

LArSoft Architecture Meeting

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Agenda

- Proposed changes to low-level architecture
- Discussion that leads to approving, or actions / decisions needed first

Scope of discussion

- What we need to consider
 - Changes to address issues identified via internal review of data products, input from experiments (mostly uBooNE), discussion from previous meetings and in hallways
 - Restrict ourselves to low-level data products
 - Will address high-level data products later
- What we will not consider
 - Questions regarding which algorithms will actually be used
 - Just agree on the abstractions needed to support existing or anticipated algorithms
 - The effort required, resources available, schedules for the changes
 - This should be a separate discussion with experiment management
 - Now just need to decide on the eventual objectives

The “low-level” data products considered

- raw::RawDigit
- recob::Wire
- recob::Hit
- recob::Cluster
- recob::EndPoint2
- recob::Track

raw::RawDigit

- Proposed change
 - Remove pedestal value
 - If subtracted prior to building the object, then not needed
 - It's in a database or somewhere else anyway
 - If calculated on the fly, then it's not needed in the RawDigit
 - Introduce values + methods to flag if a channel is saturated
 - Needed in the case that RawDigit contains pedestal-subtracted values

Current interface:

```
public:
    std::vector<short> fADC;

    // Set Methods
    void          SetPedestal(double ped);

    // Get Methods
    unsigned int  NADC()          const;
    short         ADC(int i)      const;
    uint32_t      Channel()       const;
    unsigned short Samples()      const;
    double        GetPedestal()   const;
    double        GetSigma()      const;
    raw::Compress_t Compression() const;
```

recob::Wire

- Recently modified to accommodate regions of interest
 - This was an important, useful change
- Further change proposed
 - Store the channel number internally
 - Eliminate internally stored art::Ptr to RawDigit, replace with external association
 - Eliminate SignalType() method
 - Implicit in the plane, so needn't be in each Wire object

Current recob::Wire

public:

```
// ROI constructor
Wire(const RegionsOfInterest_t& sigROIlist,
      art::Ptr<raw::RawDigit> &rawdigit);
Wire(RegionsOfInterest_t&& sigROIlist,
      art::Ptr<raw::RawDigit> &rawdigit);

// Get Methods
// zero-padded full length vector filled with ROIs
std::vector<float> Signal() const;

const RegionsOfInterest_t& SignalROI() const;
size_t NSignal() const;
art::Ptr<raw::RawDigit> RawDigit() const;
geo::View_t View() const;
geo::SigType_t SignalType() const;
uint32_t Channel() const;
```

recob::Hit

- Lots of ideas from people about what to do with hits
 - Differences between requirements of LBNE and uBooNE
 - uBooNE assumes recob::Wire is present, so suggests dropping duplicated data
 - LBNE does not store recob::Wire objects
 - This will limit the scope of proposed changes

Current recob::Hit

```
public:

    // Get Methods
    double      StartTime()      const;
    double      EndTime()        const;
    double      PeakTime()       const;
    double      SigmaStartTime()  const;
    double      SigmaEndTime()    const;
    double      SigmaPeakTime()   const;
    int         Multiplicity()    const;
    uint32_t    Channel()         const;
    double      Charge(bool max=false) const;
    double      SigmaCharge(bool max=false) const;
    double      GoodnessOfFit()   const;

    geo::SigType_t    SignalType()      const;
    geo::View_t       View()            const;
    art::Ptr<recob::Wire> Wire()        const;
    art::Ptr<raw::RawDigit> RawDigit()  const;
    geo::WireID       WireID()         const;
```

recob::Hit

- The issues
 - HitSignal vector duplicated by recob::Wire
 - Charge() method
 - Takes an argument bool to toggle between “max” and summed ADC charge
 - The “max” is really the “peak” of the fit, not the maximum ADC value observed
 - PeakTime is the time (in TDC ticks) associated with that estimated peak
 - Sigma() method: assumes Gaussian shape
 - Multiplicity() is the number of hits found between StartTick() and EndTick()
 - No index available to say where a hit is in the train of hits found
 - Internal art::Ptr to associated recob::Wire and raw::RawDigit objects
 - Policy issues
 - Clarify that “time” means “TDC tick”
 - StartTick() and EndTick() represent the interval over which hit-finding was performed, and are not start and end points for the individual hit.
 - Can therefore remove SigmaStartTime() and SigmaEndTime()

recob::Hit

- Proposed changes

- Replace Charge() method with
 - PeakAmplitude(), which returns fitted peak ADC value
 - SummedADC(), which returns sum of ADC values apportioned appropriately between shared hits
 - IntegratedADC(), the integral of the fit, so the best estimate of collected charge
- Replace Sigma() method with FWHM()
 - More general, so covers the case of non-Gaussian hit shapes
 - Allows simple calculation of Gaussian sigma when needed.
- Replace StartTime() / EndTime() with StartTick() / EndTick() to clarify meaning
 - Remove SigmaStartTime() and SigmaEndTime()
- Add LocalIndex(), which returns position of hit among those found within the StartTick() to EndTick() region, starting from StartTick() side.
- Drop internal art::Ptr objects. Use external associations as needed.

recob::Hit

- Proposed changes (cont'd)
 - Leave HitSignal() as is
 - This is a large overhead for uBooNE, so may need a better solution

recob::Cluster

- Add methods used in shower versus track discrimination
 - NHits()
 - OpeningAngle(), a shape variable
 - TotalSummedADC()
 - AverageSummedADC()
 - RMSSummedADC()
 - TotalIntegrateADC()
 - NWire / NHit, a shower / track discriminant
 - Width(), a shape variable
- Remove $dQ/dW()$, which is unused

Current recob::Cluster

```
public:
  /// Accessors
  double          Charge()          const;
  geo::View_t     View()            const;
  double          dTdW()            const;
  double          dQdW()            const;
  double          SigmadTdW()       const;
  double          SigmadQdW()       const;
  std::vector<double> StartPos()    const;
  std::vector<double> EndPos()      const;
  std::vector<double> SigmaStartPos() const;
  std::vector<double> SigmaEndPos() const;
  int             ID()              const;
  const geo::PlaneID& Plane()       const; ///< returns the geometry plane of the cluster
  //@}

  /// Returns whether geometry plane is valid
  bool          hasPlane()          const;

  /// Moves the cluster to the specified plane
  Cluster& MoveToPlane(const geo::PlaneID& new_plane);

  /// Makes the plane of this cluster invalid
  Cluster& InvalidatePlane();

  Cluster      operator + (const Cluster&);
```

recob::EndPoint2D

- The issues
 - We need two distinct roles
 - A point in a plane indicating, e.g., the start / end of a cluster (a geometric object)
 - A 2D vertex (a reconstructed object)
- Proposed changes
 - Use a 2D point in places where the geometry object is needed
 - Introduce a 2D reconstructed vertex class for cases when vertex is needed
 - Move Strength() method here
 - Add Multiplicity() to indicate how many clusters / tracks are associated

Current recob::EndPoint2D

```
public:
  EndPoint2D(double driftTime,
             geo::WireID wireID,
             double strength,
             int id,
             geo::View_t view,
             double totalQ);

  double          Charge()    const;
  geo::View_t     View()      const;
  double          DriftTime() const;
  geo::WireID     WireID()    const;
  int             ID()        const;
  double          Strength()  const;
```


recob::Track

- The main issues

- A track is a collection of attributes of the clusters / collection of hits that form the track + a trajectory + results of a fit used to obtain the trajectory
 - Anything else is typically computed separately, so should be associated
 - Momentum estimate, energy estimate, PID, etc
- Bezier tracks:
 - Parameterization for a continuous trajectory stored as recob::Track trajectory pts
 - Such tracks cannot be interpreted like a “normal” recob::Track
 - The actual BezierTrack class inherits from Track, is created as a transient object from a recob::Track
- Meaning of trajectory points is not clear
 - Meaning, method of defining trajectory points are not well-defined
- Contains dQ/dx
 - Not used anywhere, and not needed as part of pattern recognition

Current recob::Track

```
public:
    void          Extent(std::vector<double> &xyzStart,
                        std::vector<double> &xyzEnd)          const;
    void          Direction(double *dcosStart,
                           double *dcosEnd)                  const;
    double        ProjectedLength(gco::View_t view)            const;
    double        PitchInView(gco::View_t view,
                              size_t trajectory_point=0)      const;
    int           ID()                                         const;

    // A trajectory point is the combination of a position vector
    // and its corresponding direction vector
    size_t        NumberTrajectoryPoints()                    const;
    size_t        NumberCovariance()                          const;
    size_t        NumberFitMomentum()                          const;
    size_t        NumberdQdx(gco::View_t view=gco::kUnknown) const;
    double        Length(size_t p=0)                           const;
    void          TrajectoryAtPoint(unsigned int p,
                                    TVector3      &pos,
                                    TVector3      &dir)          const;
    const double&  DQdxAtPoint(unsigned int p,
                                gco::View_t view=gco::kUnknown) const;
    const TVector3& DirectionAtPoint (unsigned int p)           const;
    const TVector3& LocationAtPoint  (unsigned int p)           const;
    const double&  MomentumAtPoint  (unsigned int p)           const;
    const TMatrixD& CovarianceAtPoint(unsigned int p)           const;

    const TVector3& Vertex()                                    const;
    const TVector3& End()                                       const;
    const TVector3& VertexDirection()                           const;
    const TVector3& EndDirection()                               const;
    const TMatrixD& VertexCovariance()                           const;
    const TMatrixD& EndCovariance()                               const;
    const double&  VertexMomentum()                             const;
    const double&  EndMomentum()                                 const;

    double        Theta()                                       const;
    double        Phi()                                         const;

    // Calculate rotation matrices between global (x,y,z) and local (u,v,w)
    // coordinate systems based on track direction (fDir).
    // The local w-axis points along the track direction.
    void GlobalToLocalRotationAtPoint(unsigned int p, TMatrixD& rot) const;
    void LocalToGlobalRotationAtPoint(unsigned int p, TMatrixD& rot) const;
```

recob::Track

- The proposed solution (one of many possible)
 - Introduce a trajectory class to represent continuous trajectory
 - Abstract interface + concrete data product classes for specific parameterizations
 - Classes that now use BezierTrack should use recob::Track + trajectory class
 - Introduce a momentum object
 - Contains vector of momentum vectors, covariances + other parameters needed to characterize quality of the momentum estimate
 - Typically only care about the momentum at the vertex
 - Do not require that N momentum estimates = N trajectory points
 - Remove fit momentum from the track
 - Currently not used anywhere
 - But, If needed for physics, create a momentum object
 - Remove dQ/dx
 - Not used, and is a calorimetry object anyway

recob::Track

- The proposed solution (cont'd)
 - Trajectory points
 - Much thought and discussion about whether to include these in the track or put them into an associated object
 - Include:
 - *Most people consider them to be an intrinsic property of the track*
 - *Easy to use if just in there*
 - Associate:
 - *Could be multiple ways to calculate them, particularly if standardizing on a definition*
 - Eventually decided to leave them in the track for now
 - Define a policy / algorithm for calculating the trajectory points
 - Wire plane intersections,
 - *If distance between points is > a configurable maximum, add mid-point*

Discussion