Fermilab **ENERGY** Office of Science



Introduction to Multi-Threading

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Overview

Who am I?

- What is multi-threading?
- Why use multi-threading
- Multi-threading difficulties
- Thread safety
- Things to avoid



Who am I?

I'm in charge of the CMS event processing framework art was derived from an earlier version of the CMS framework

I lead CMSes effort to switch to a multi-threaded framework
I designed the how the CMS framework uses threads
I lead the team that changed the framework
I implemented a large portion of the conversion
I provided instructions to the CMS developers on how to adapt their code

This talk is based on that 6 years of experience



What is Multi-threading?

A thread is the smallest unit of sequential processing

Each thread has its own call stack Have own function local variables Have own function callback stack

All threads in a process share the same memory address space If a thread changes a value in memory it affects other threads using the memory

Contrast: multiple processes do not share the same memory address space If a process changes a memory address it can NOT affect other processes



Why Use Multi-threading

Speed

Shared Resources



Speed

Using multiple threads can make processing one event faster There is always some point where threads are waiting for the last thread to complete

Multi-threading does not decrease the time to process ALL events Running multiple single-threaded jobs each processing events is usually faster Many single-threaded jobs are usually the most CPU efficient

Why bother with multi-threading?



Computing Hardware Trends

CPU frequencies no longer increase

Manufacturers are increasing number of CPU cores

Cost of memory decrease at a slower rate than increase core count Memory per Core is either flat or decreasing

Intel Xeon we can afford 2 GB/core

Intel Xeon Phi have 256 'cores' but only afford 96GB total If single threaded job takes 1.5 GB could only run 64 jobs on the machine Would take 4x as many computers to use single-threading compared to multi-threading



Shared Resources

Multi-threaded programs can share memory across many events E.g. Geometry, Conditions, Configuration CMS: 1.5GB can be shared and each event needs 0.2 to 0.5 GB

Multi-threading help Batch and Workflow management systems scale Do not have to have a batch slot per core Systems only grow as the number of machines, not number of cores

Multi-threading puts less pressure on computing sites Database connections are shared across cores File opens can be shared across cores



Multi-threading Difficulties

Race condition

Deadlock



Race Condition

A shared memory address where One thread is writing to the memory Another thread is reading or writing to the memory

There is no such thing as a 'benign' race condition



Race Condition Example

std::vector<double> values;

Thread 1
values.push_back(1.);
for(auto v:values) cout <<v;</pre>

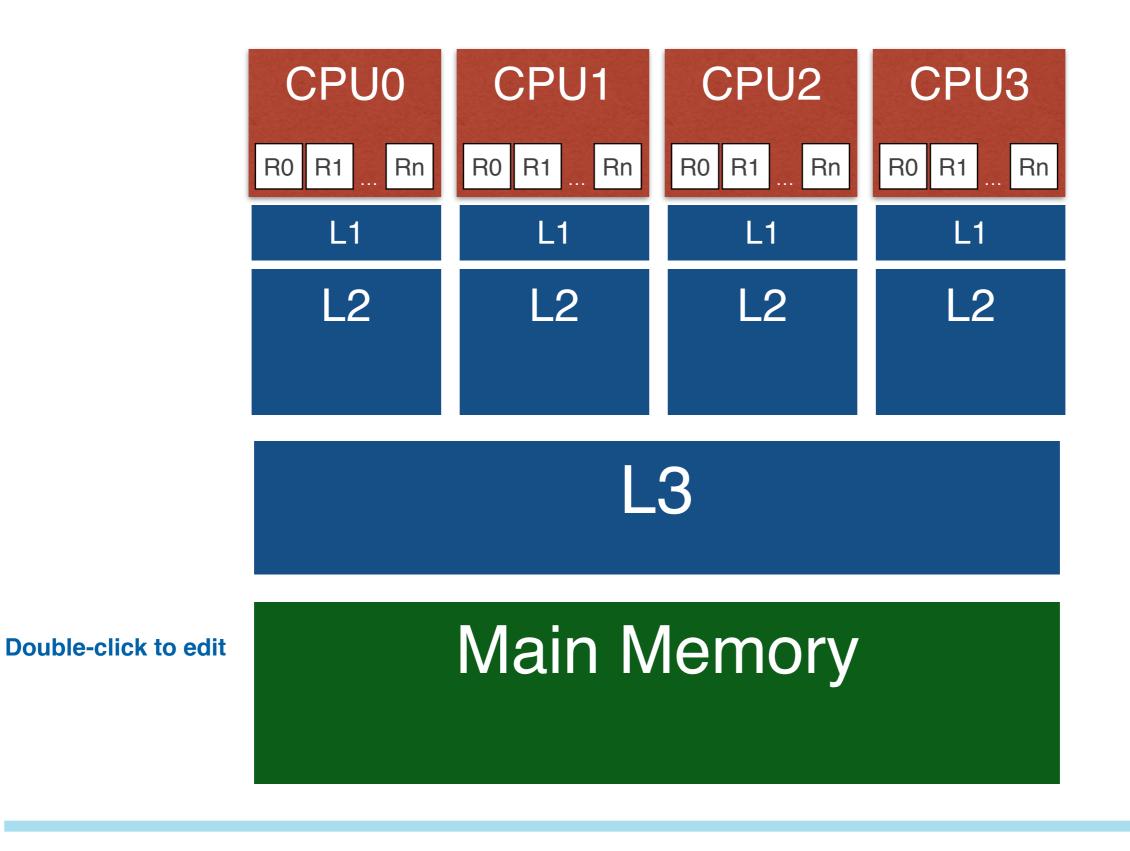
Thread 2
values.push_back(2.);
for(auto v:values) cout <<v;</pre>

Results could be 1.0 1.0 2.0 2.0 2.0 1.0 1.0 2.0 2.0 1.0 Segmentation violation Double-click to edit

Double-click to edit



CPU Memory Model





Race Condition Example

std::vector<bool> bools={false,false};

Thread 1
bools[0] = true;
cout <<" 0 "<<bools[0];</pre>

Thread 2
bools[1] = true;
cout <<" 1 "<<bools[1];</pre>

Results could be '0 true' and '1 true' '0 false' and '1 true' '0 true' and '1 false'



Deadlock

...

A deadlock is when two or more threads are waiting for other threads in the group to finish before continuing.

...

```
Thread 1
acquireGeometry();
acquireCalibration();
```

```
releaseCalibration();
releaseGeometry();
```

```
Thread 2
acquireCalibration();
acquireGeometry();
```

```
releaseGeometry();
releaseCalibration();
```



Thread Safety

The easiest way to be thread safe is to never have a thread write to memory that another thread will read.

For all other cases, C++ requires the use of synchronization mechanism

- E.g. mutex, semaphore, atomic
- These will not be covered in this talk
- art will automatically handle synchronization across modules
 - An object put into the Event by a module can safely be read by a module in another thread



Levels of Thread Safety for Objects

Thread-hostile

Thread friendly

const-thread safe

Thread safe



Thread Hostile

It is not safe for more than one thread at a time to call methods even for different class instances

```
E.g. with static
   class Foo {
   public:
     int convert(int iIn) const {
        static int s_oldIn{iIn};
        static int s_cache{ calculate(iIn) };
        if( iIn != s_oldIn) { s_cache = calculate(iIn);
                               s_oldIn = iIn; }
        return s_cache;
     }
```



};

Thread Friendly

Different class instances can be used by different threads safely Sharing the same instance across multiple threads is not safe

E.g. with mutable cache

```
class Foo {
  mutable int cache_;
  mutable int oldIn_;
public:
  int convert(int iIn) const {
   if( iIn != oldIn_) { cache_ = calculate(iIn);
                         oldIn_ = iIn; }
    return cache_;
  }
  ...
};
```

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const Thread-Safe

Multiple threads can call const methods on the same class instance Classes in the C++ standard library are const thread-safe

Classes put into the art::Event must be const thread-safe

```
class Foo {
   std::vector<int> values_;
public:
   Foo() : values_{calculateAllAllowedValues()} {}
   int convert(int iIn) const {
     return values_[iIn];
```

```
}
....
};
```



Thread Safe

Multiple threads can call non-const methods on the same class instance

Intel's Thread Building Block library has thread-safe containers tbb::concurrent_vector, tbb::concurrent_hash_map, etc. TBB is distributed with *art*

Results could be 1.0 2.0 2.0 1.0



Things to Avoid

non-const global memory

mutable data members in Event data products

art based Services with mutable state

Starting your own threads



Avoid: Non-const Global Memory

Global Memory: memory accessible from global C++ scope

Types of global memory File scope variables

- Function static variables
- Class static variables

No way to know if another thread is changing the values



Avoid: Mutable Data Members in Event Data Products

Event data products are shared across threads Multiple threads can be calling const functions on the same class instance

```
class Displacement {
  Cartesian3D vec_;
  mutable Polar3D polar_;
  mutable bool polarIsSet_;
public:
  Polar3D const& polar() const {
    if(not polarIsSet_) { polarIsSet_ = true;
                           polar_ = calculatePolar(); }
    return polar_;
  }
  ...
};
```



Avoid: Services with Mutable State

Services are shared across threads NOTE: storing event data in a Service is not considered best practice in *art*

```
class TrackFittingService {
   std::vector<Hit> hits_;
public:
   void setHits(std::vector<Hit> const& iHits) {
      hits_ = iHits; }
   Track fitToTrack() const;
```

};

•••



Avoid: Starting a Thread

Grid sites specify how many threads a process can use

art will start with the maximum allowed number of threads

Additional high CPU threads can lead to a site killing the process

art will provide facilities to allow you to do work concurrently within a module Calling TBB parallel algorithms within an art module is supported To start TBB add to configuration: services.num_threads: *<n>*



Conclusion

Multi-threading is coming to art

This will allow HEP processes to run on resource constrained systems

Need to prepare code now Remove use of 'global' variables Do not use mutable member data for Event data products Remove mutable state from Services



Advanced Resources

Useful book about C++ concurrency "C++ Concurrency in Action" by Anthony Williams

Useful talk about C++ threading memory model <u>https://channel9.msdn.com/Shows/Going+Deep/Cpp-and-Beyond-2012-Herb-Sutter-atomic-Weapons-1-of-2</u>

