



MICE: Status of Online and C&M Systems

Pierrick Hanlet

30 May 2014



Outline

I Organization

II Online Systems Summary

- A MLCR and Rack Rooms
- B Infrastructure
- C DAQ and Trigger

III Controls and Monitoring (C&M)

- A Description
- B Integrated Hardware Plan
- C Higher Level Operations
- D Other Items



Outline

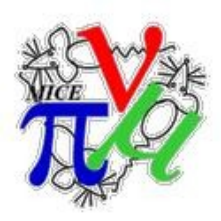
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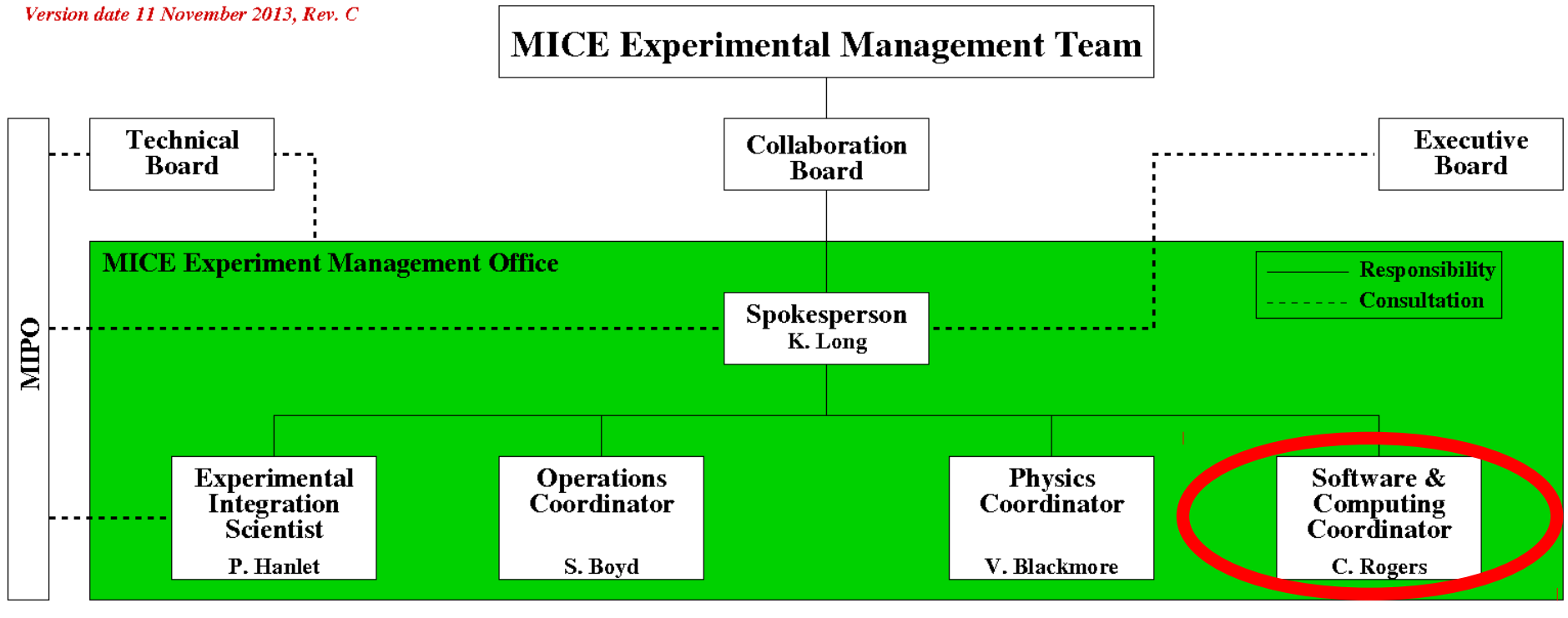
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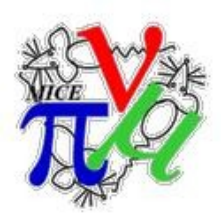
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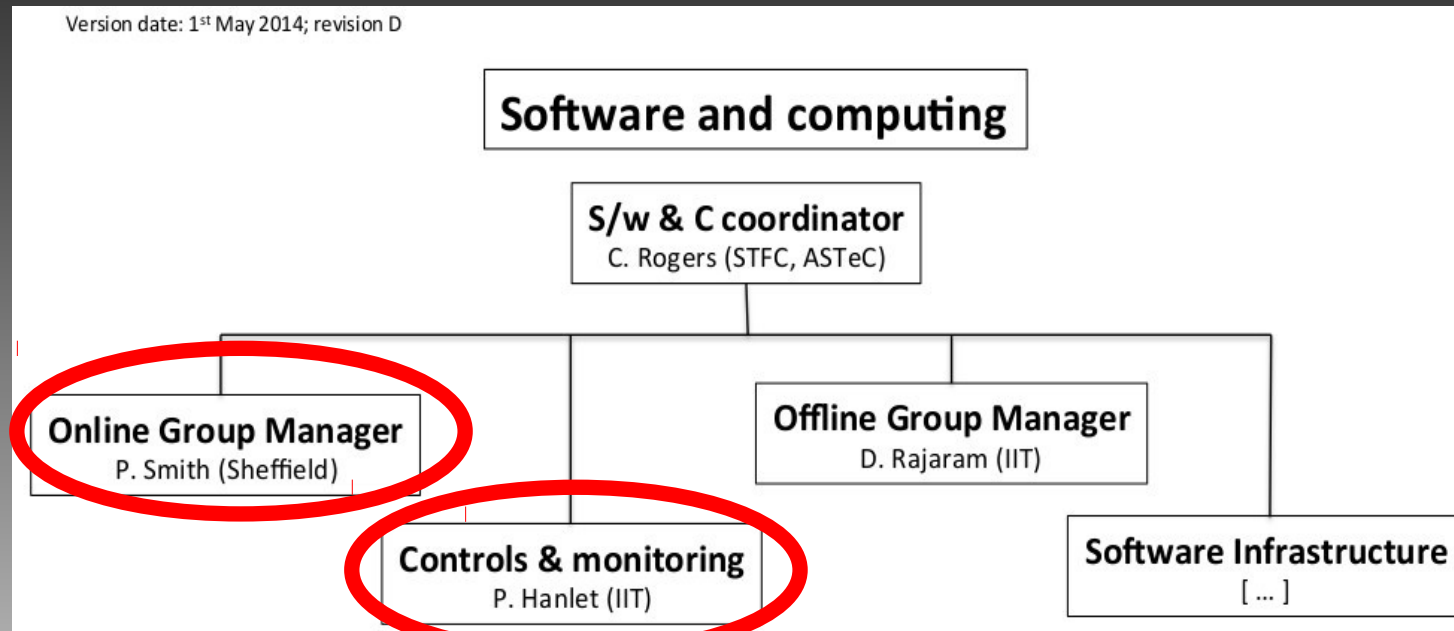
Version date 11 November 2013, Rev. C





Organization

Within MEMO



- *Since last MAP, C&M is its own work package.*
- *Online is under new leadership.*
- *Computing infrastructure continues to be handled by Online*



Outline



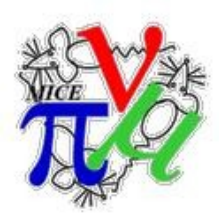
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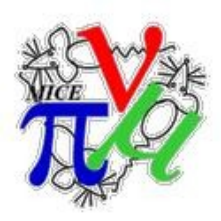
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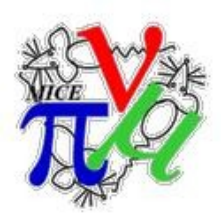
Online Organization

- *Online systems serve to provide platforms for Operations team to interface w/HW*
- *Responsible for HW in MICE Local Control Room (MLCR)*
- *Responsible for HW in Rack Rooms (RR1 & RR2)*
 - *Local Network Switch*
 - *Servers and Operator Interface computers for:*
 - *Online Monitoring*
 - *Online Reconstruction*
 - *C&M*
 - *DAQ*
 - *Trigger*



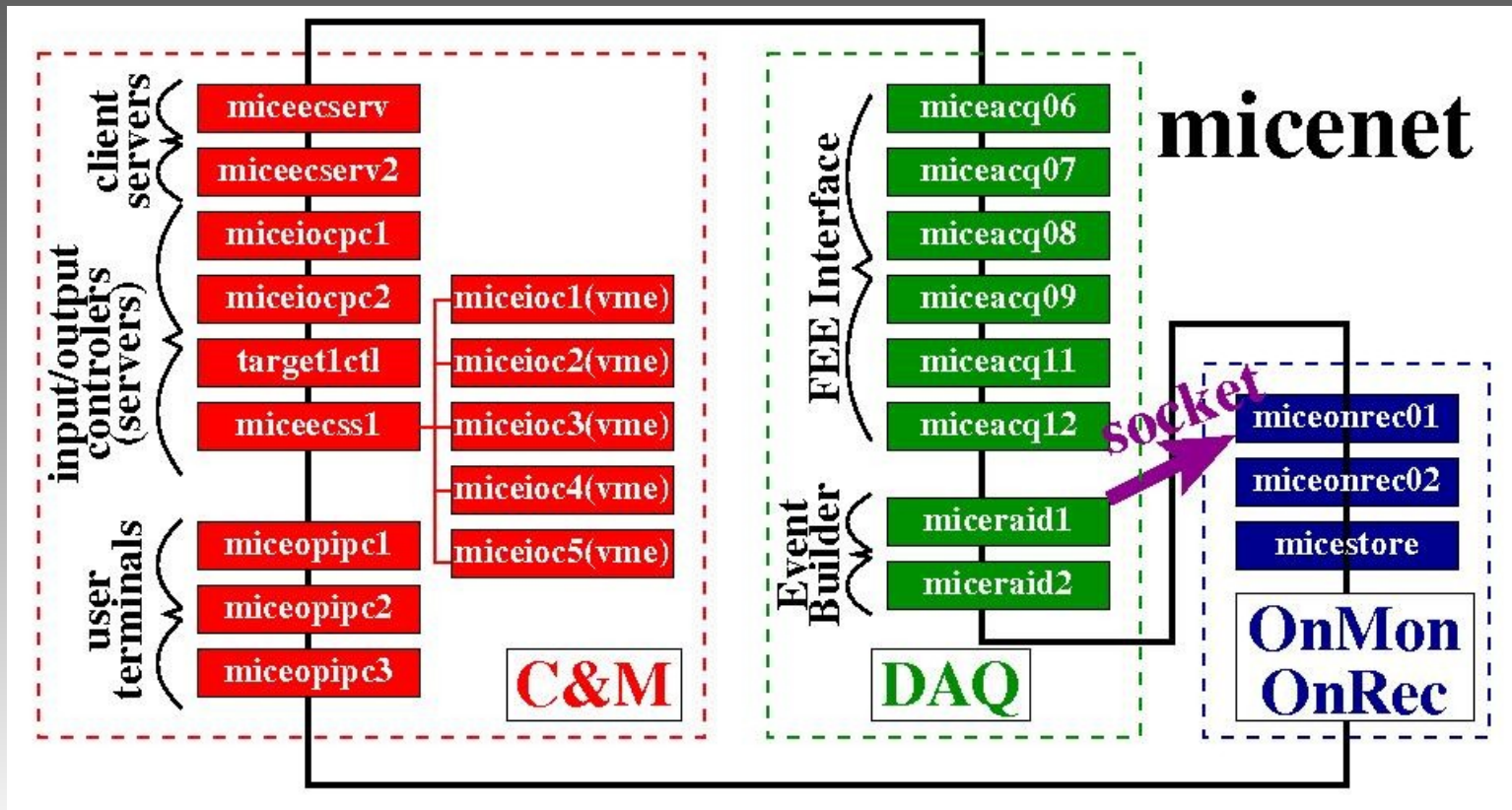
Responsibility: RR1

- **Infrastructure:**
 - Network Switch stack (3+1)
 - UPS (6)
 - KVM (2)
 - miceserv1 and micestore (1 each)
- **Online Monitoring/Reconstruction:**
 - miconrec (3)
- **Machine Type (required + backup)**
- **6 spare servers will soon become available when miceacq machines are replaced**
- **RR2 Hardware list pending**
- **Upgrading C&M pcs to SL6.4**
- **C&M Servers:**
 - micecserv (1+1)
 - miceiocpc (1+1)
 - miceopipc (2+1)
 - target1ctl (1)
 - cagateway (1)
 - miceisisgateway (1)
 - micecss (1+1)
- **DAQ**
 - Detector readout boards
 - trigger hardware
 - miceacq (6)
 - miceraid (2)



Infrastructure: Network

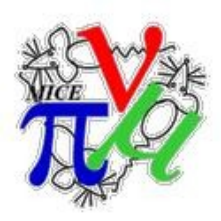
- MICE runs a secure virtual LAN, managed by RAL Networking, of 254 IP addresses
- Forms backbone of C&M, DAQ, and Online Mon/Rec





DAQ and Trigger

- *DAQ is complete and stable*
- *All PID systems now being read out by DAQ*
- *Await full tracker integration (earlier test successful)*
- *No rate limitation observed for MICE expected rates*
- **New FPGA Trigger**
 - *Developed by Geneva*
 - *Replaces NIM/CAMAC based system*
 - *Installed this Spring and tested with pulser*
 - *Awaiting beam running for full commissioning*



Outline

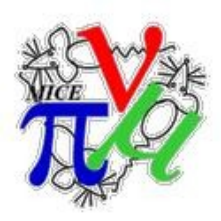
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The Task

“the obvious”

Controls and Monitoring (C&M):

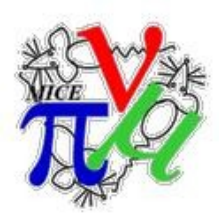
- provide hardware controls
- provide user interfaces
 - synoptic displays – GUIs
- protect equipment
 - alarm handling
 - data archiving
- contribute to protect data quality
 - alarm handling
 - data archiving

Not responsible for personnel protection

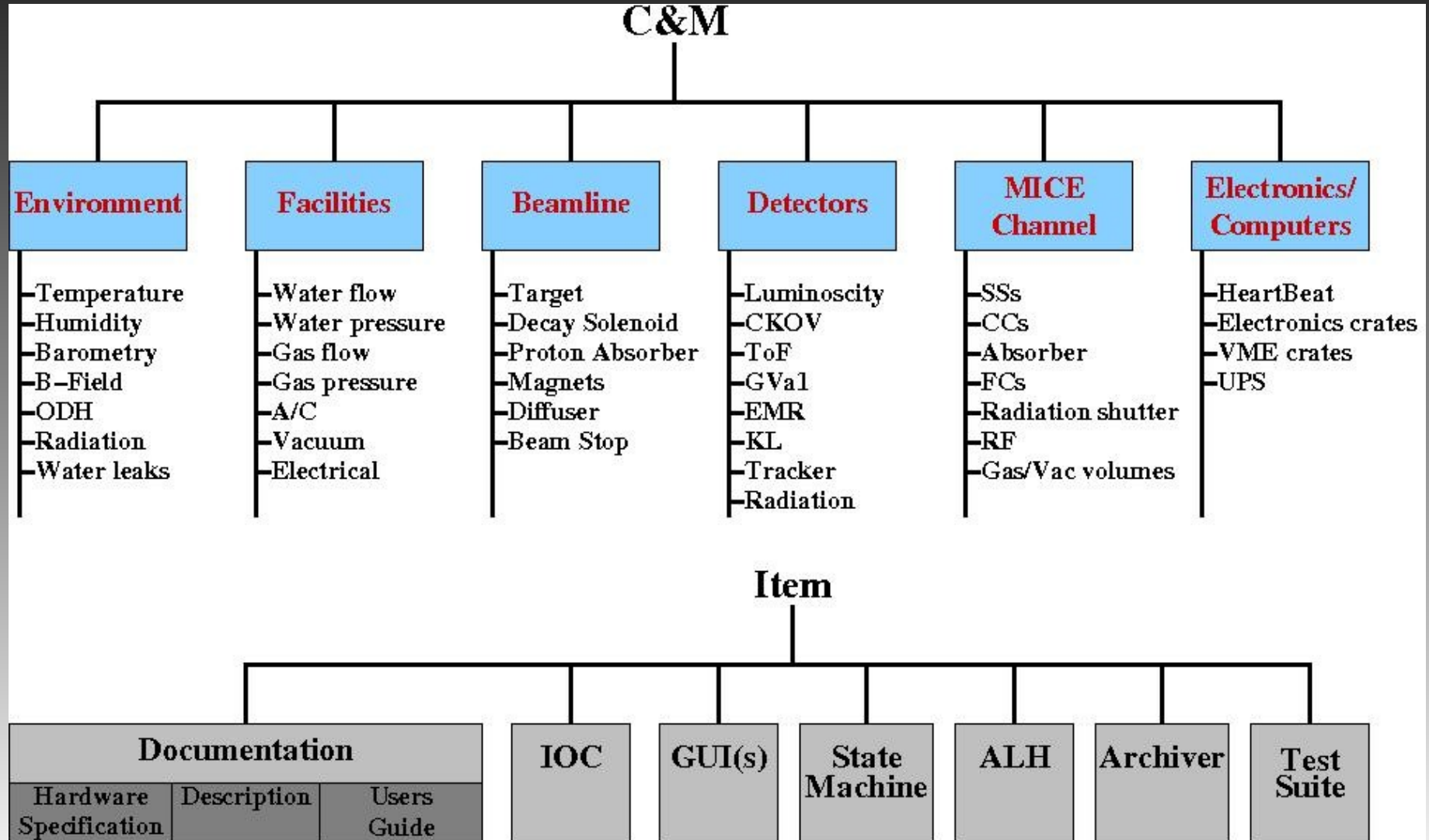


The Procedure

- **Subsystems controls built/commissioned independently**
 - specified by subsystem owners
 - interlocks built in at component level
 - standalone C&M tested with subsystems
- **New integrated C&M hardware**
 - re-arrange racks to share space/resources
 - install in RR2 – allows access while running
- **Higher level controls interface with subsystems**
 - *Document in progress*
 - *MICE-NOTE-GEN-431*



Organization





Organization

Understanding the Scope

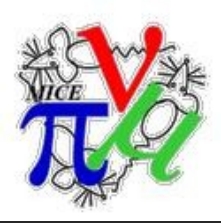
Partial list example

			Owner	Required Time (Hours)	Proportion Done (%)	Person Occupancy	Modifier	Estimated Task Time (Days)	Actual Time Taken
Environment	Temperature Humidity Barometry WaterLeaks	IOC	Hanlet	3	95	60.00%	1	0.03	
		GUI(s)	Hanlet	1	95	60.00%	1	0.01	
		ALH	Heidt	1	80	5.00%	1	0.50	
		Archiver	Heidt	1	80	5.00%	1	0.50	
		StateMachine	NA	0	0	0.00%	1	0.00	
		TestSuite	NA	0	0	0.00%	1	0.00	
		Documentation	Taylor	0	0	50.00%	1	0.00	
	B-Field	IOC	Hanlet	24	0	60.00%	1	5.00	
		GUI(s)	Hanlet	2	0	60.00%	1	0.42	
		ALH	Heidt	1	0	5.00%	1	2.50	
		Archiver	Heidt	1	0	5.00%	1	2.50	
		StateMachine	NA	0	0	0.00%	1	0.00	
		TestSuite	NA	0	0	0.00%	1	0.00	
		Documentation	Uchida	0	0	5.00%	1	0.00	
	ODH	IOC	Hanlet	12	0	60.00%	1	2.50	
		GUI(s)	Hanlet	1	0	60.00%	1	0.21	
		ALH	Heidt	1	0	5.00%	1	2.50	
		Archiver	Heidt	1	0	5.00%	1	2.50	
		StateMachine	NA	0	0	0.00%	1	0.00	
		TestSuite	NA	0	0	0.00%	1	0.00	
		Documentation	Nebrensky	0	0	50.00%	1	0.00	
	Radiation	IOC	Hanlet	24	0	60.00%	1	5.00	
		GUI(s)	Hanlet	1	0	60.00%	1	0.21	
		ALH	Heidt	1	0	5.00%	1	2.50	
		Archiver	Heidt	1	0	5.00%	1	2.50	
		StateMachine	NA	0	0	0.00%	1	0.00	
		TestSuite	NA	0	0	0.00%	1	0.00	
		Documentation	Torun	0	0	1.00%	1	0.00	

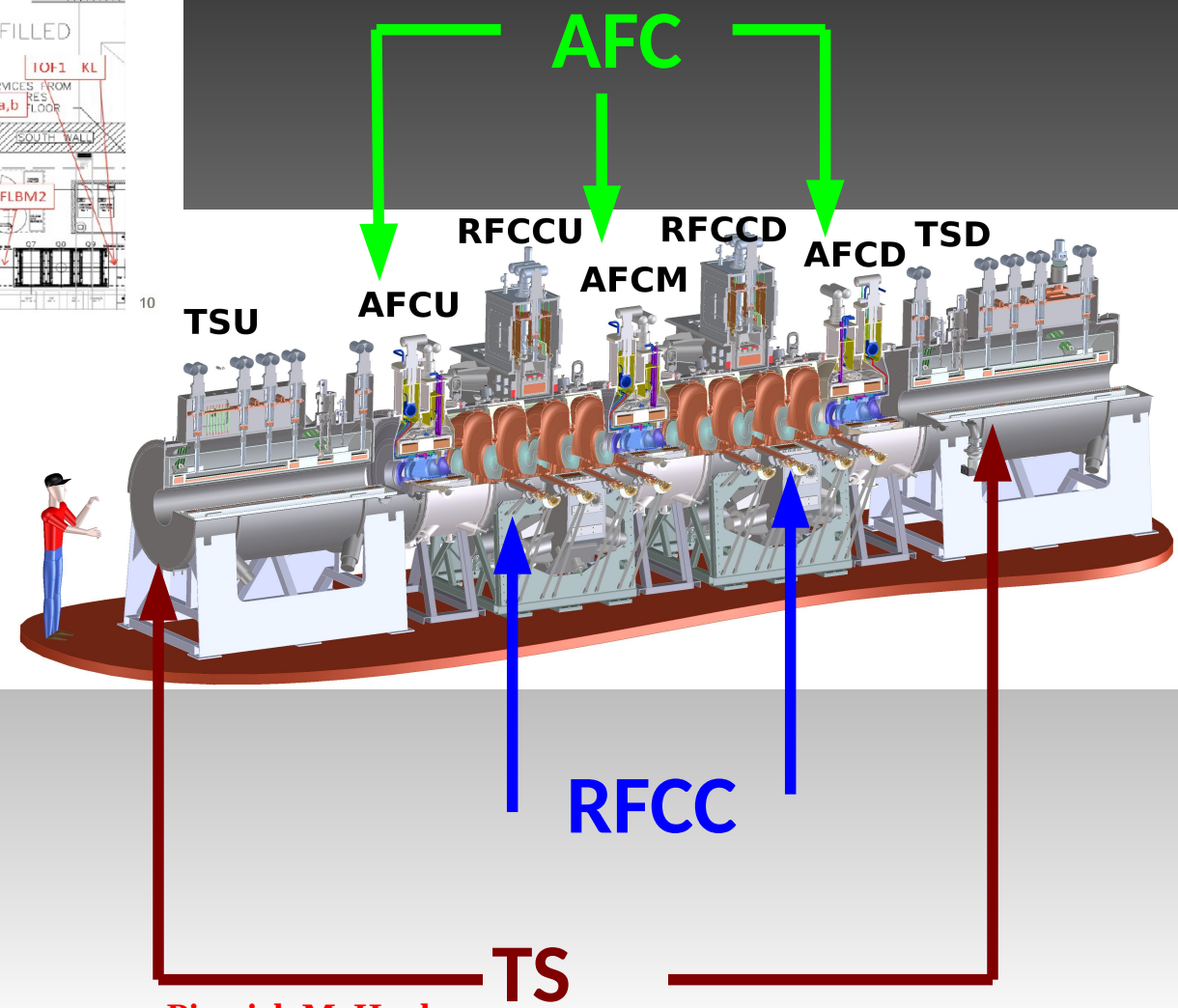
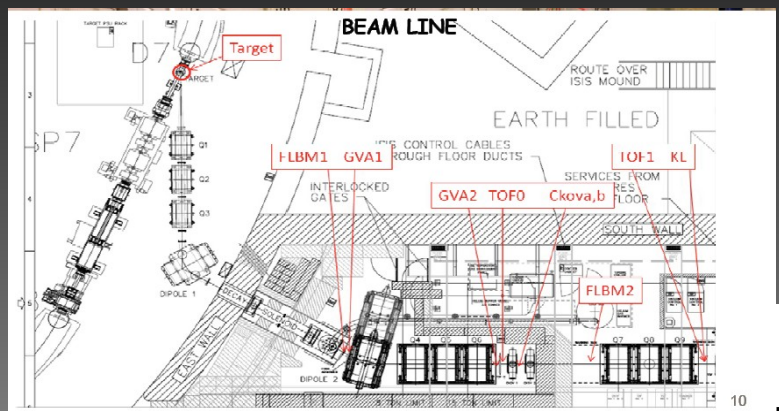


Organization

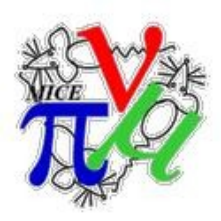
- **Large systems provided by controls team from Daresbury Lab (DL):**
 - **SS/FC/DS/conventional magnets**
 - **LH₂ system**
 - **Integrated cooling channel controls**
 - **FC/DS quench protection**
 - **Target/Tracker infrastructure**
 - **Vacuum**
- **Target/Tracker: Leaver/Robinson/Adey**
- **Coordination/integration: Hanlet**
- **Smaller systems: Hanlet/Taylor/Heidt**



MICE Channel



μ



Controls & Monitoring

•Beamline

- conventional magnets
- proton absorber
- beam stop
- diffuser

•Particle ID (PID)

- GVa1
- ToF 1/2/3
- CKOV A/B
- KL
- EMR

•Environment

- temp./humidity..

•Facilities/Computing

•Target

•SC Solenoids

- spectrometer solenoids
- focus coil(s)
- coupling coils (Step V or VI)
- decay solenoid

•Trackers

•Absorbers

- LH₂
- solid absorbers

•RF (Steps V&VI)

These systems require:

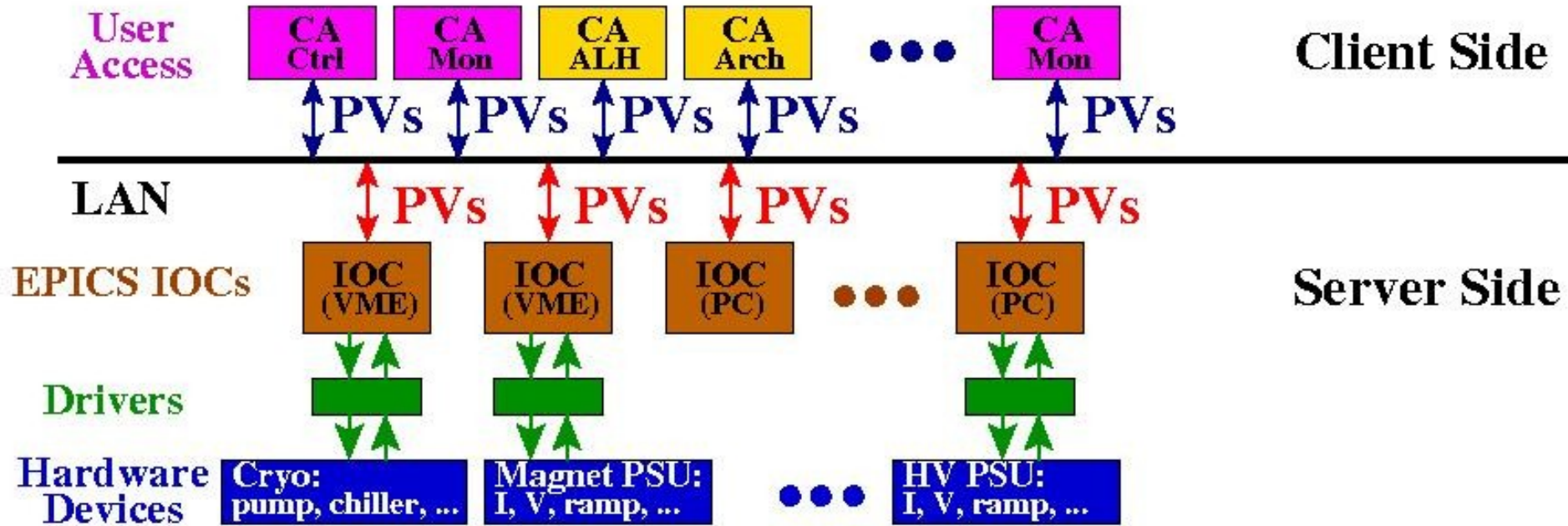
- vacuum
- cryogenics
- power supplies



Framework: EPICS

Experimental Physics & Industrial Control Systems

- HW+Drivers connect to IOCs (Input/Output Controllers)
- IOCs create PVs (process variables) to represent params
- PVs are further described with native fields
- PVs available on LAN to other IOCs or clients

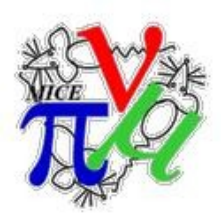




Hardware Description

DL Platform

- IOCs are VME based system with Hytek processors running VxWorks.
- Sensor controllers interfaced via RS232.
- CANbus employed for interlocks/digital controls
- Analog devices monitored/controlled with VME based ADCs and DACs.
- LH₂ system controlled by Omron PLCs
 - EPICS used solely for remote monitoring



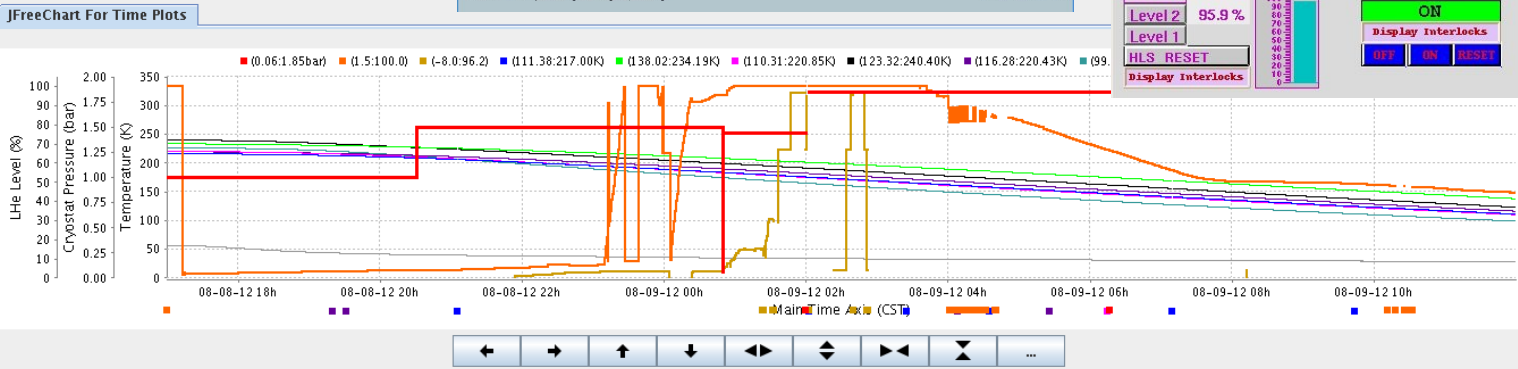
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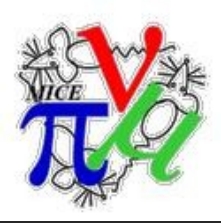
- Other IOCs implemented on Linux PCs
 - Ckov, radiation monitoring, high voltage for the PID detectors, proton absorber, beamstop, RF tuners, environment monitoring, air conditioning, LH₂ monitoring, and computer/electronics "heart beat" monitoring
- Employ a variety of interfaces
 - serial RS232 and RS485, SNMP, and TCP/IP.



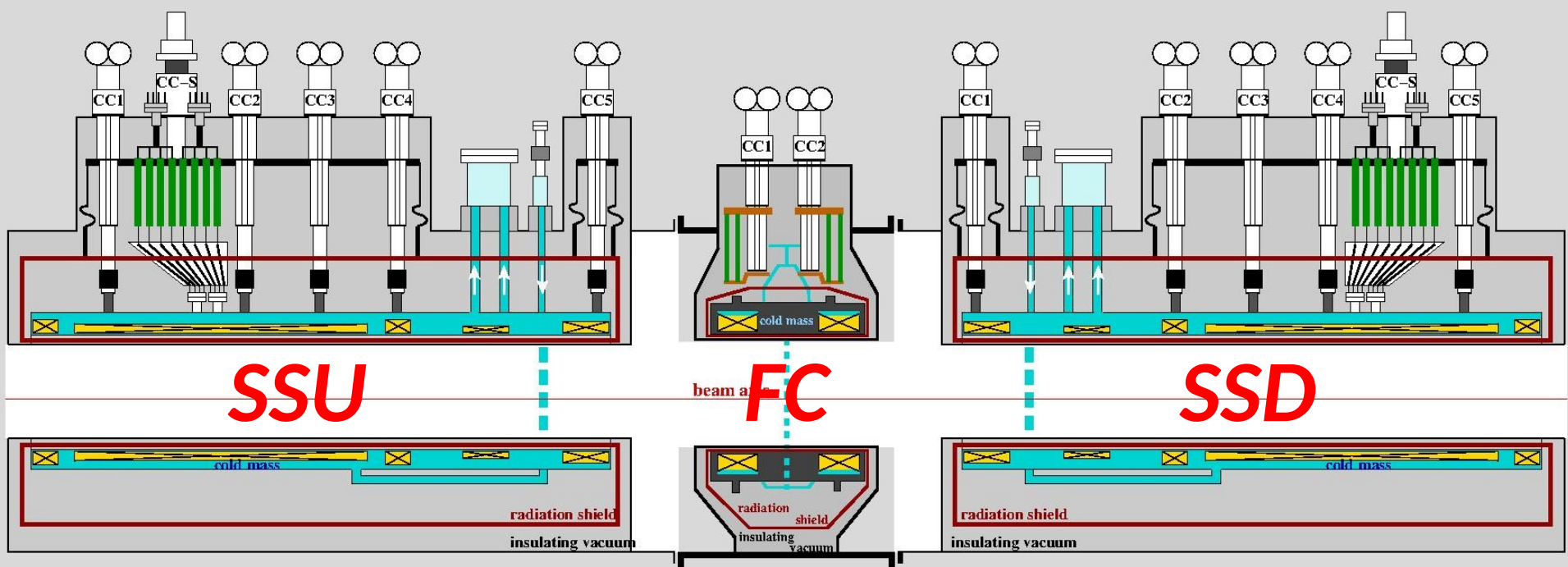
Framework: EPICS

- PVs are used for:
- controlling the hardware
 - interacting with other IOCs
 - graphical displays - GUIs
 - alarm handlers
 - archiving





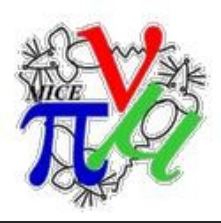
Step IV Interface



- Vacuum
- Compressors
- Cryogenics
- Pressure
- Power Supply

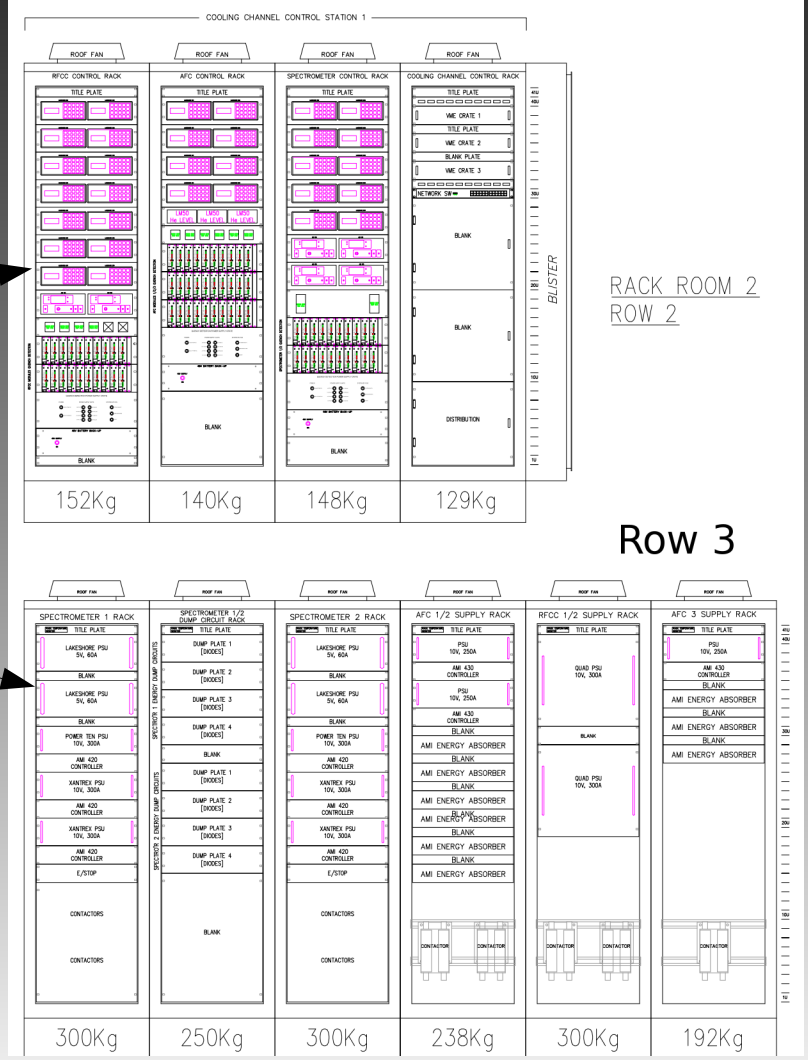
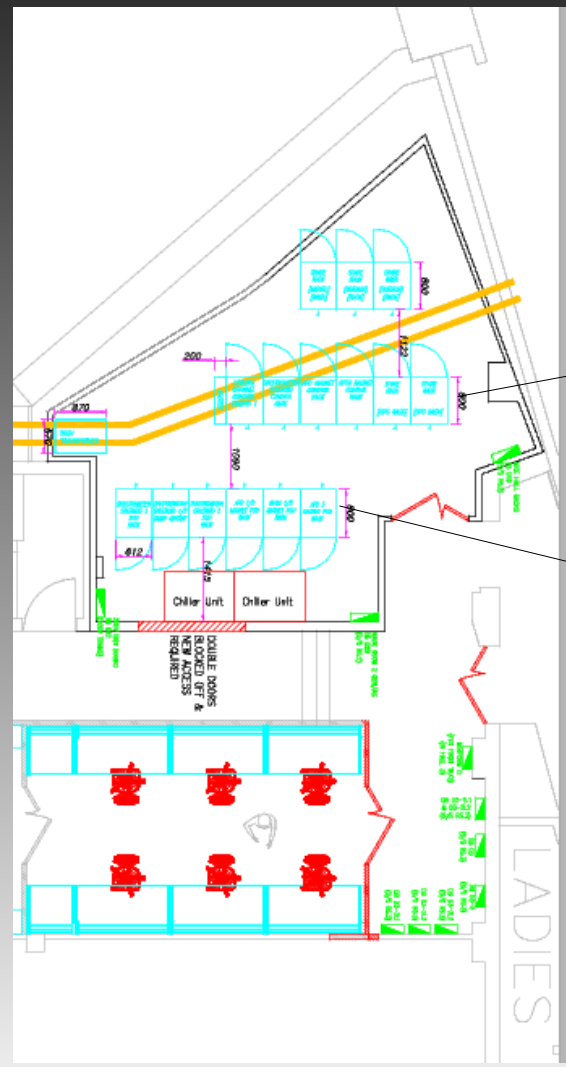
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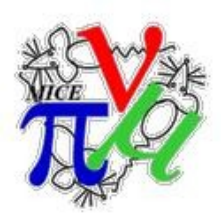
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Hardware Plan

Step IV Rack Layout





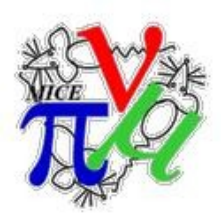
Hardware Progress



DL C&M racks for
Rack Room 2

Awaiting
controllers
to populate
racks

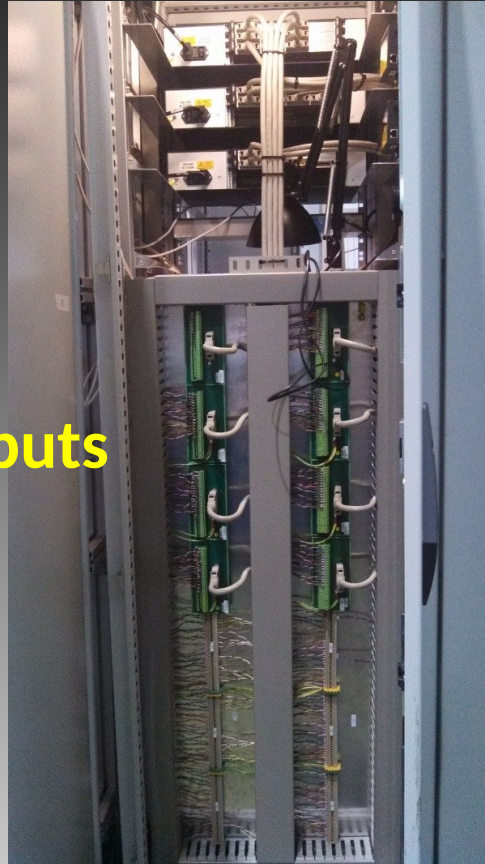




Hardware Progress



Canbus/
Controllers



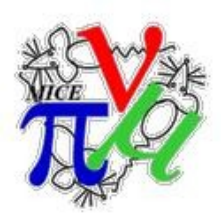
Analog
Sensors

Inputs



Magnet
Power

Energy
Absorber



Higher Level Operation

With installation/commissioning of the new controls HW (DL), the subsystems must be able to operate together, share resources, and not adversely affect each other. These are handled by:

- State Machines for each major subsystem
- Mother State Machine
- Run Control

Documented in MICE Note 431

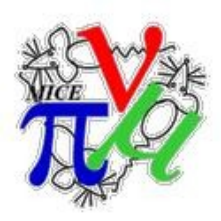


State Machines

EPICS state notation language employed:

- define equipment operational states
- for each state:
 - define transitions out of state
 - set alarm limits
 - set archiving features
 - define critical variables
- check for software interlocks; e.g. quench
- check for errors
- check for transition

All parameters come from configuration database (CDB) – ensures correct settings

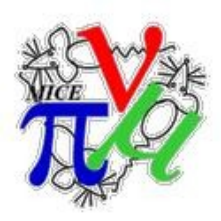


State Machine Requirements

Subsystem Owners must enumerate the states and provide for each state:

- 1) Description of state
- 2) Transition into state
- 3) PVs of interest
- 4) Alarm limits for PVs
- 5) Archiving features for PVs
- 6) AutoSMS (auto dialer) flag
- 7) Hardware interlocks*
- 8) Software “interlocks” (enables)

- Required for each state
- Stored in the CDB



State Machine: SS Example

Spectrometer Solenoid Magnets:

- 1)Offline
- 2)Pumping: establish insulating vacuum
- 3)Pumped_Warm: insulating vacuum established
- 4)Pre_Cooling: N₂ pre-cooling (T>100K)
- 5)Cooling: cryo-coolers lower shield/cold mass T
- 6)LHe_Filling: add liquid He
- 7)Cold_Ready: cold and stable
- 8)Ramping: applying current
- 9)Powered: stable operation
- 10)Quenched: quench detected
- 11)Error: error requires operator intervention
- 12)Testing: interlocks disabled for manual testing

Successfully used in training/mapping SS magnets



SS1 Example

For each state, owner provides

PV Name	Description	Measured		ALARM				Units	ARCHIVE R			Transition		
		Low	High	LoLo	Low	High	HiHi		Mode	Frequency (s)	Headband	Alarm Mgr	Description	Value
NICE-SS1-ACC-01-PPDMM	accelerating vacuum			1.0E-10	1.0E-09	2.0E-09	2.0E-08	torr	normal	300	1.0E-08	TRIP	N/A	0.0
NICE-SS1-SD-01-RBDC	Top of HTS lead #1 side	0.0	0.0	1.00	1.25			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-02-RBDC	Rad Shield near vertical copper plates	0.0	0.0	21.0	2100			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-03-RBDC	CC1 Cu Plate	0.0	0.0	187.0	1870			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-04-RBDC	Rad Shield near HT end upper support	0.0	0.0	225.0	2250			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-05-RBDC	CC2 Cu Plate	0.0	0.0	217.0	2170			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-06-RBDC	Rad Shield	0.0	0.0	221.0	2210			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-07-RBDC	CC1 Stage 1	0.0	0.0	189.0	1890			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-08-RBDC	CC2 Stage 1	0.0	0.0	200.0	2000			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-09-RBDC	CC3 Stage 1	0.0	0.0	212.0	2120			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-10-RBDC	CC4 Stage 1	0.0	0.0	219.0	2190			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-11-RBDC	Cold Head single stage stage	0.0	0.0	690	74			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-12-RBDC	CC5 Stage 1	0.0	0.0	237.0	2370			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-13-RBDC	CC1 Cu Plate	0.0	0.0	245.0	2450			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-14-RBDC	Rad Shield	0.0	0.0	259.0	2590			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-15-RBDC	CM Support HT end lower support	0.0	0.0	265.0	2650			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-16-RBDC	Rad Shield inside bore watching coil end	0.0	0.0	280.0	2800			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-17-RBDC	CM Support watching coil end upper support	0.0	0.0	282.0	2820			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-18-RBDC	Centre of Radiation bore at bottom	0.0	0.0	284.0	2840			K	mean	300		FRISC	N/A	0.0
NICE-SS1-SD-19-RBDC	Bottom of outer cylinder of Radiation shield on the single stage cold head surface	0.0	0.0	225.0	2250			K	mean	300		FRISC	N/A	0.0
NICE-SS1-CA-01-RBDC	Cold Mass bottom by MA	0.0	0.0	105.0	1100			K	mean	300		FRISC	N/A	0.0
NICE-SS1-CA-02-RBDC	Cold Mass top by MA	0.0	0.0	105.0	1100			K	mean	300		FRISC	N/A	0.0
NICE-SS1-CA-03-RBDC	CC3 Cu Plate	0.0	0.0	218.0	2180			K	mean	300		FRISC	N/A	0.0
NICE-SS1-CA-04-RBDC	CC4 Cu Plate	0.0	0.0	223.0	2230			K	mean	300		FRISC	N/A	0.0
NICE-SS1-CA-05-RBDC	CC1 Stage 2	0.0	0.0	179.0	1890			K	mean	300		FRISC	N/A	0.0
NICE-SS1-CA-06-RBDC	CC2 Stage 2	0.0	0.0	207.0	2170			K	mean	300		FRISC	N/A	0.0
NICE-SS1-CA-07-RBDC	CC3 Stage 2	0.0	0.0	219.0	2190			K	mean	300		FRISC	N/A	0.0
NICE-SS1-CA-08-RBDC	CC4 Stage 2	0.0	0.0	227.0	2270			K	mean	300		FRISC	N/A	0.0
NICE-SS1-CA-09-RBDC	CC5 Stage 2	0.0	0.0	242.0	2420			K	mean	300		FRISC	N/A	0.0
NICE-SS1-CA-10-RBDC	Cold Mass bottom of LTS leads	0.0	0.0	200.0	2050			K	mean	300		FRISC	N/A	0.0
NICE-SS1-CA-11-RBDC	Low fill line heater	0.0	0.0	100.0	105.0			K	mean	300		FRISC	N/A	0.0
NICE-SS1-CA-12-RBDC	Cold Mass bottom heater	0.0	0.0	100.0	105.0			K	mean	300		FRISC	N/A	0.0
NICE-SS1-CA-13-RBDC	Top of HTS lead #2 side	0.0	0.0	129.0	1340			K	mean	300		FRISC	N/A	0.0
NICE-SS1-CC-01-STA	Cryo Compressor 1 status	0.0	0.0	0.0	0.0			-	normal	60.0	0.0	TRIP	N/A	0.0
NICE-SS1-CC-02-STA	Cryo Compressor 2 status	0.0	0.0	0.0	0.0			-	normal	60.0	0.0	TRIP	N/A	0.0
NICE-SS1-CC-03-STA	Cryo Compressor 3 status	0.0	0.0	0.0	0.0			-	normal	60.0	0.0	TRIP	N/A	0.0
NICE-SS1-CC-04-STA	Cryo Compressor 4 status	0.0	0.0	0.0	0.0			-	normal	60.0	0.0	TRIP	N/A	0.0
NICE-SS1-CC-05-STA	Cryo Compressor 5 status	0.0	0.0	0.0	0.0			-	normal	60.0	0.0	TRIP	N/A	0.0
NICE-SS1-CC-01-ALM	Cryo Compressor 1 OK of alarm states	0.0	0.0	0.0	0.0			-	normal	60.0	0.0	TRIP	N/A	0.0
NICE-SS1-CC-02-ALM	Cryo Compressor 2 OK of alarm states	0.0	0.0	0.0	0.0			-	normal	60.0	0.0	TRIP	N/A	0.0
NICE-SS1-CC-03-ALM	Cryo Compressor 3 OK of alarm states	0.0	0.0	0.0	0.0			-	normal	60.0	0.0	TRIP	N/A	0.0
NICE-SS1-CC-04-ALM	Cryo Compressor 4 OK of alarm states	0.0	0.0	0.0	0.0			-	normal	60.0	0.0	TRIP	N/A	0.0
NICE-SS1-CC-05-ALM	Cryo Compressor 5 OK of alarm states	0.0	0.0	0.0	0.0			-	normal	60.0	0.0	TRIP	N/A	0.0
NICE-SS1-PS-01-RP	Low fill pressure from ABC	1.0E	1.1E	1.90	2.00			bar	normal	1.0	0.02	FRISC	N/A	0.0
NICE-SS1-PS-01-ALM	Low of alarm states	0.0	0.0	0.0	0.0			-	normal	1.0	0.00	FRISC	N/A	0.0
NICE-SS1-PS-01-ERR	communication error codes							-	normal	1.0	0.00	FRISC	N/A	0.0
NICE-SS1-PS-02-RP	High fill pressure from ABC	1.0E	1.1E	1.90	2.00			bar	normal	1.0	0.02	FRISC	N/A	0.0
NICE-SS1-PS-02-ALM	High of alarm states	0.0	0.0	0.0	0.0			-	normal	1.0	0.00	FRISC	N/A	0.0
NICE-SS1-PS-02-ERR	communication error codes							-	normal	1.0	0.00	FRISC	N/A	0.0
NICE-SS1-HET-01-SES	Cold mass heater	0.0	0.0	0.0	1.0			-	normal	1.0	0.0	TRIP	N/A	0.0
NICE-SS1-HET-02-SES	High mass heater	0.0	0.0	0.0	1.0			-	normal	1.0	0.0	TRIP	N/A	0.0
NICE-SS1-LEVEL-01-RLV	Low level	0.0	0.0	190.0	1000			%	mean	0.0	0.0	FRISC	Low=85%	85.0
NICE-SS1-LEVEL-02-SES	Low level switch	-1.0	-1.0	2.0	2.0			normal	0.0	0.0	FRISC	N/A	0.0	
NICE-SS1-LEVEL-03-RLV	Low level overflow	0.0	0.0	100	20.0			%	mean	0.0	0.0	FRISC	N/A	0.0

Load these to CDB

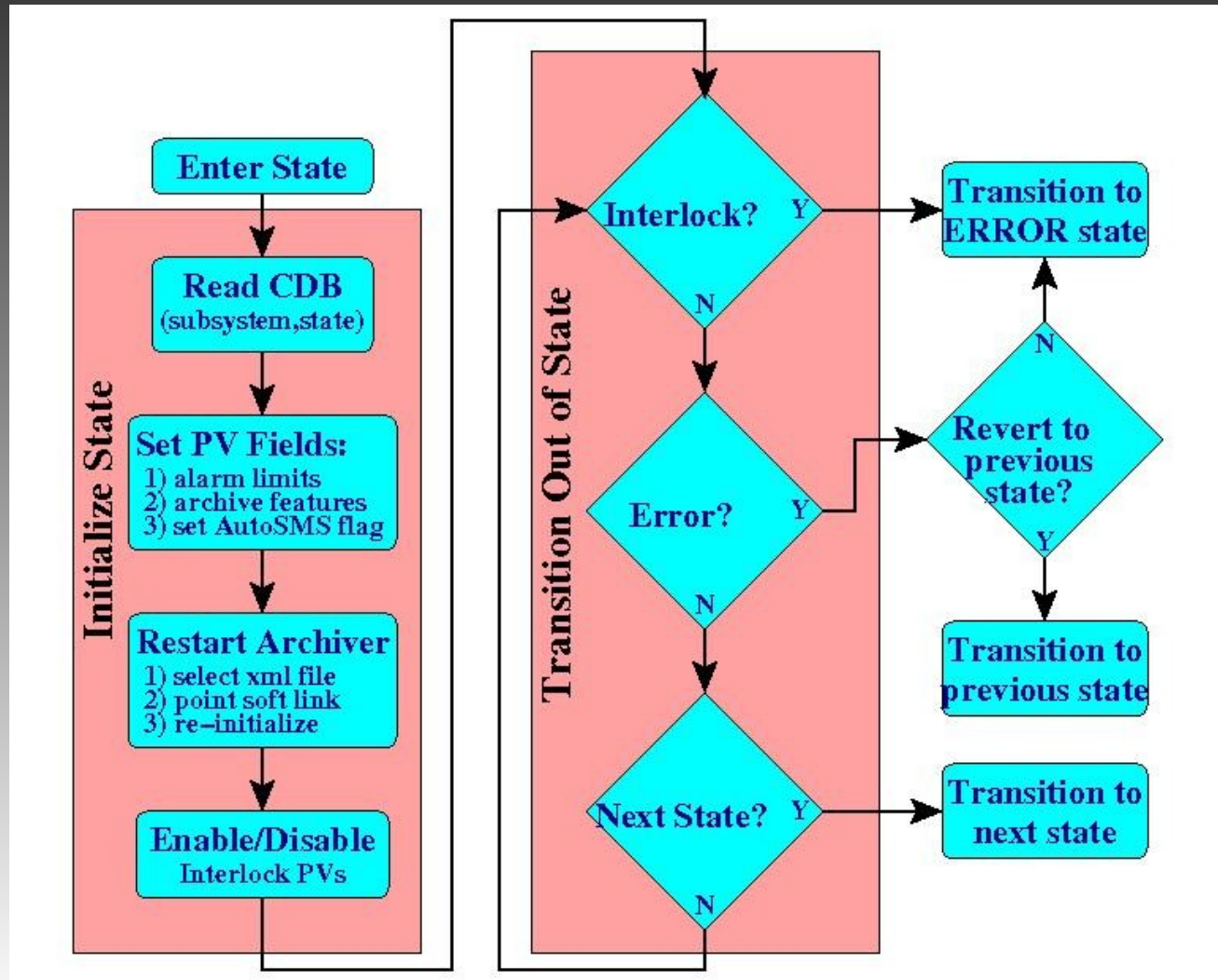


State Machine Algorithm

For each subsystem & state, the algorithm:

Transitions:
• manual
• automatic

Note: states can be static or dynamic





State Machine Status

Existing (*at least started*):

- Spectrometer Solenoids
- Focus Coil
- Decay Solenoid

Required (*not started*):

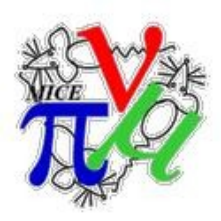
- Absorber
- Conventional magnets
- Target
- Trackers



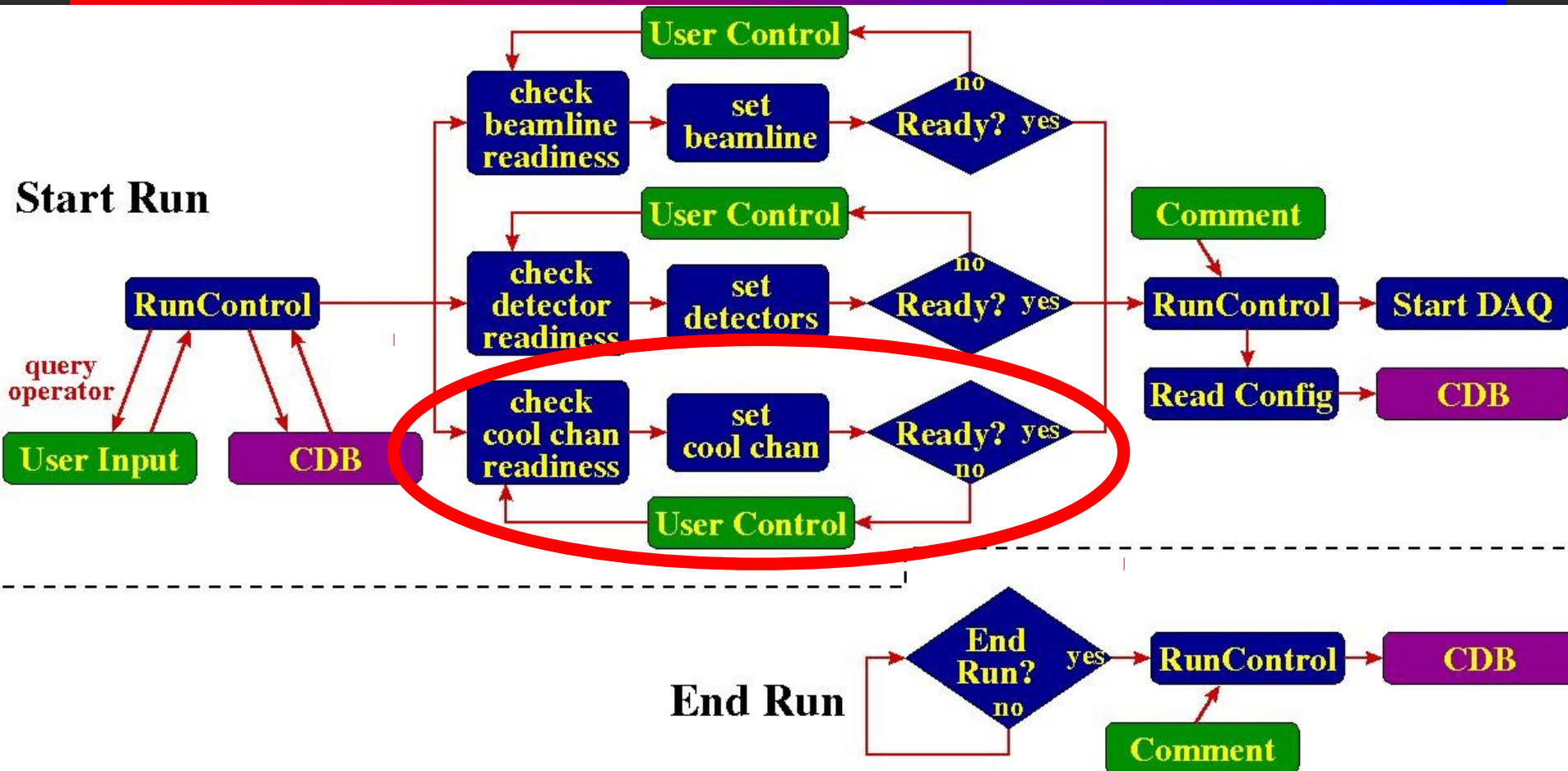
Run Control

Checks readiness of all required subsystems

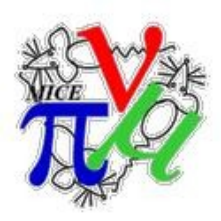
- Serves to control
 - Beamline magnets
 - Particle ID detectors
 - Trackers
 - Absorber(s)
 - Channel magnets power supplies
 - RF (Step V or VI)
- Integrates:
 - Beamline
 - DAQ
 - target
 - tracker
 - absorbers
 - SC magnets



State Machine Effect on RunControl



State machines for magnet control greatly reduces complexity of RunControl. RC need only check state of each magnet.



Other Items

•Risks

- Personnel
- Expertise
- Tests

•Infrastructure

- computing
- code repository
- documentation

* Ian Taylor

•Cleaning up

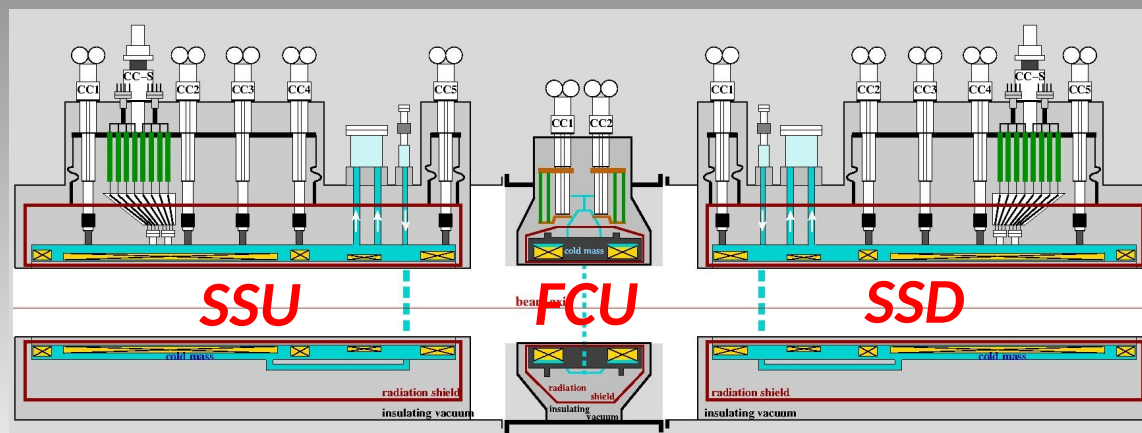
- production and development versions
- Alarm Handlers and Archivers
- testing tools

* Chris Heidt



Conclusions

- Online systems in good shape: infrastructure and DAQ
- Much C&M progress since last MAP CM
- Resource loaded schedule completed
- Integrated HW plan in place
- State machines under development
- Still risks in personnel and expertise



- **Needs to be finished within ~10 months!**