

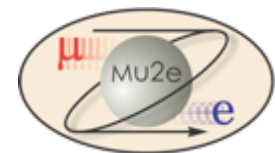


U.S. DEPARTMENT OF
ENERGY

Office of
Science

Director CD-2 review: Mu2e Calorimeter

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Outline

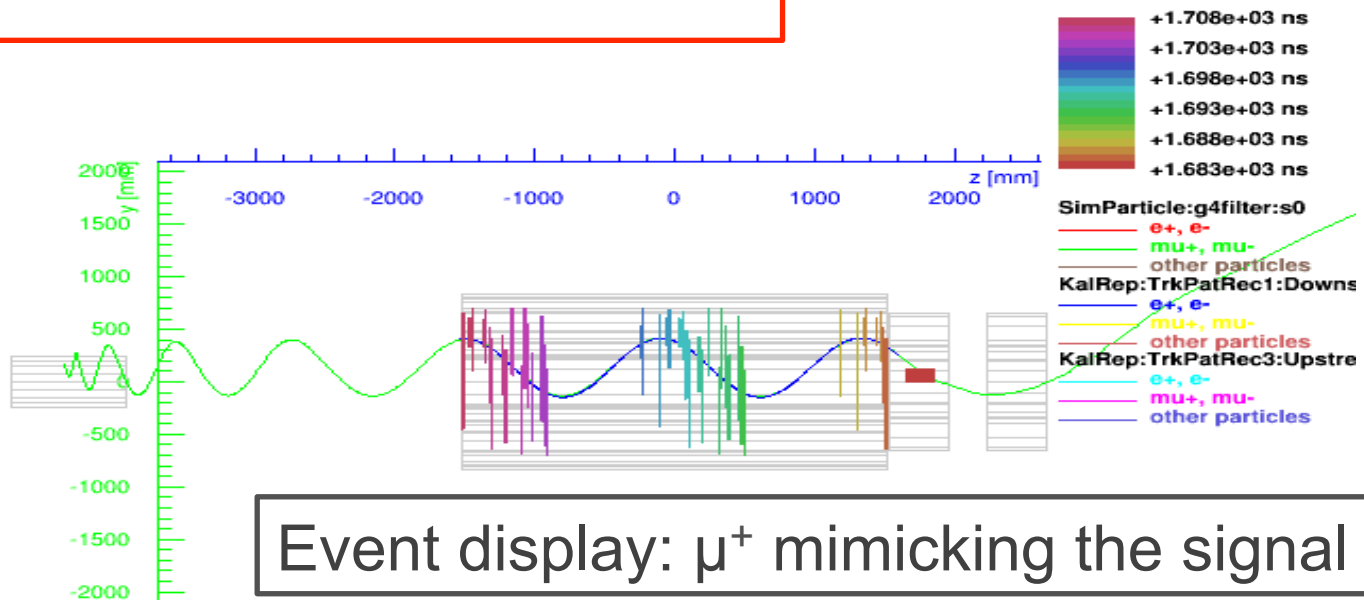
- **Particle Identification (PID)**

- **Calorimeter driven pattern recognition**

PID – Requirement

- CRV studies showed:
 - Assuming a CRV inefficiency of 10^{-4}
 - To of have < 0.1 fake events from atmospheric particles

➤ μ rejection factor ~ 200 is needed!



Run #: 16467483
Sub Run #: 921
Event #: 766909

PID – Cosmic rays background

- Cosmic rays can either interact or be captured in the Detector solenoid, mimicking the signal in several ways:
 1. Positive particles (e^+ , μ^+) moving upstream, reconstructed as downstream tracks
 2. Negative particles (e^- , μ^-) moving downstream and reconstructed as downstream particles
- **Positive particles** can be clearly identified just comparing the calo-cluster time with the track impact time
- The **irreducible** part is from e^- : only the CRV can veto that!
- How can μ^- be identified?

PID – Cosmic rays background

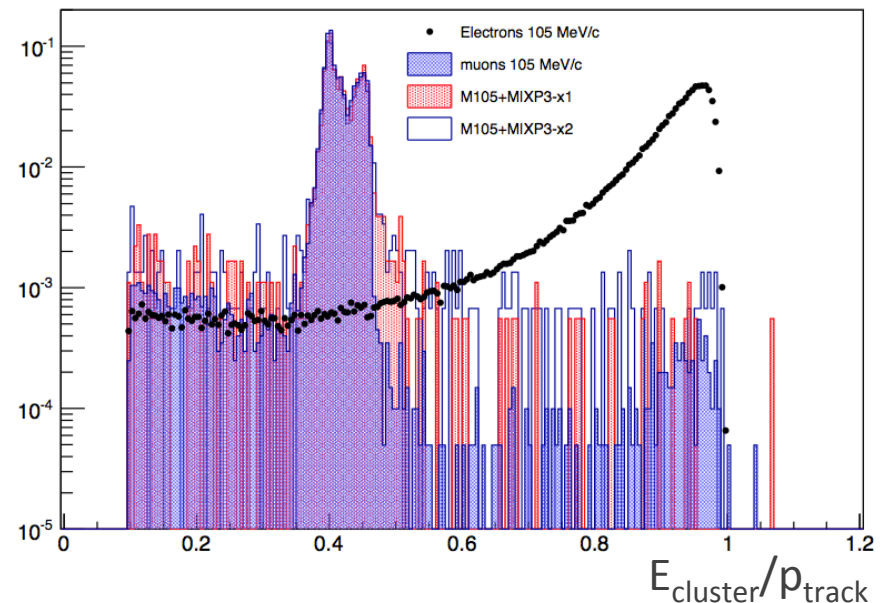
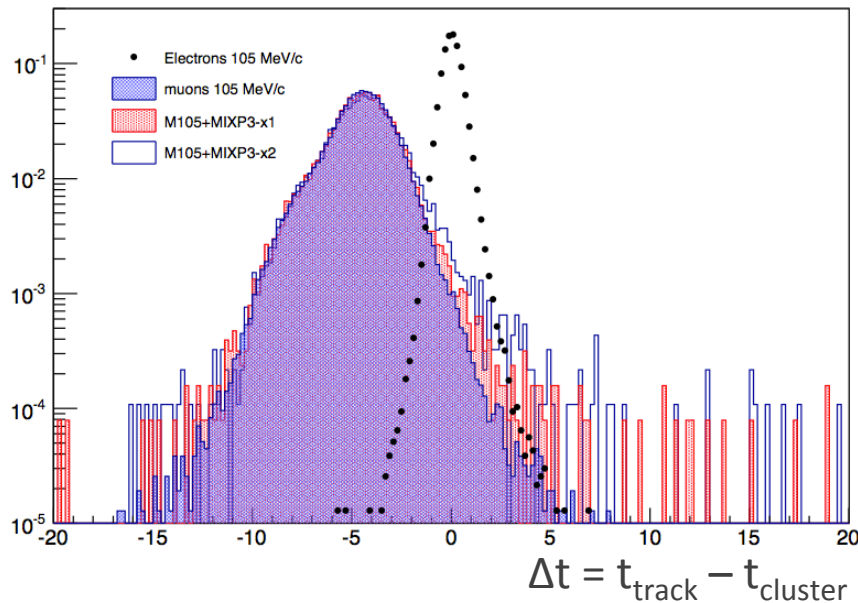
- μ 's with $p = 104.97$ MeV/c are no longer relativistic particles!
- This implies also that their kinetic energy is too low!

$$\beta = \frac{p}{E} \sim 0.7, \quad E_{kin} = E - m \sim 40 \text{ MeV}$$

- **Timing** and **energy** information result to be very good discriminant parameters for tagging μ !

PID – basic idea

- Compare the reconstructed track and calorimeter information:
 - $E_{\text{cluster}}/p_{\text{track}}$
 - $\Delta t = t_{\text{track}} - t_{\text{cluster}}$, where t_{track} is the track time extrapolated to the calorimeter and t_{cluster} is the reconstructed cluster time



PID – Algorithm

Two steps used for doing the PID:

1. Define a likelihood using distributions in $E_{cluster}/p_{track}$ and Δt :

$$\ln L_{e,\mu} = \ln P_{e,\mu}(\Delta t) + \ln P_{e,\mu}(E_{cluster}/p_{track})$$

$P_{e,\mu}(\Delta t)$ and $P_{e,\mu}(E/p)$ are the pdf for e and μ respectively

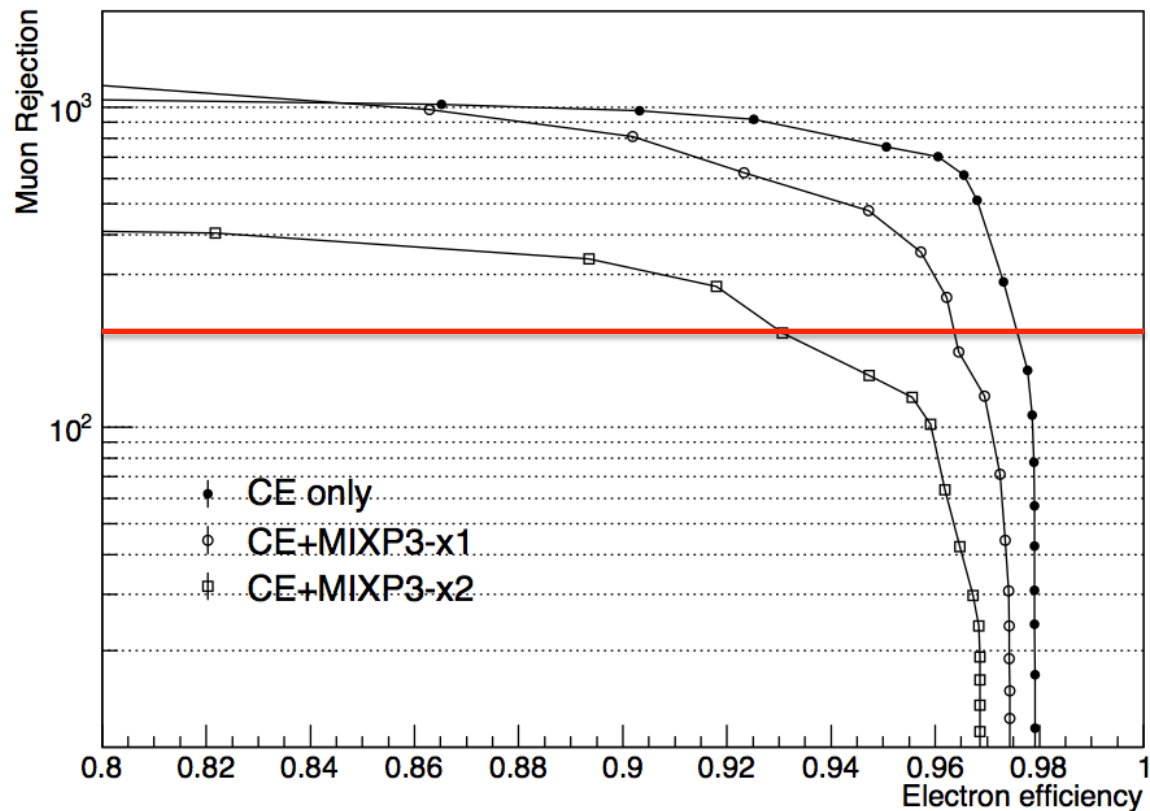
2. The ratio of the likelihoods is the final parameter used:

$$\ln L_{e/\mu} = \ln \frac{L_e}{L_\mu} = \ln L_e - \ln L_\mu$$

PID – Performance

- μ rejection of 200 results in an e^- efficiency of $\sim 96\%$
- background occupancy x2 scales the e^- efficiency at $\sim 93\%$

Muon Rejection Vs Electron Efficiency



PID – Calorimeter assumptions

- Toy MC used for evaluating the PID performance with respect to the expected calorimeter timing and energy resolutions
- The adopted procedure follows:
 1. Smear the E/p and Δt distributions with Gaussian functions according to the calorimeter resolution
 2. Remade the pdf for μ and e
 3. Evaluate the likelihood ratio using pseudo experiments

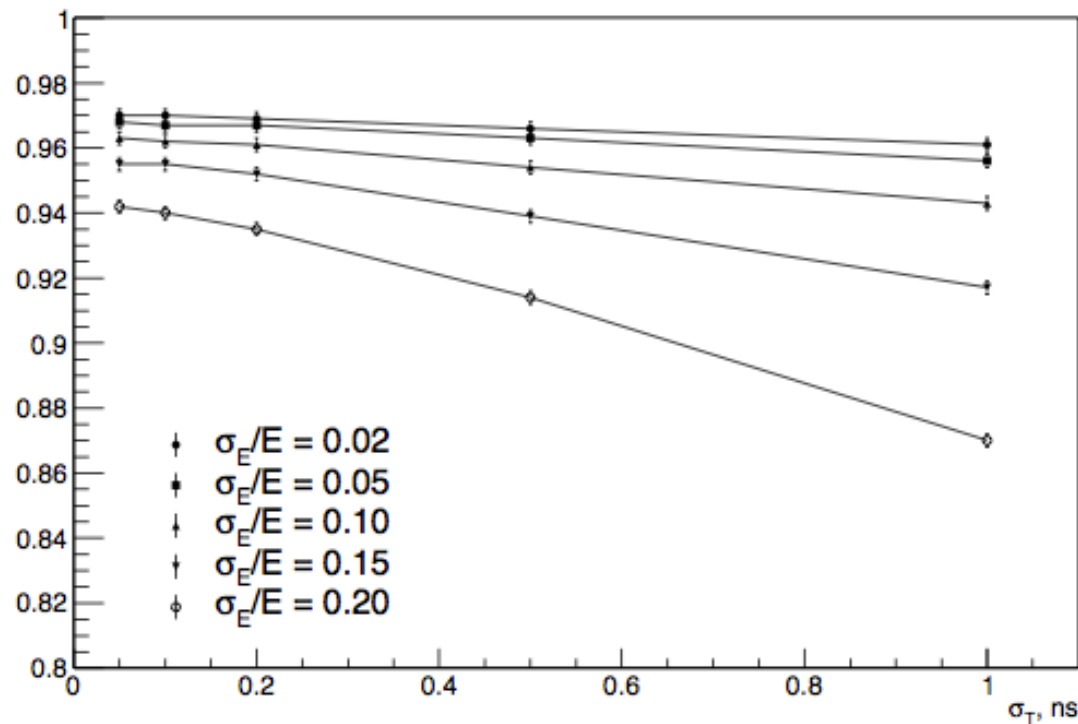
PID – Resolutions vs e⁻ efficiency

- In the expected range of resolution:

$$\sigma_E/E < 0.1, \sigma_t < 0.5 \text{ ns}$$

the e⁻ efficiency is stable up to 2%

Electron efficiency for muon rejection of 200

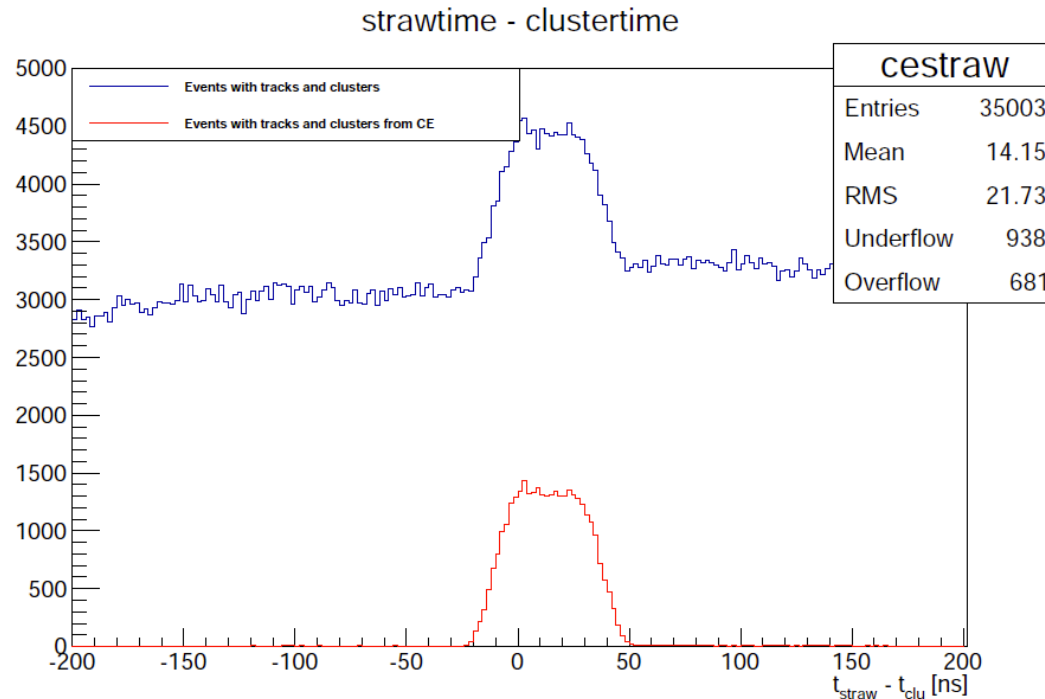


PID – Conclusion

- Calorimeter timing and energy information provide a good μ identification satisfying the experiment requirement
- Worst scenario with bkg occupancy x2 scales e^- efficiency of about 3%
- Toy MC showed that in the range of the expected calorimeter resolutions the e^- efficiency is stable up to 2%

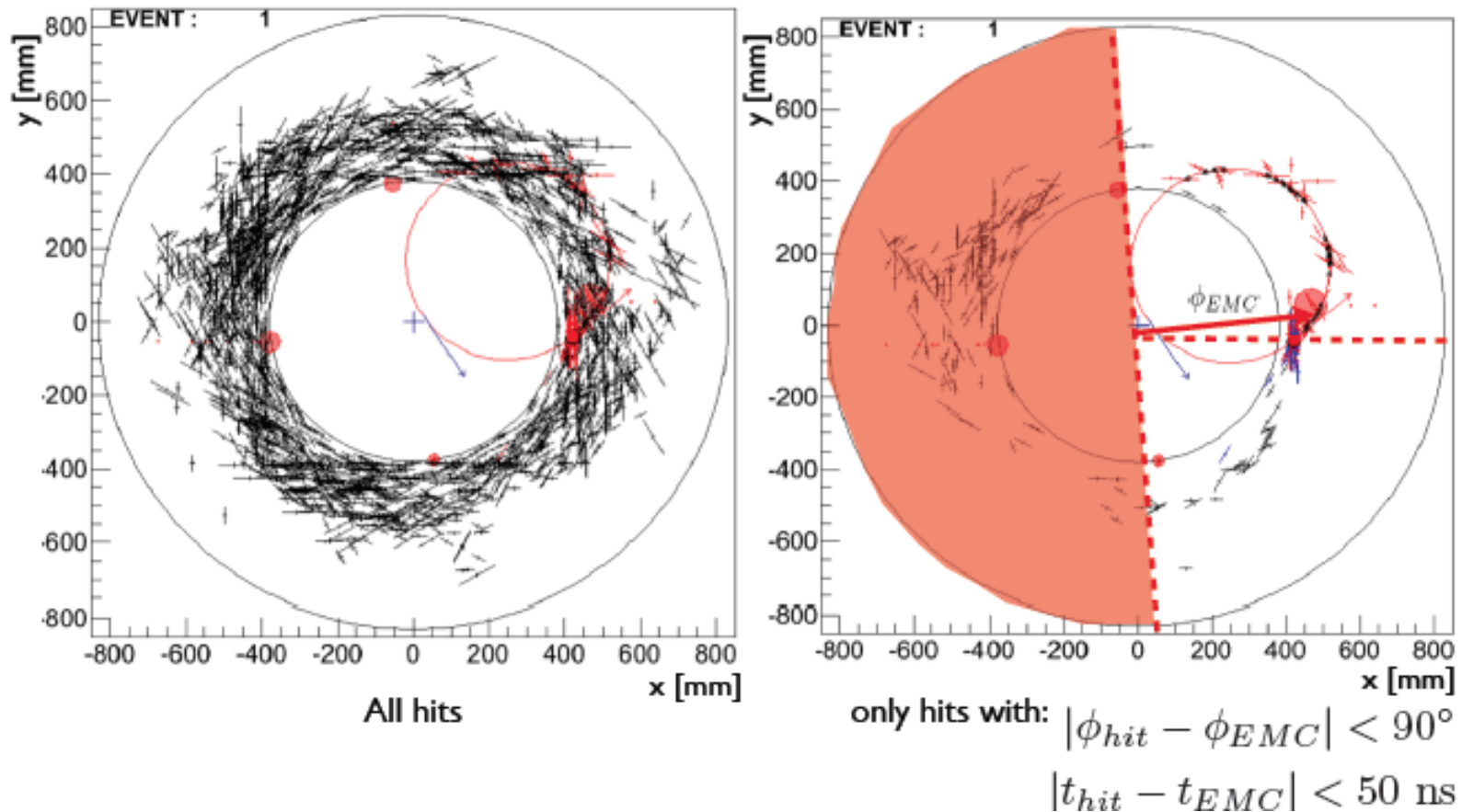
Why a calo-based Pattern Reconstruction?

- Pattern recognition in the tracker does NOT use any assumption on the track- t_0 (crossing time of the middle of the tracker)
- Straw hits and calorimeter cluster of the same track have strong correlation!



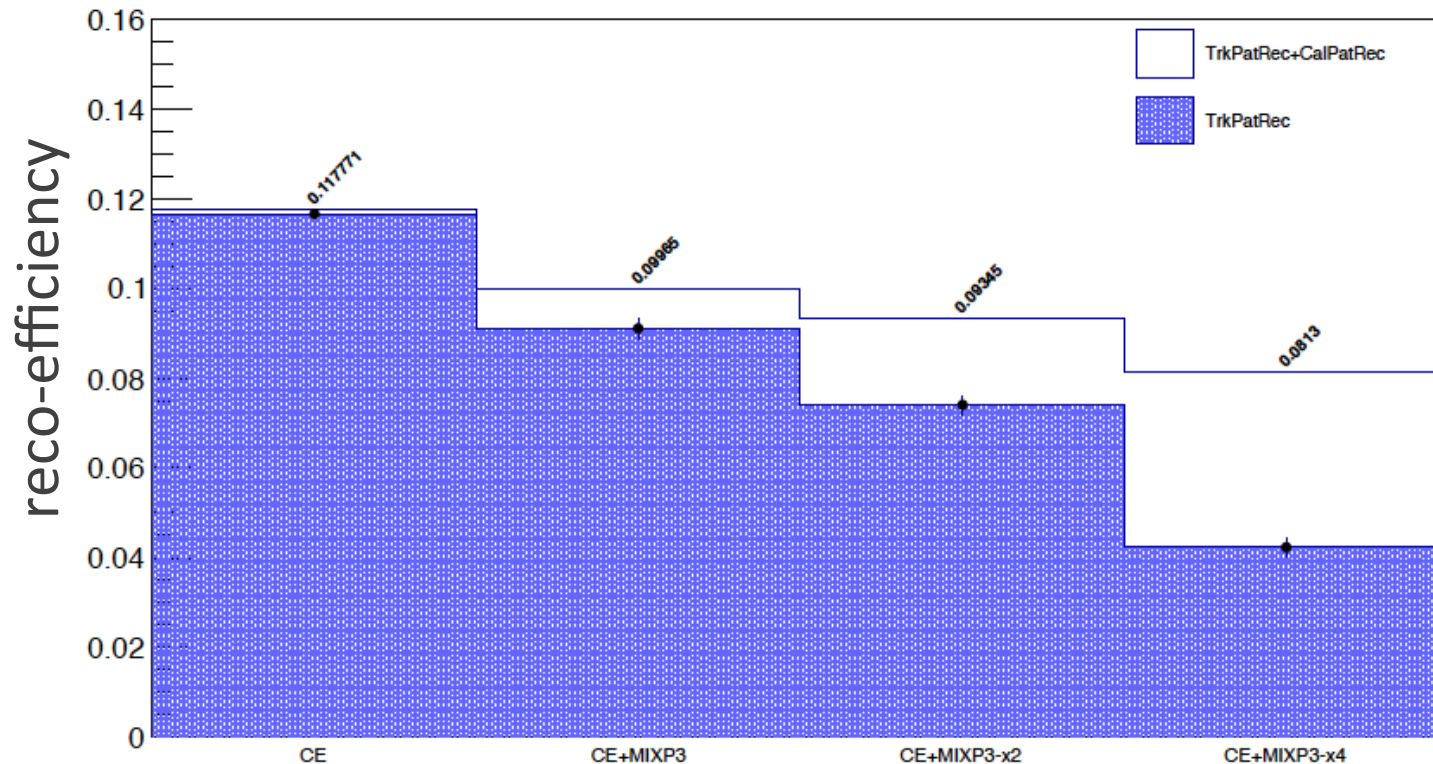
CalPatRec – Event display

- **Patter recognition:** cluster time and position used to select the right pattern of straw hits



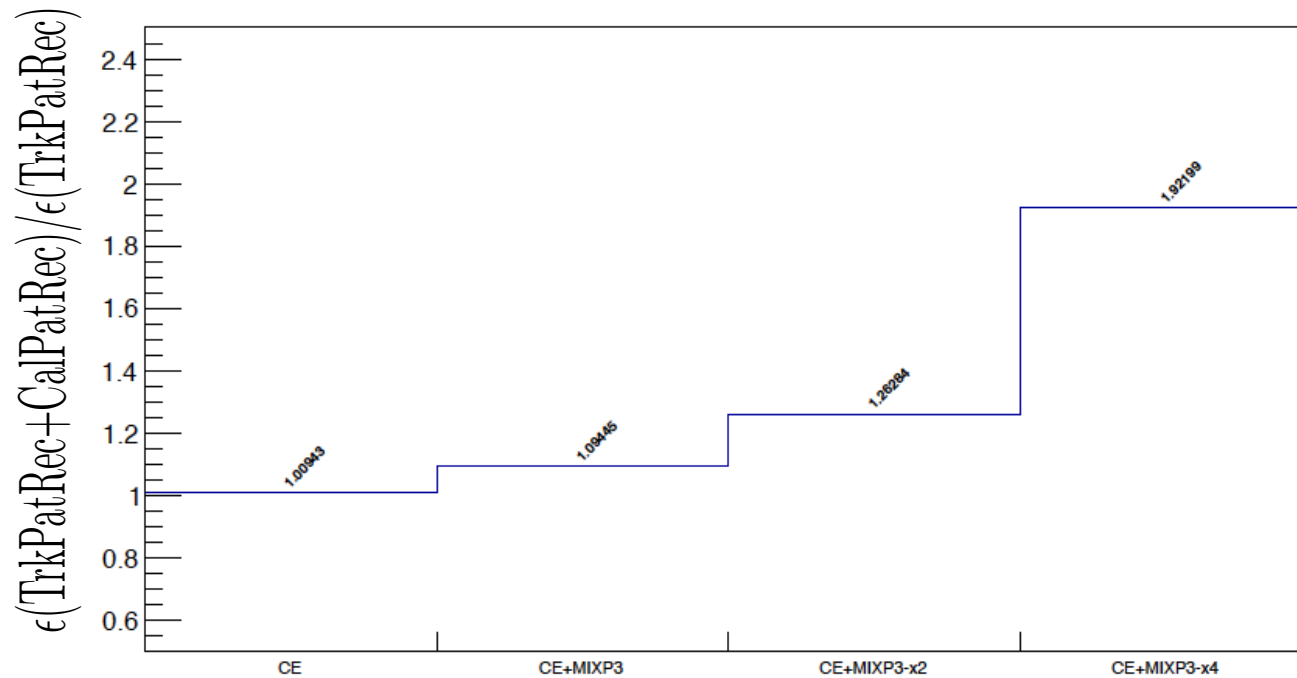
CalPatRec - Results

- Using the or of CalPatRec and the default (TrkPatRec) efficiency scales from $\sim 12\%$ to $\sim 8\%$ up to occupancy $\times 4$
- Wo CalPatRec efficiency goes down to $\sim 4\%$



CalPatRec - Results

- With the expected background occupancy CalPatRec adds ~10% (relative)
- At occupancy x4 CalPatRec improves the reco-efficiency by a factor 1.9



CalPatRec - Conclusion

- CalPatRec allows to recover 10% of the default reconstruction efficiency
- CalPatRec makes the reco-algorithm more stable also in higher occupancy scenarios



Backup slides