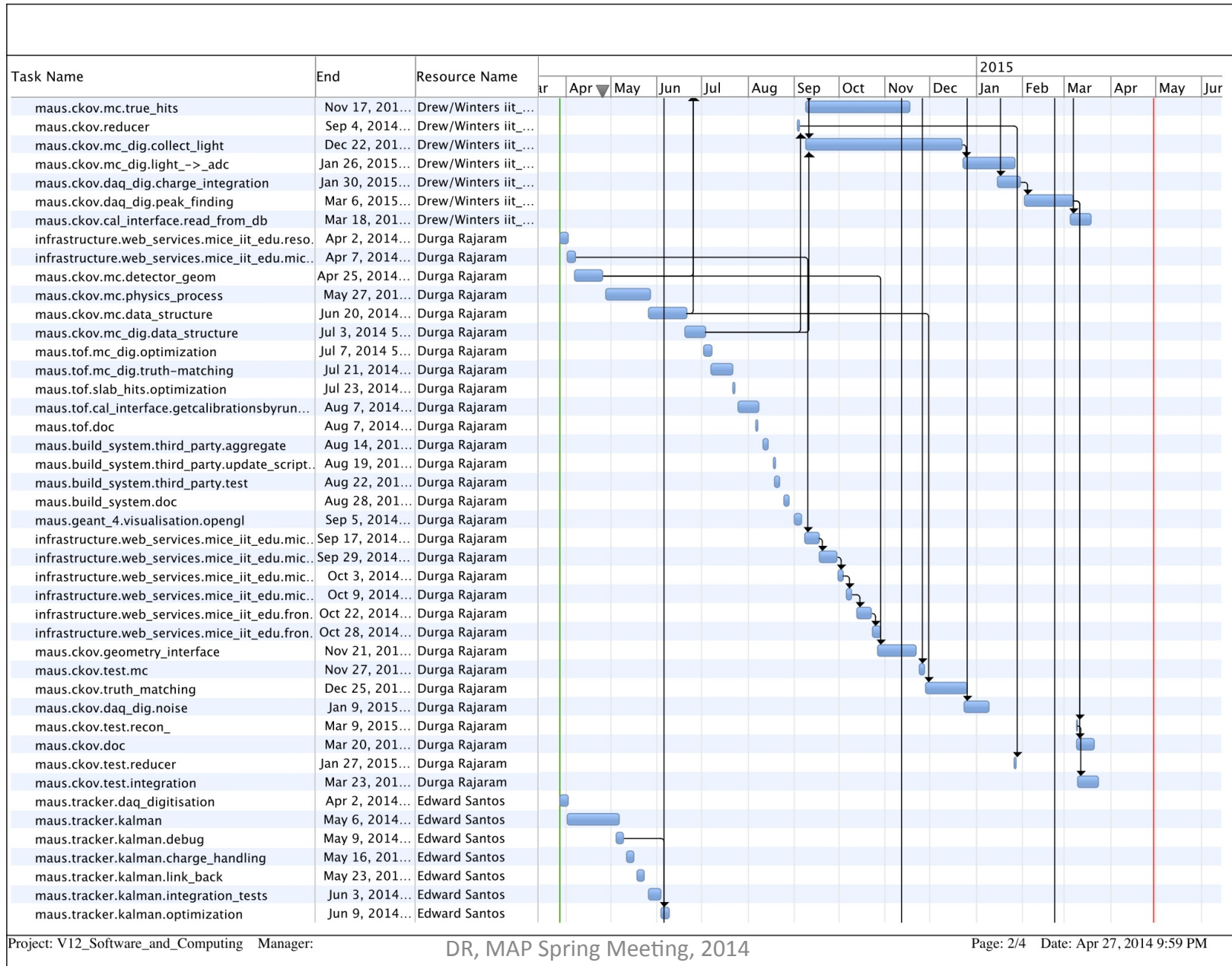
SOFTWARE QA & TESTING

- Software QA process
 - Style tests: does the code conform to style guidelines?
 - Unit tests: does the function do what's expected?
 - Currently, python coverage is ~68%, C++ coverage is ~78%
 - Integration tests: testing workflow – do all the pieces play nice together
 - Validation tests: does the simulation/reconstruction produce expected results?
- Continuous Integration test servers provide offline and online environments for developers to test their code before merging with the development branch
- Redmine issue tracker for bugs and features
- New release every ~2-4 weeks

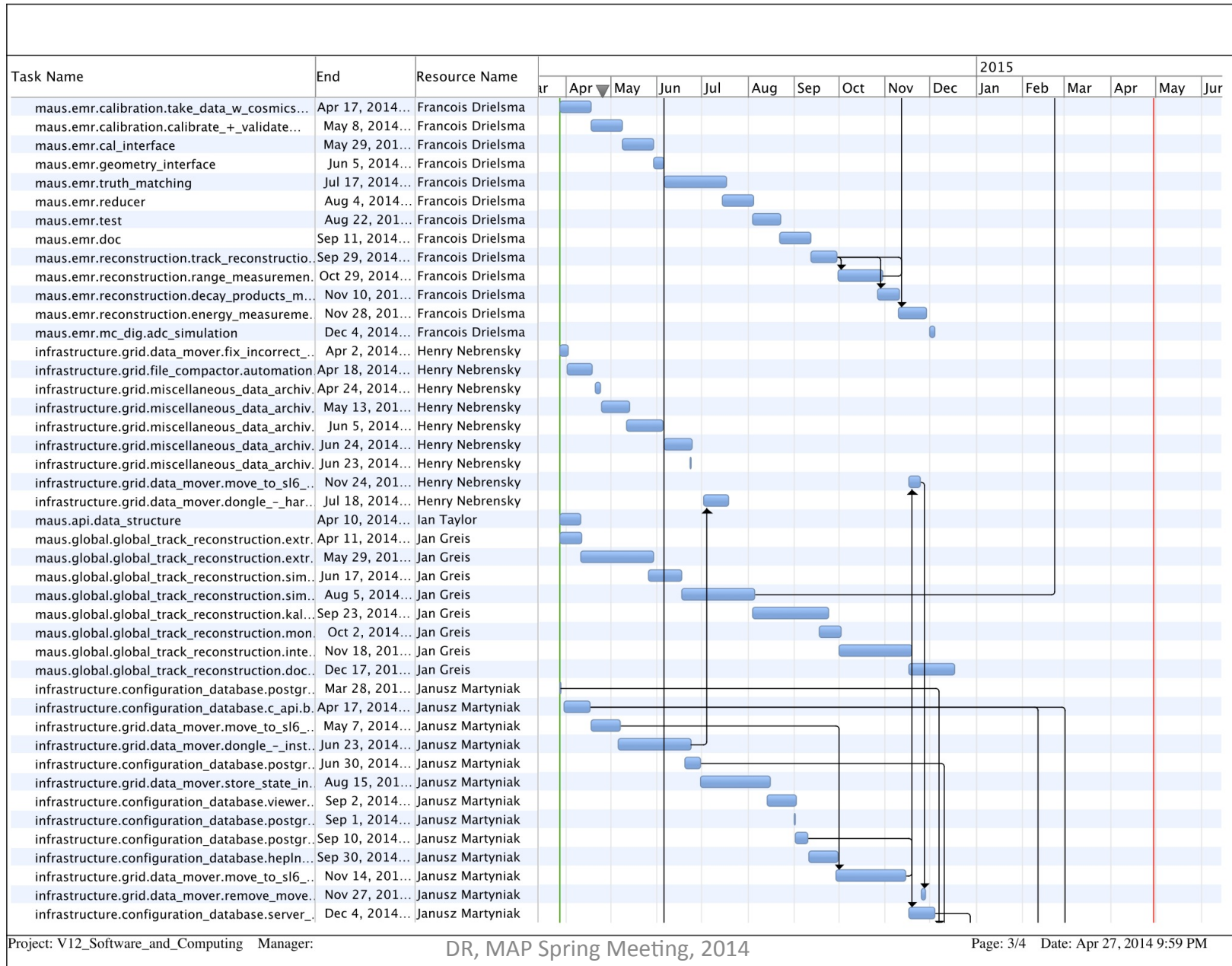
SCHEDULE



SCHEDULE



SCHEDULE



CONCLUSIONS

- MAUS can reconstruct data from every Step IV detector
- Capable of simulating the TOF, KL, and Tracker
 - EMR and Ckov in development
- The big gap is global track reconstruction
 - New manager, two students ramping up
- CAD-geometry implementation has progressed
 - Ongoing validation against full simulation
 - Usability and optimization issues to be evaluated
- Need to focus and make sure we have working simulation and reconstruction (beam + geometry + detectors + global) ready for Step IV