

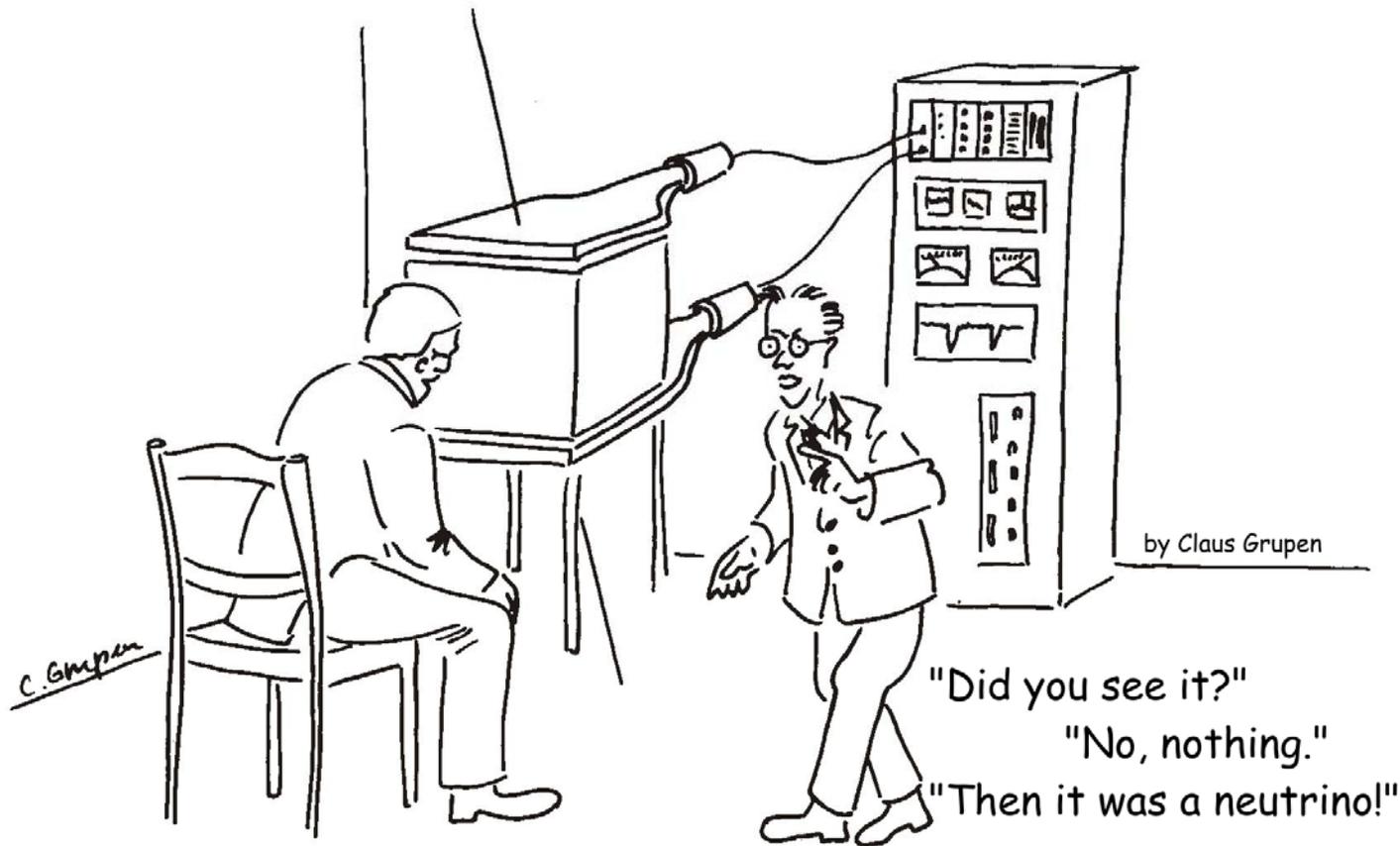
FIFTH CERN-FERMILAB HADRON COLLIDER PHYSICS SUMMER SCHOOL

August 16-27, 2010

PARTICLE IDENTIFICATION OLAV ULLALAND (CERN)

Mainly nuts and bolts
and how they could fit
together.

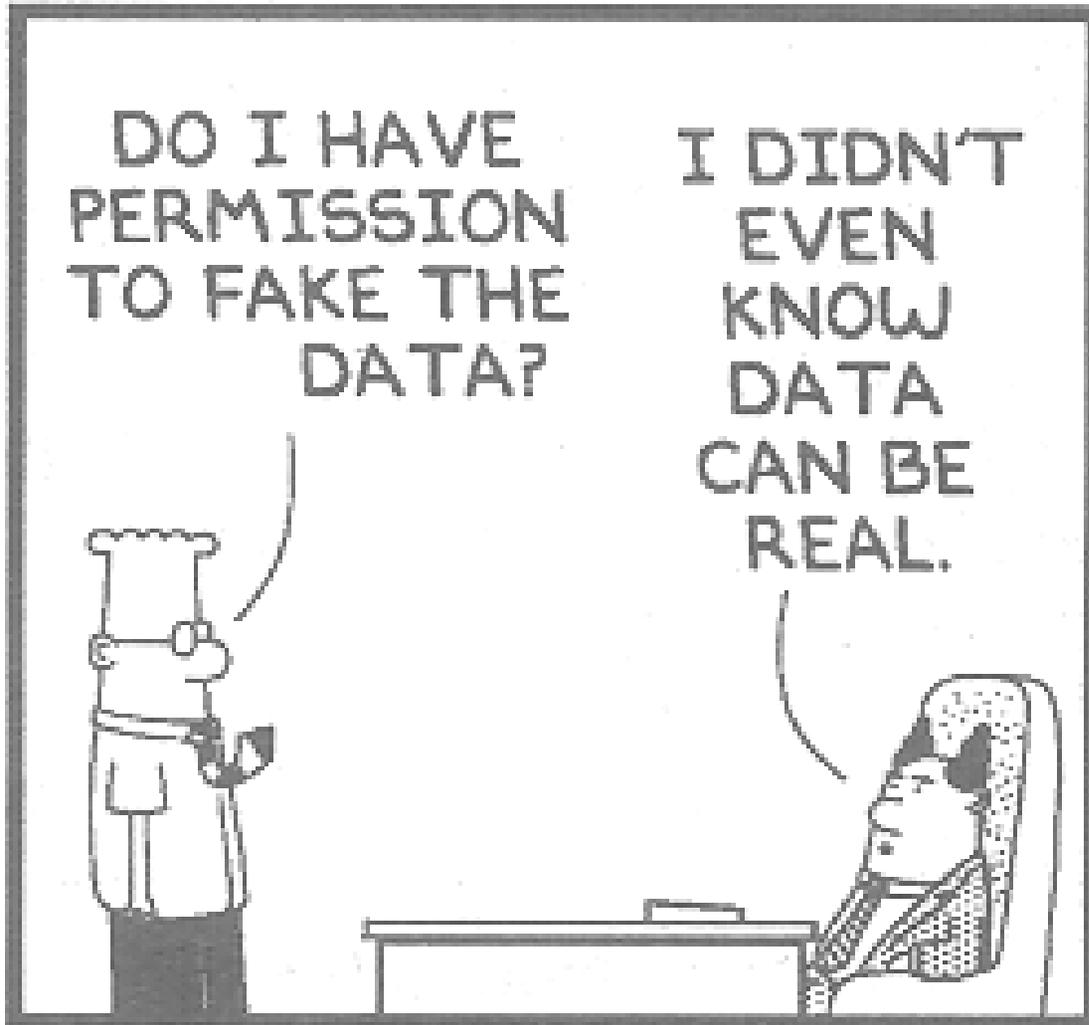




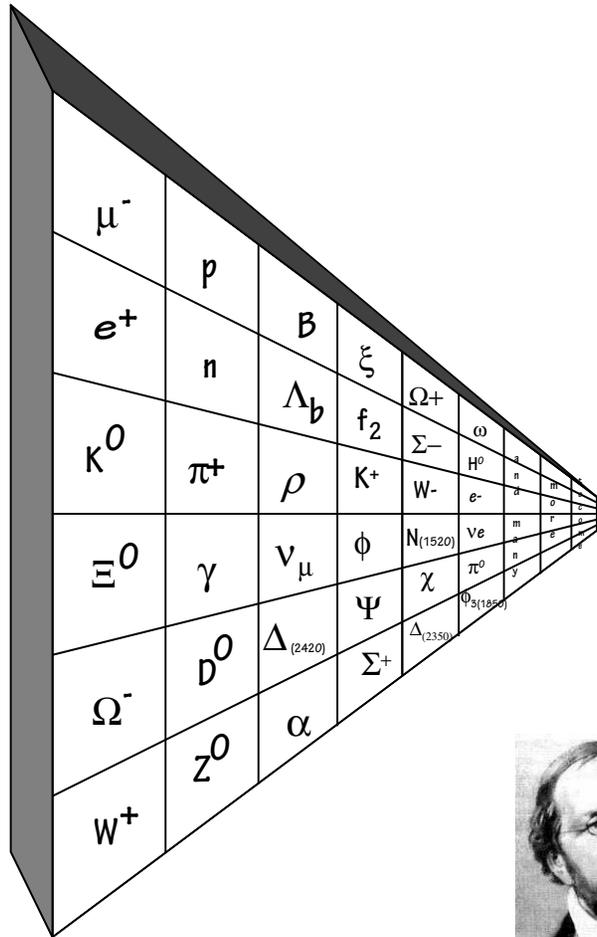
We will focus on charged particle identification as the detection and identification of neutral particles is covered in the **Calorimeter** lectures by **Jane Nachtman**. For particle **Tracking** see lecture of **Michael Hildreth** and **Statistics and Systematics** was given by **Roger Barlow**.

References and acknowledgements are normally given whenever appropriate.

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We will also have a look at where the real data is coming from and why.



We will not be concerned by all the charged particles which are around.
 We will just concentrate on those which have a lifetime long enough for us to observe them.
 That is:

$e, \mu, \pi, K, p.$

Main topics: _____

- Time-of-Flight
- Cherenkov
- Transition radiation
- and a little
 - Muon
 - dE/dX



The Pigeon Hole Principle.

If you have fewer pigeon holes than pigeons and you put every pigeon in a pigeon hole, then there must result at least one pigeon hole with more than one pigeon.

It is surprising how useful this can be as a proof strategy.

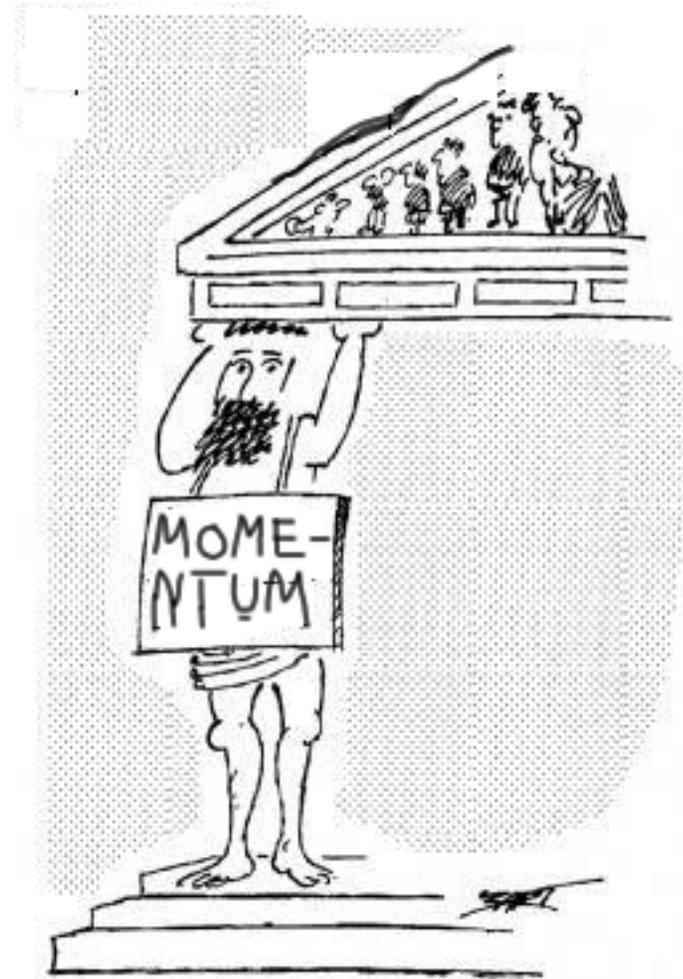
First stated in 1834 by **Peter Dirichlet** (1805-1859)

He got instant fame, not for this, but since his first publication concerned the famous Fermat's Last Theorem. The theorem claimed that for $n > 2$ there are no non-zero integers x, y, z such that $x^n + y^n = z^n$.

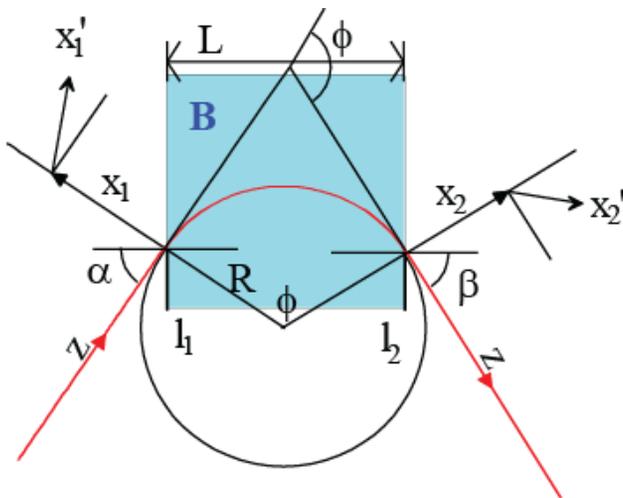
Particle Identification Detectors are normally not stand-alone detectors.

As a rule, they require that the momentum of the particle is measured by other means.

And - of course - by measuring the momentum, the track is defined.



search ID: bron177

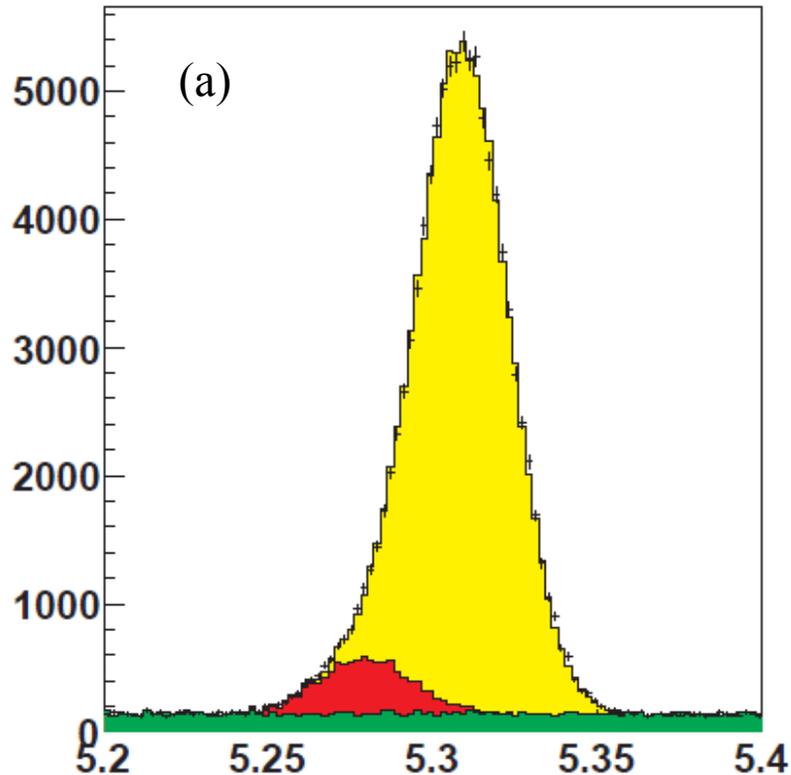


"Other means" is usually called a magnet and if:

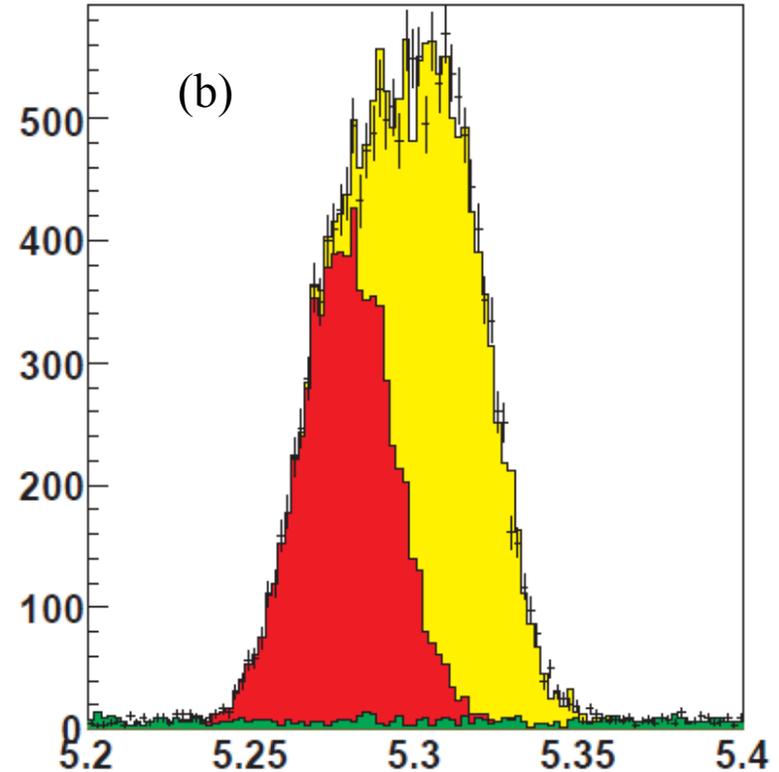
$$\alpha = \beta \text{ then } \phi \cong 0.03 \frac{BL \text{ kG m}}{p \text{ GeV}/c}$$

Why bother?

**No
Particle Identification**



**With
Particle Identification**



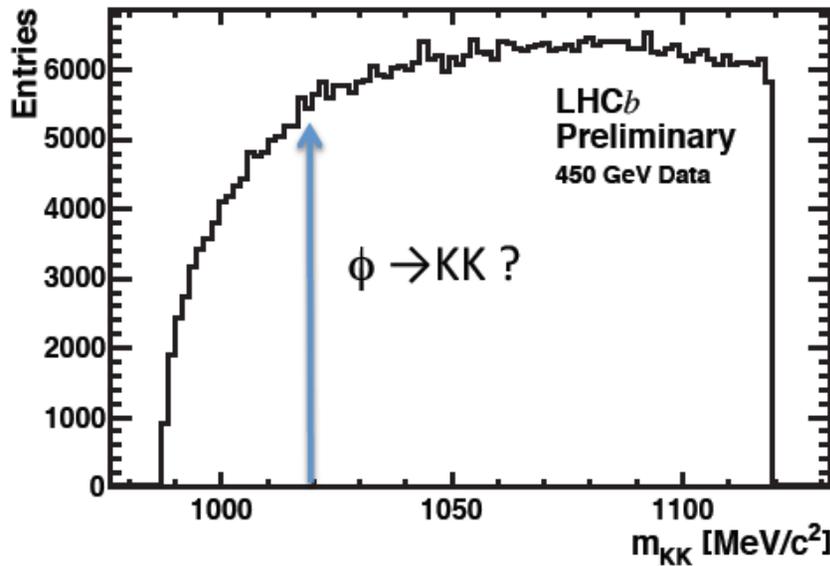
The invariant mass spectrum in units of GeV/c for selected $B^\pm \rightarrow D^0 K^\pm$ candidates, (a) before and (b) after information from the RICH detectors is introduced.

Genuine $B^\pm \rightarrow D^0 K^\pm$ candidates are shown in red while misidentified $B^\pm \rightarrow D^0 \pi^\pm$ candidates are shown in yellow. Combinatoric events are shown in green.

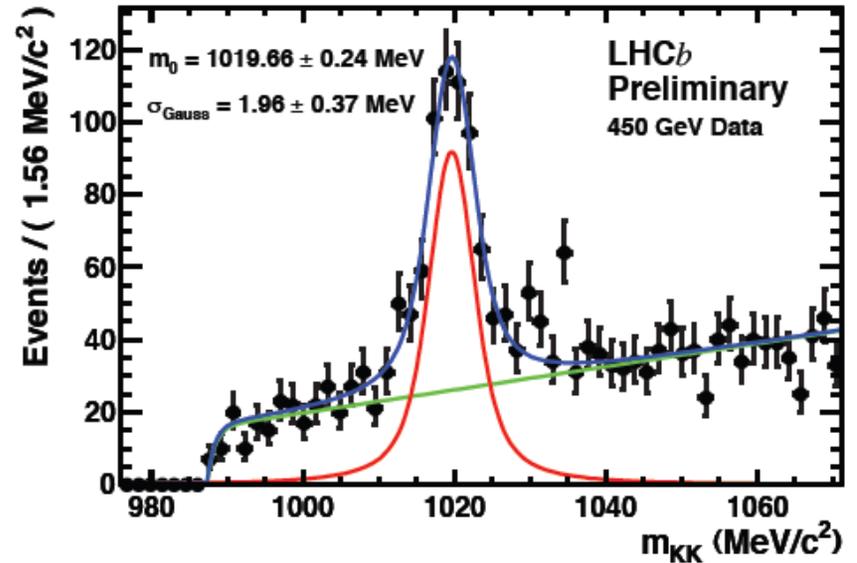
PID,

or the physics signal could be drowned in combinatory background.

No Particle Identification



With Particle Identification



But the right tool might
be required.

The tools.



Cherenkov radiation: Prompt signal, measure photon emission angle, calculate β .

Detector: photon detector 150 to 1000 nm.

Transition radiation: Prompt signal, measure photon energy, calculate γ .

Detector: (normally) X-ray >1 keV

Time-of-Flight: measure time and flight path, calculate β .

Detector: Any detector that can detect charged particles.

dE/dX: measure (small) energy deposit

Detector: Any detector that can detect charged particles.

Muon: measure whatever survives in the muon filter.

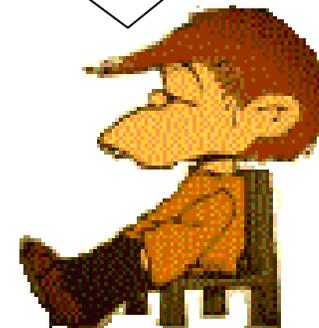
Detector: Any detector that can detect charged particles.



Scramjet Missile Sets Record for Mach 5 Flight Time

Particle
Identification
by
**Time
of
Flight**
measurement.

Awesome! maybe



With Time-of-Flight to Nobel Prize.

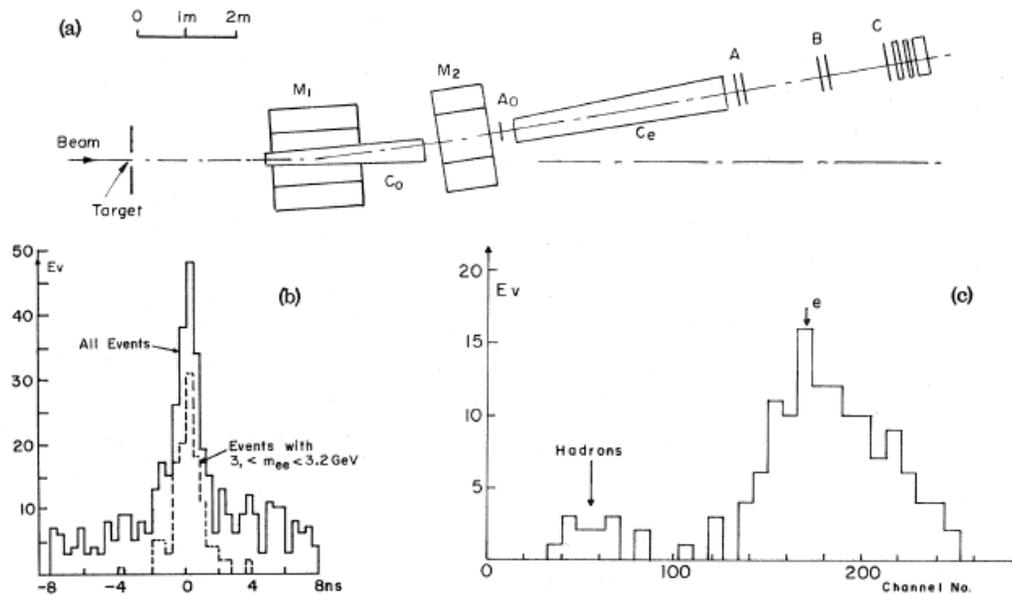


Fig. 1. (a) Simplified side view of one of the spectrometer arms. (b) Time-of-flight spectrum of e^+e^- pairs and of those events with $3.0 < m < 3.2 \text{ GeV}$. (c) Pulse-height spectrum of e^- (same for e^+) of the e^+e^- pair.

During the experiment, the time-of-flight of each of the hodoscopes and the Čerenkov counters, the pulse heights of the Čerenkov counters and of the lead-glass and shower counters, the single rates of all the counters together with the wire chamber signals, were recorded and continuously displayed on a storage/display scope.

Nobel Lecture, 11 December, 1976

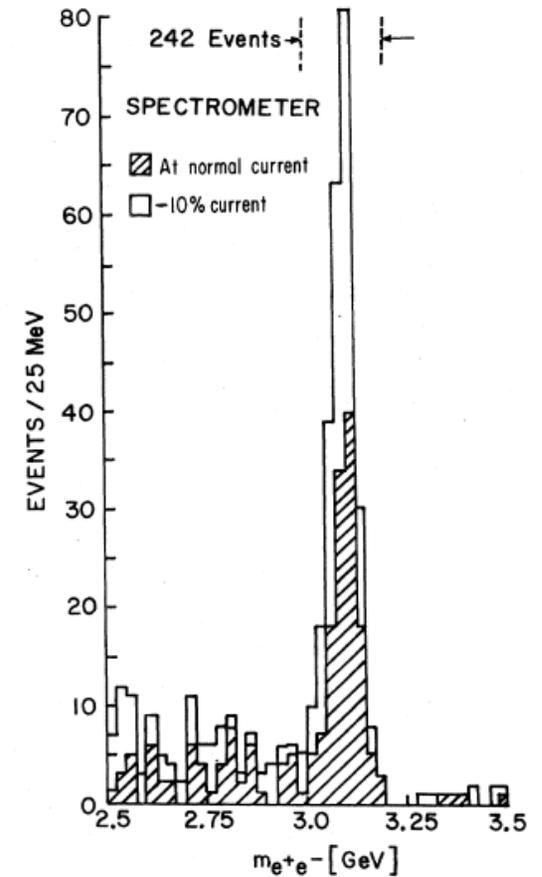
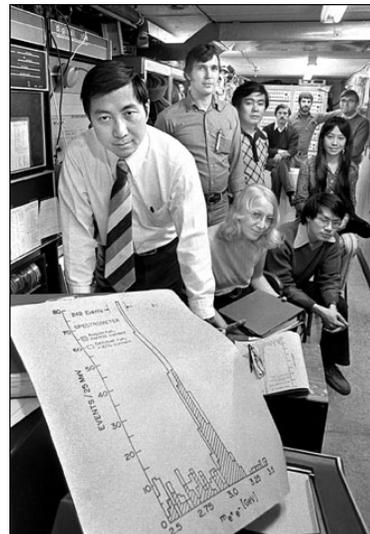
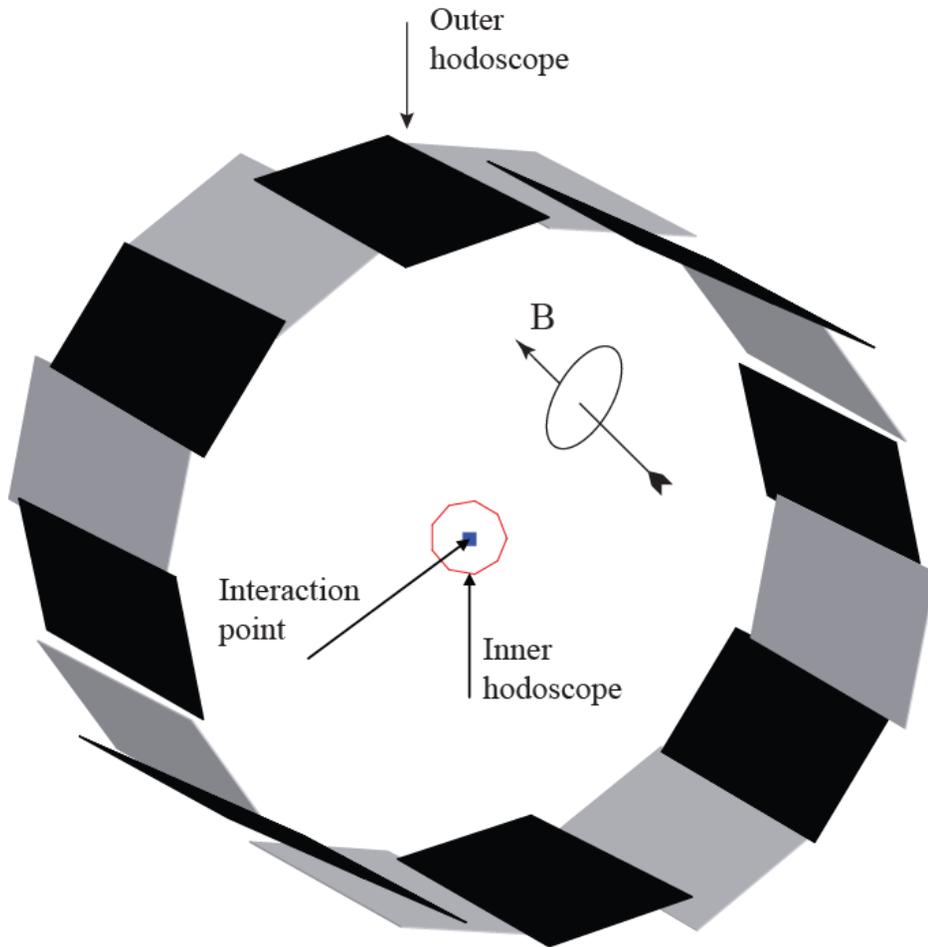


FIG. 2. Mass spectrum showing the existence of J . Results from two spectrometer settings are plotted showing that the peak is independent of spectrometer currents. The run at reduced current was taken two months later than the normal run.

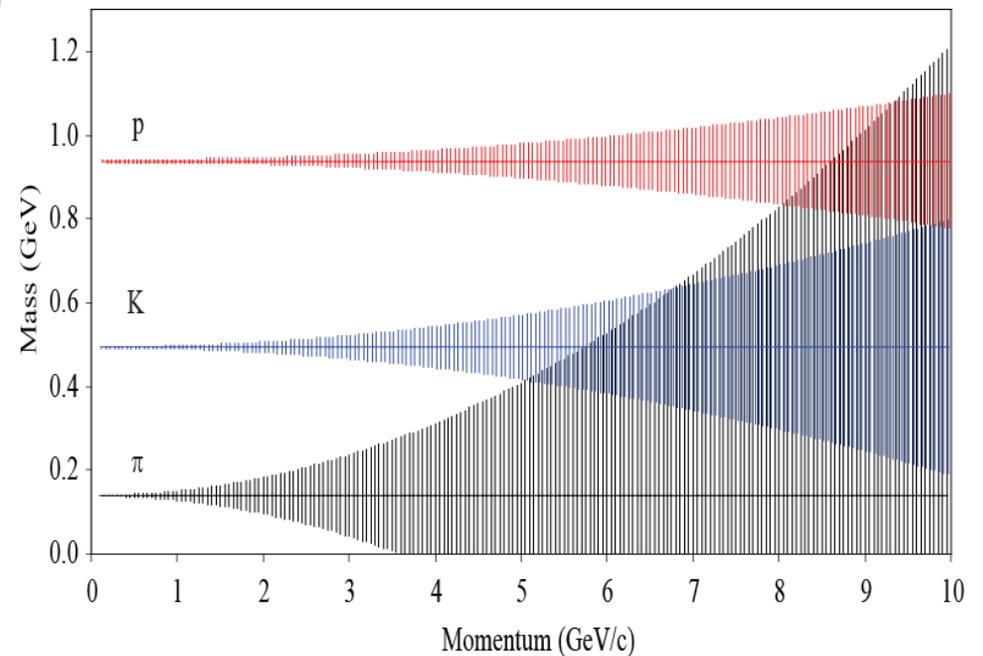
Time-of-Flight Measurements.



$$m_i^2 = \frac{P_i^2}{l^2} [ct_i - l][ct_i + l]$$

$$\left(\frac{\Delta m}{m}\right)^2 = \left(\frac{\Delta p}{p}\right)^2 + \gamma^4 \left[\left(\frac{\Delta t}{t}\right)^2 + \left(\frac{\Delta l}{l}\right)^2 \right]$$

$\Delta p/p = 4 \cdot 10^{-3}$
 $l = 10\text{m}, \Delta l/l = 10^{-4}$
 $\Delta t = 50\text{ps}$.
 The bars are $\pm 1\sigma$.



When considering how many σ 's are required, it can be helpful to remember that (almost) all secondary particles are π (and have a momentum around 2 GeV/c) and then we have to dig out something interesting with a K or a p. Or - not confusing the π -issue with whatever the K or p is doing in the data set.

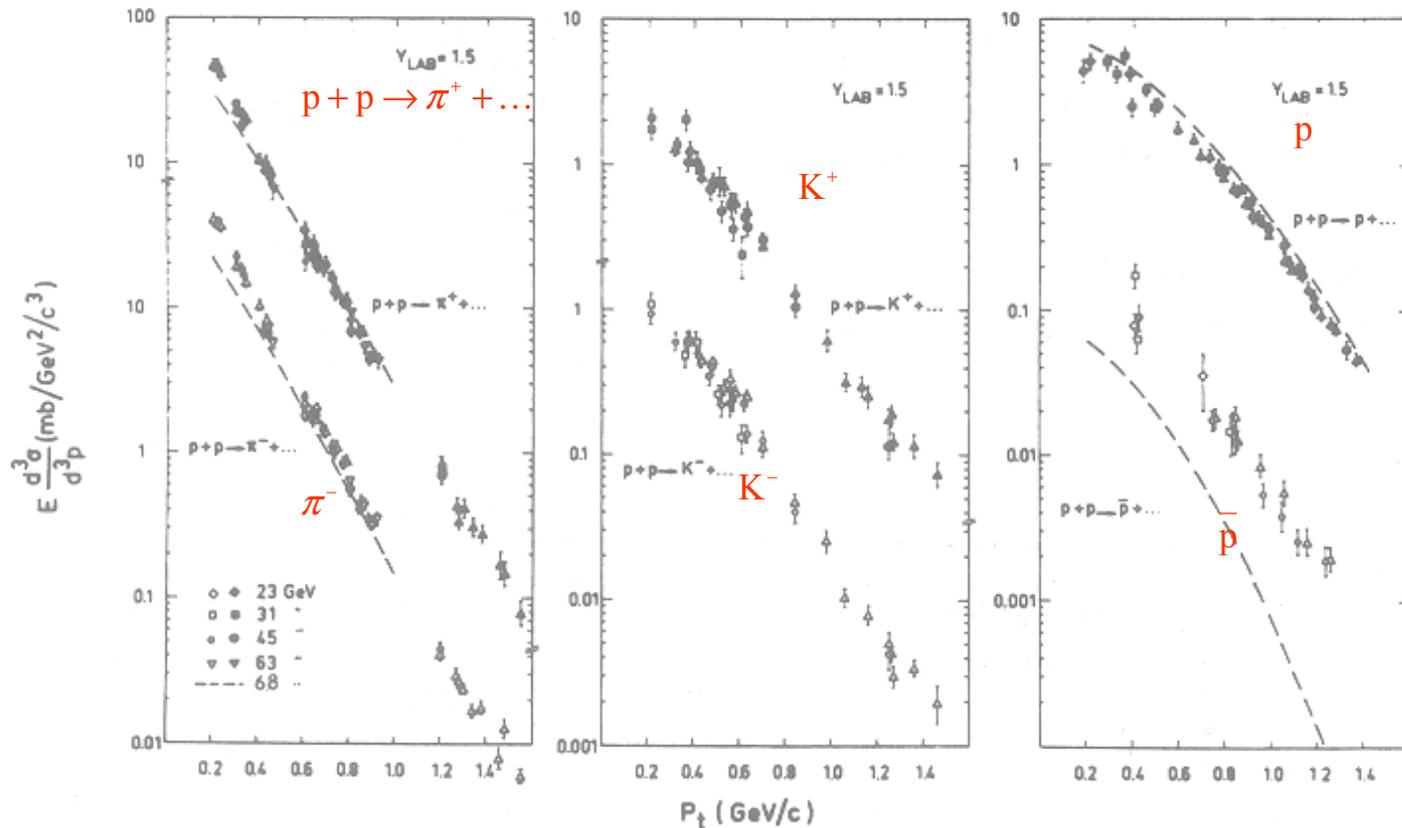


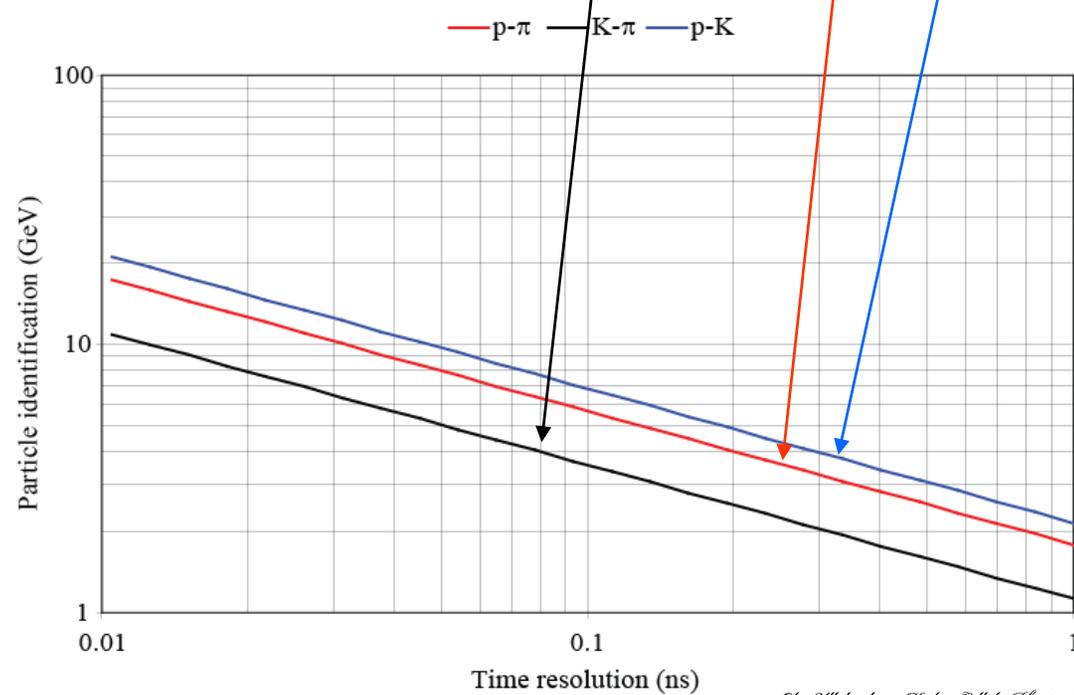
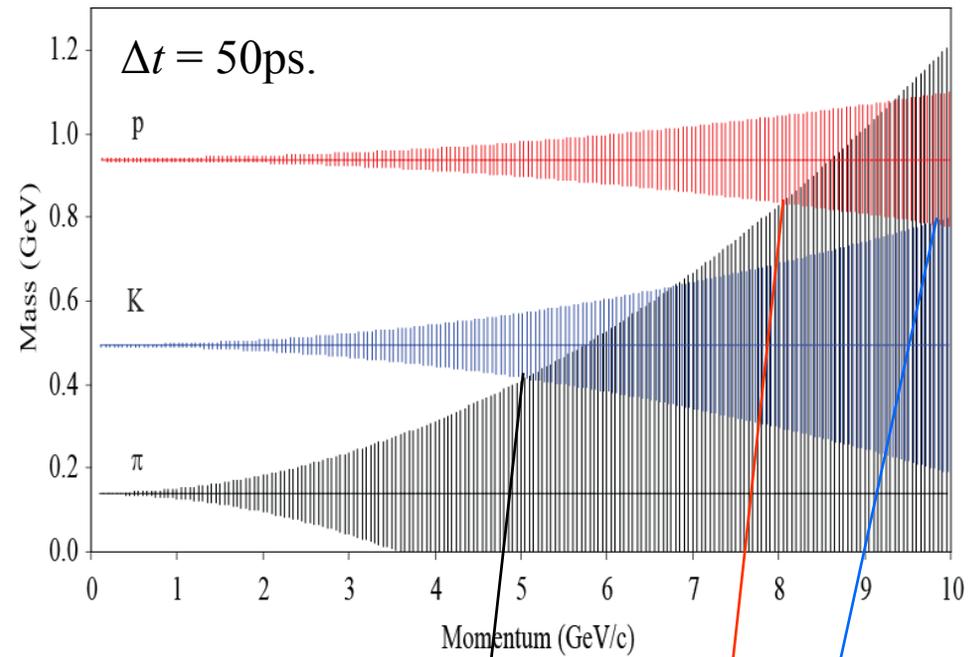
Fig. 8 - The invariant cross sections for π^+ , π^- , K^+ , K^- , p and \bar{p} production plotted versus P_t at $Y_{\text{LAB}} = 1.5$.

Assuming a spectrometer with the following characteristics:

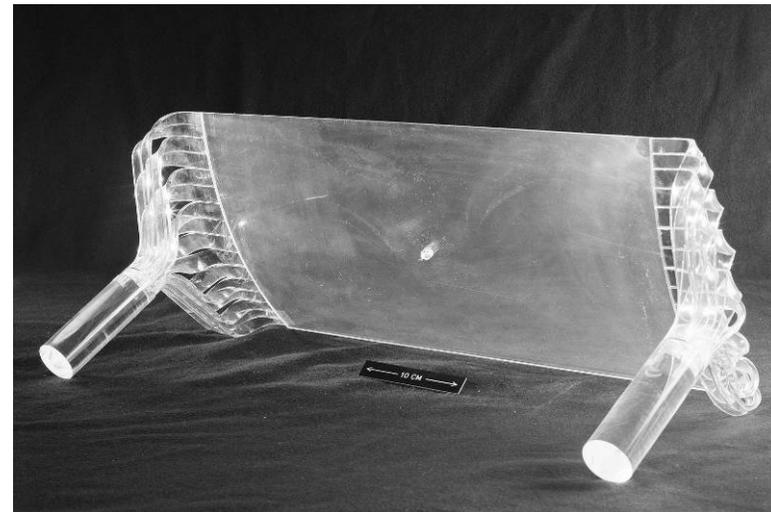
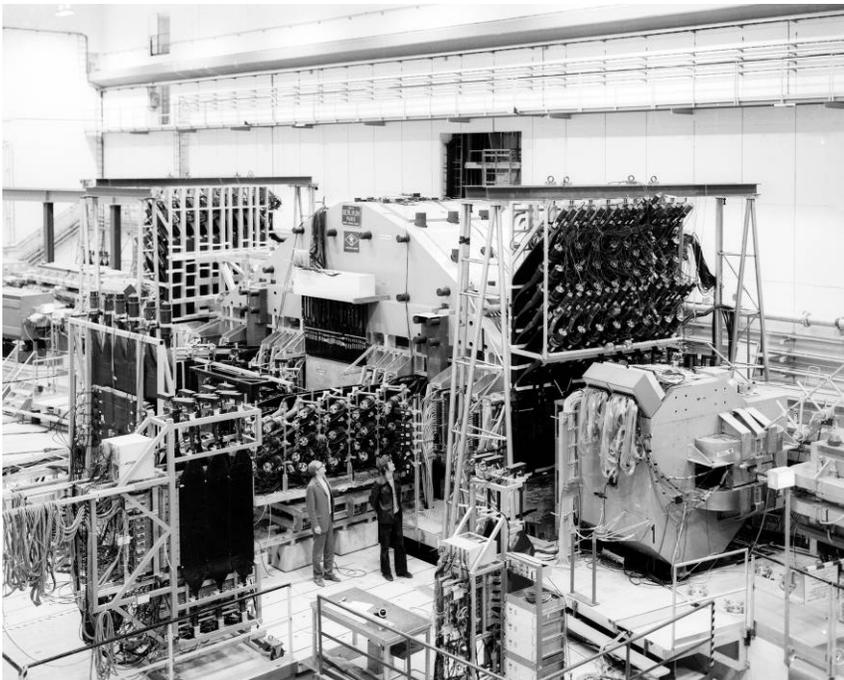
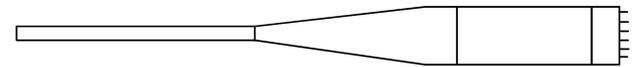
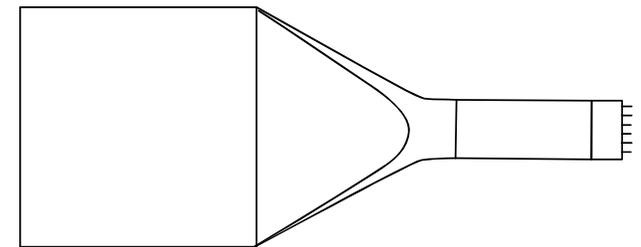
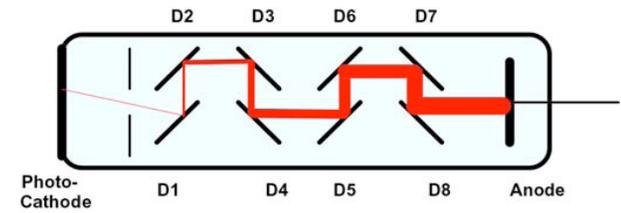
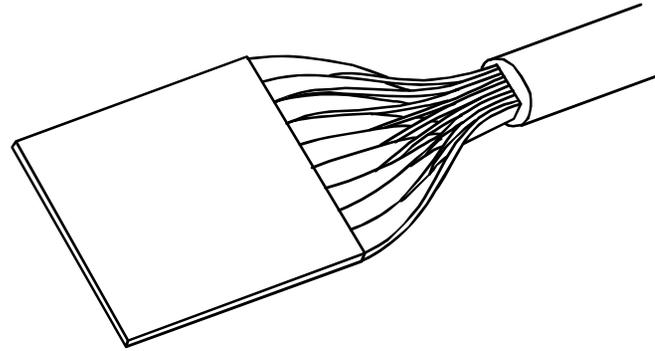
$$\Delta p/p = 4 \cdot 10^{-3}$$

$$l = 10\text{m}, \Delta l/l = 10^{-4}$$

What time resolution is required to do a particle identification up to X GeV/c?



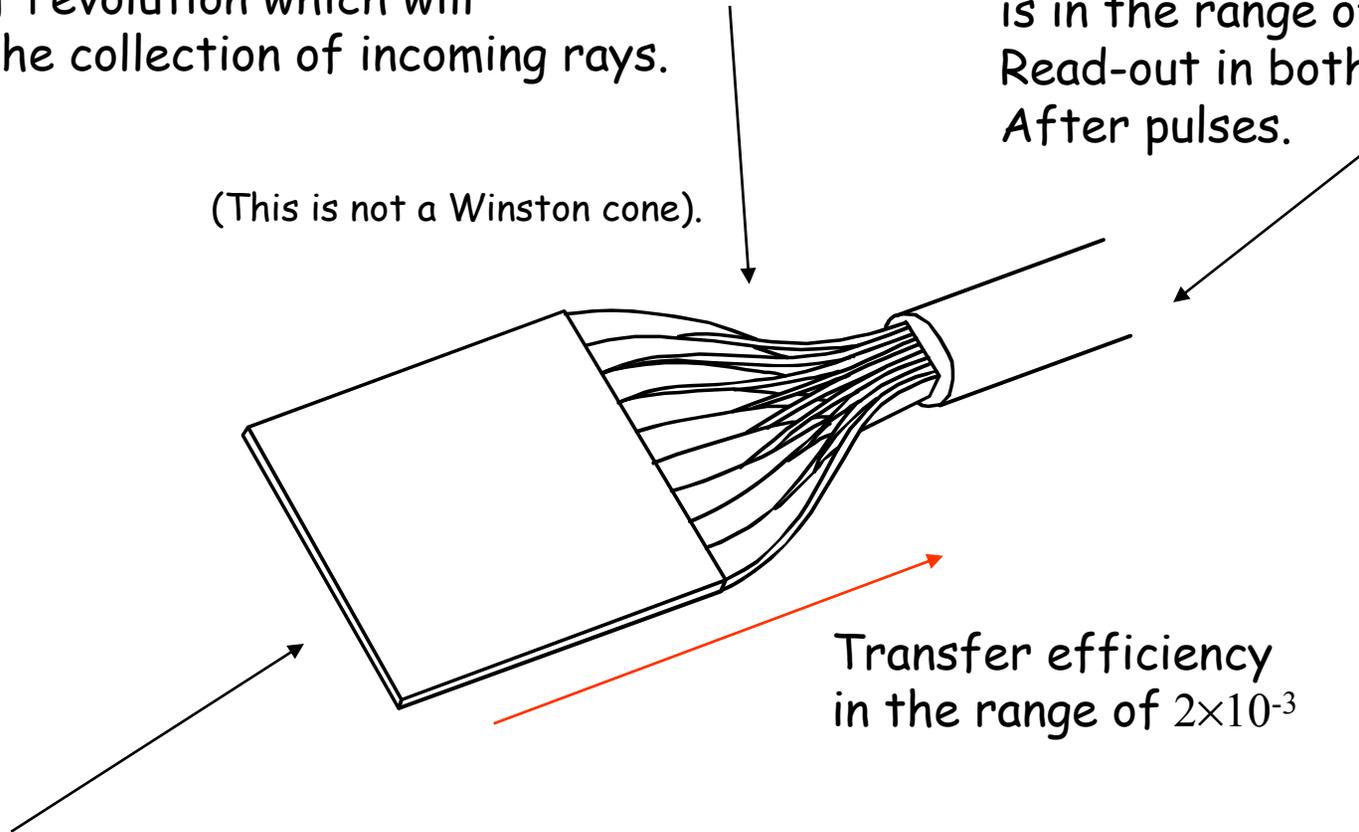
Have a closer look at the old workhorse.



Winston Cone is a nonimaging off-axis parabola of revolution which will maximise the collection of incoming rays.

Transient time spread is in the range of 1 ns. Read-out in both ends. After pulses.

(This is not a Winston cone).



Transfer efficiency in the range of 2×10^{-3}

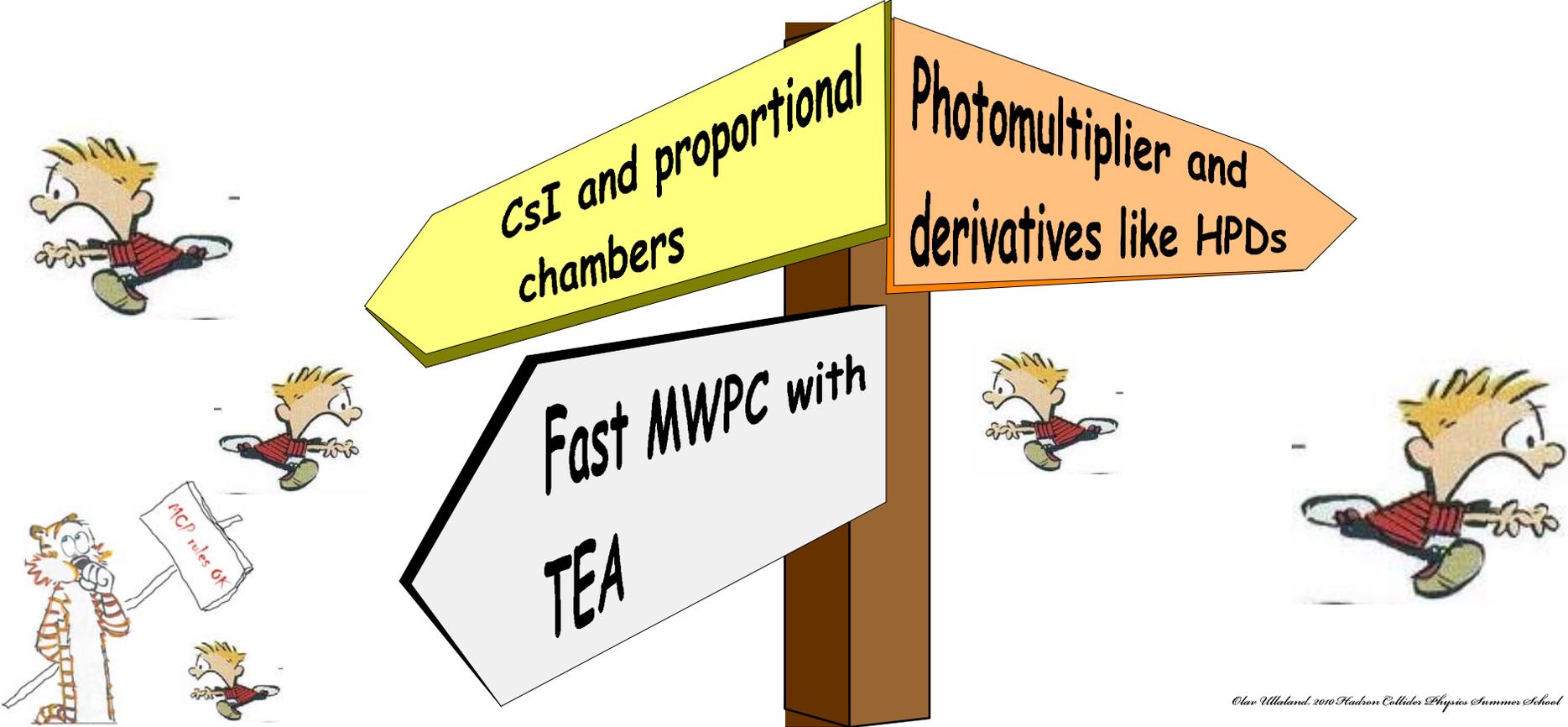
dE/dx_{\min} for a plastic scintillator is about $2 \text{ MeV cm}^2/\text{g}$, or about $2 \cdot 10^4$ photons/cm. This number of photons will be greatly reduced due to: the attenuation length of the material, the losses out from the material.

Time resolution of the order of 50 ps is reported (for reasonable large detectors).



the rule of thumb

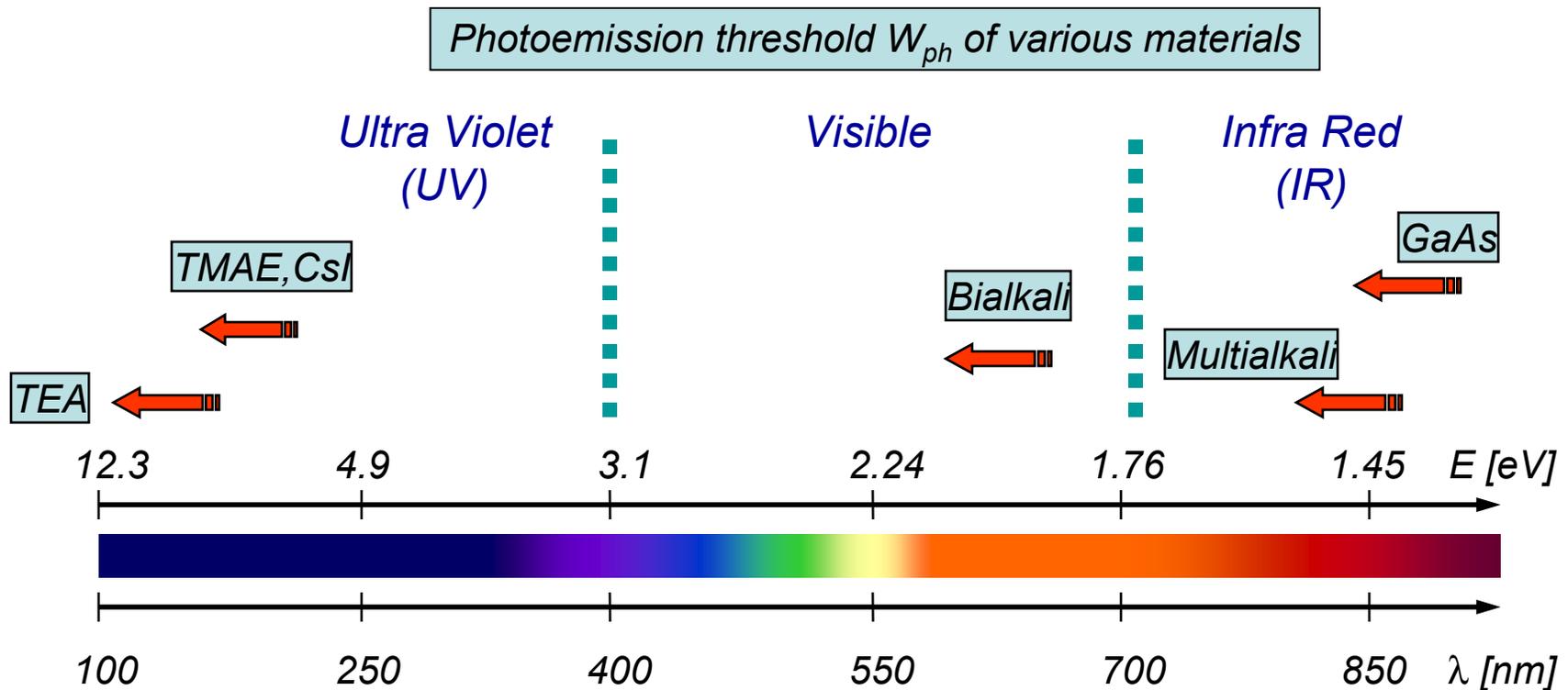
The choice of photon detector.



Photon detectors

Main types of photon detectors:

- gas-based
- vacuum-based
- solid-state
- hybrid



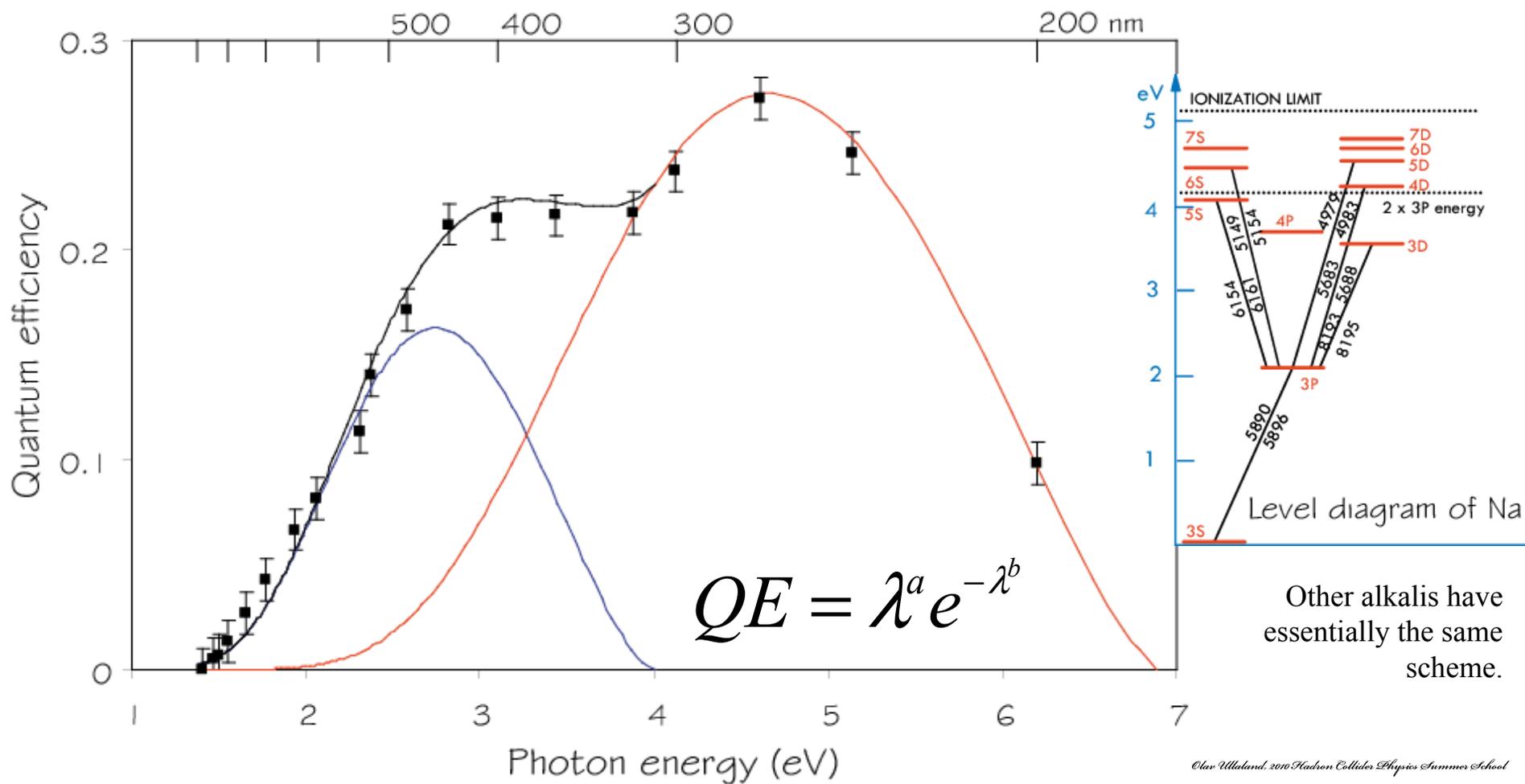
S-20 (Sb-Na₂-K-Cs) tri-alkaline photo cathode with quartz window.

Ionisation potential

Alkali		bi-alkali	
Cs	3.894 eV	Sb	8.64
K	4.341		
Na	5.139		

Photo-electric work function

Cs	2.1 eV
K	2.3
Na	2.8
Sb	4.8



How to know when the signal was there.
Time slewing and other evil things.

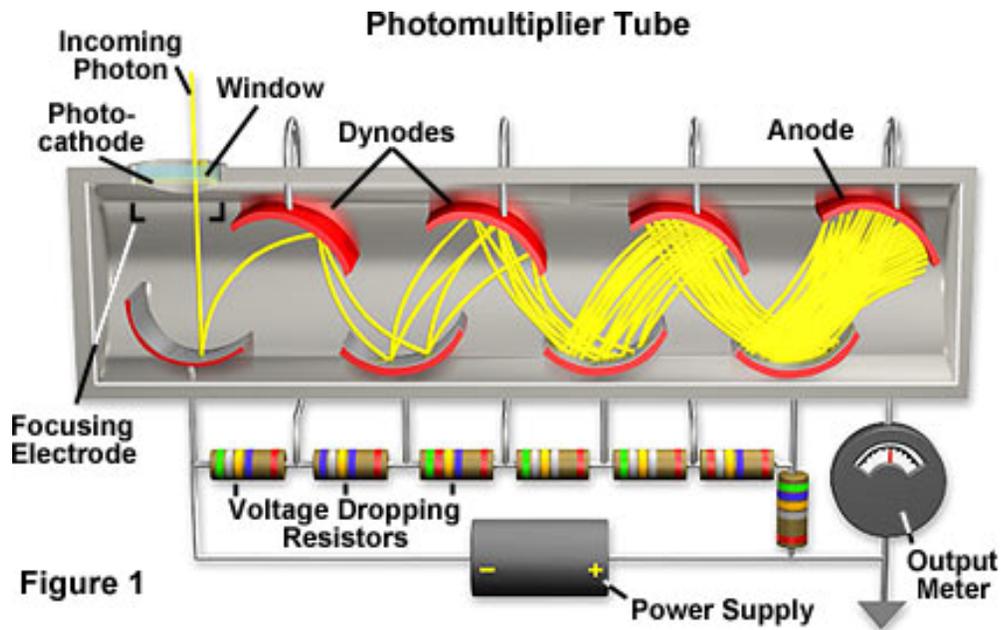
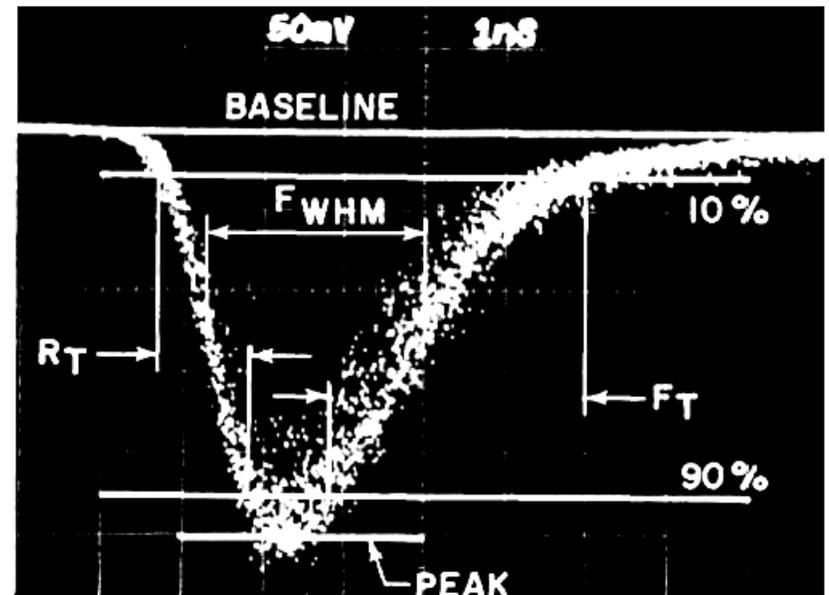
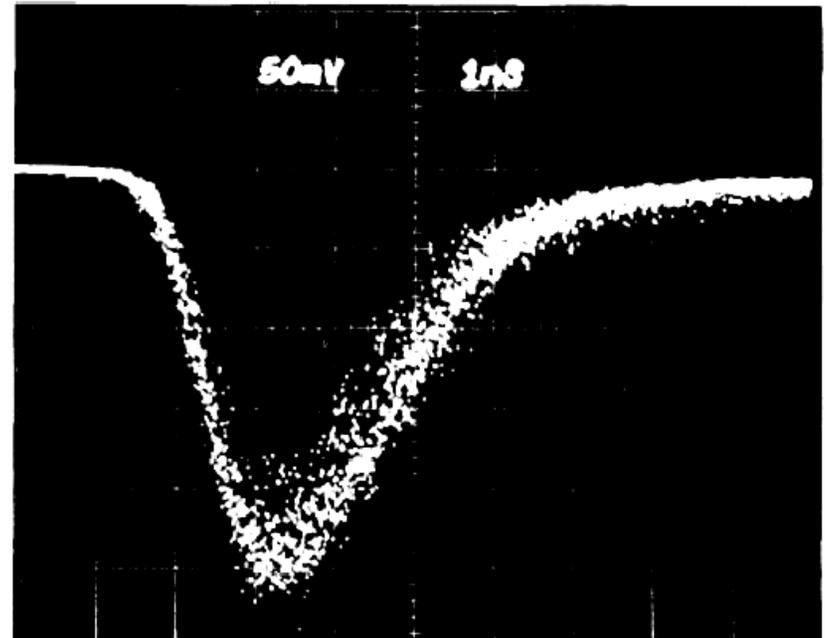
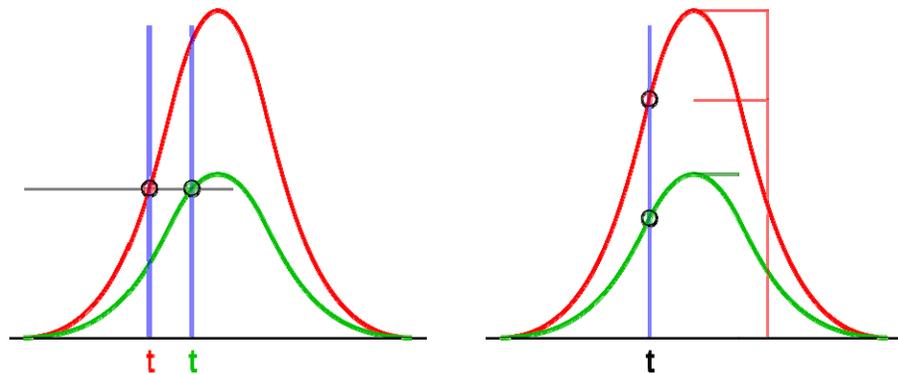


Figure 1



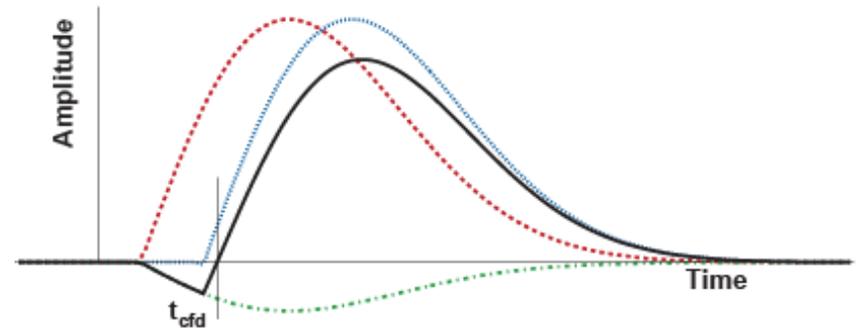
Thanks to Hamamatsu and Burle.



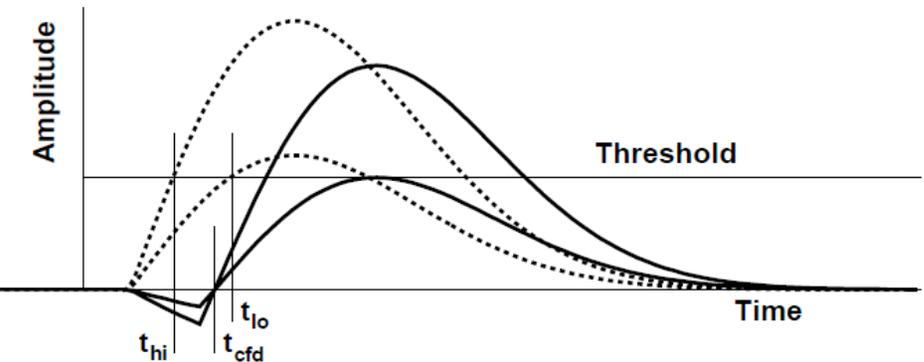
Comparison of threshold triggering (left) and constant fraction triggering (right)

http://en.wikipedia.org/wiki/Constant_fraction_discriminator

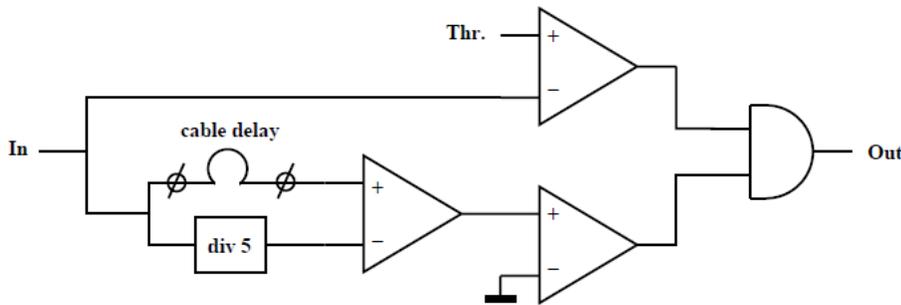
Constant Fraction Discriminator.



Operation of the cfd. The input pulse (**dashed curve**) is delayed (**dotted**) and added to an attenuated inverted pulse (**dash-dot**) yielding a bipolar pulse (**solid curve**). The output of the cfd fires when the bipolar pulse changes polarity which is indicated by time t_{cfd} .



The moment at which the threshold discriminator fires depends on the amplitude of the pulse. If the cable delay of the cfd is too short, the cfd fires too early (t_{cfd}). For small input pulses, the timing is determined by the threshold discriminator and not by the cfd part.



Basic functional diagram of a constant fraction discriminator.

Martin Gerardus van Beuzekom, Identifying fast hadrons with silicon detectors (2006) Dissertaties - Rijksuniversiteit Groningen

See also:

Wolfgang Becker, Advanced time-correlated single photon counting techniques, Springer Berlin Heidelberg (January 14, 2010)

Corrections for time slewing can also be done by measuring the apparent charge of the signal.

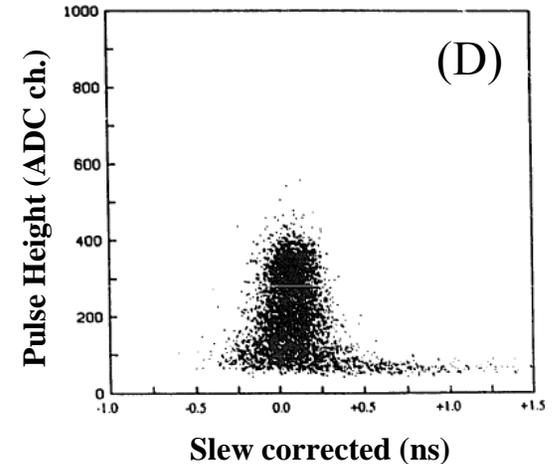
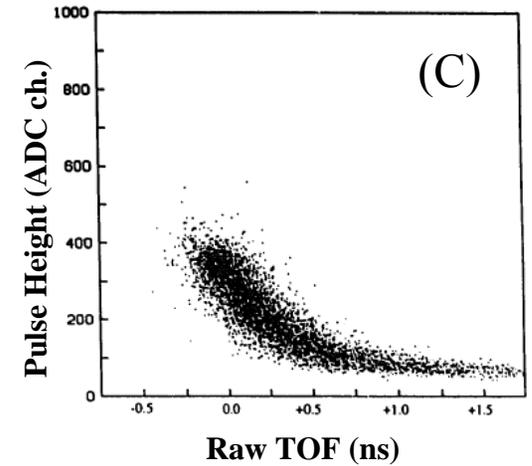
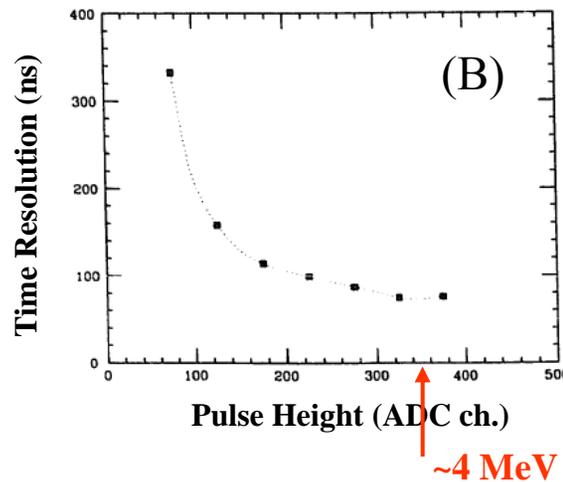
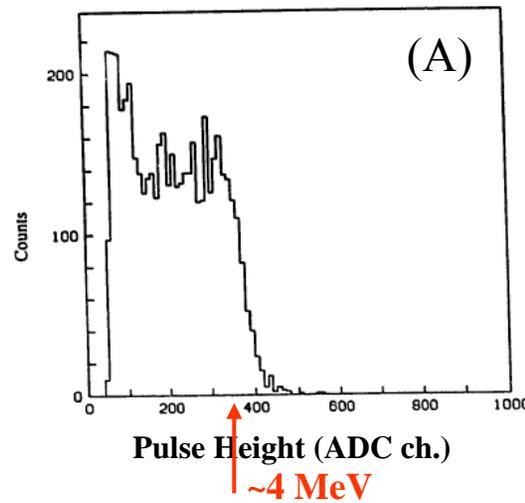
Slew-correction time, t_{cor} , is defined as:

$$t_{cor} = t + \frac{A_0}{\sqrt{ADC}}$$

where the constant A_0 is normally evaluated for each PMT and ADC is the signal pulse height.

→ σ : 55 ps

In a similar approach, Time-over-Threshold (ToT), can be used for time slewing correction.



- (A) Pulse height distribution of one PM.
- (B) Rms time resolution as a function of pulse height . ADC channel 350 corresponds to an energy deposit of about 4 MeV.
- (C) Scatter plot of TOF(T-S1) and pulse height before slew correction.
- (D) Scatter plot of TOF(T-S1) and pulse height after slew correction.

T. Kobayashi and T. Sugitate, Test of Prototypes for a Highly Segmented TOF Hodoscope, Nucl. Instrum. Methods Phys. Res., A: 287 (1990) 389-396



The **clock** issue.

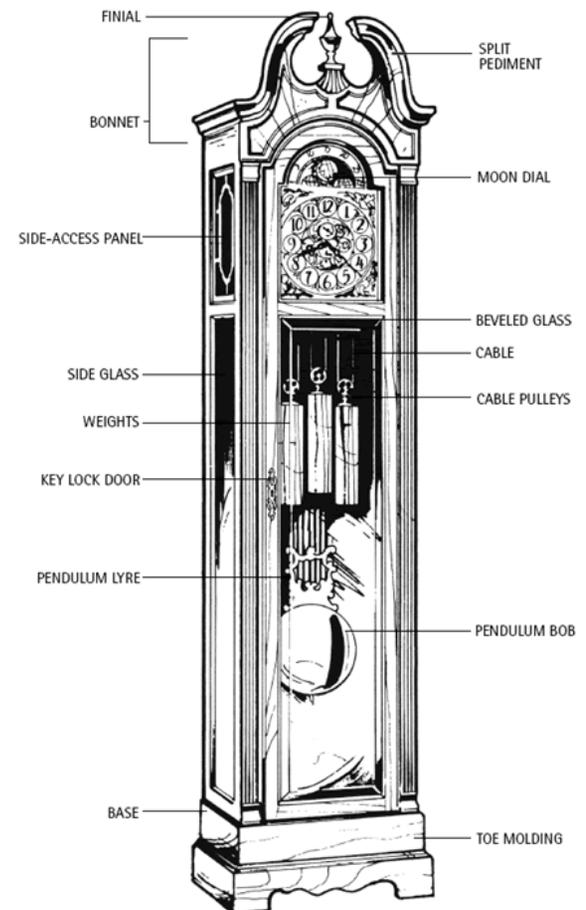
It is challenging to issue a high frequency clock to a large distributed system without falling into traps of slewing, power requirements, length of strips across the cell

We will use the proposed NA62 experiment at CERN as an example.

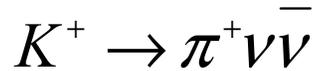
For more information see:

<http://na62.web.cern.ch/NA62/>

http://na62.web.cern.ch/NA62/Documents/Chapter_3-3_GTK_V1.4.3.pdf

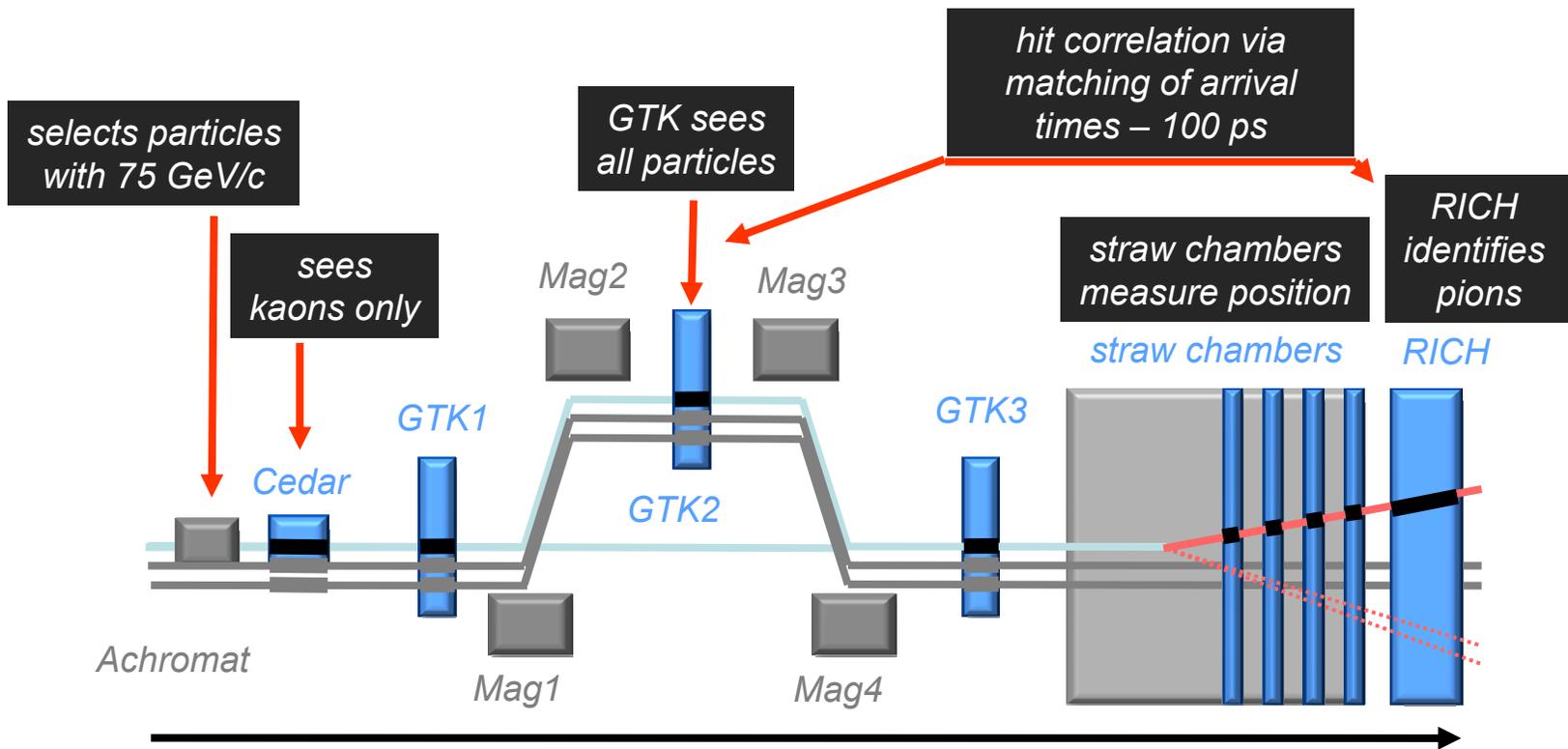


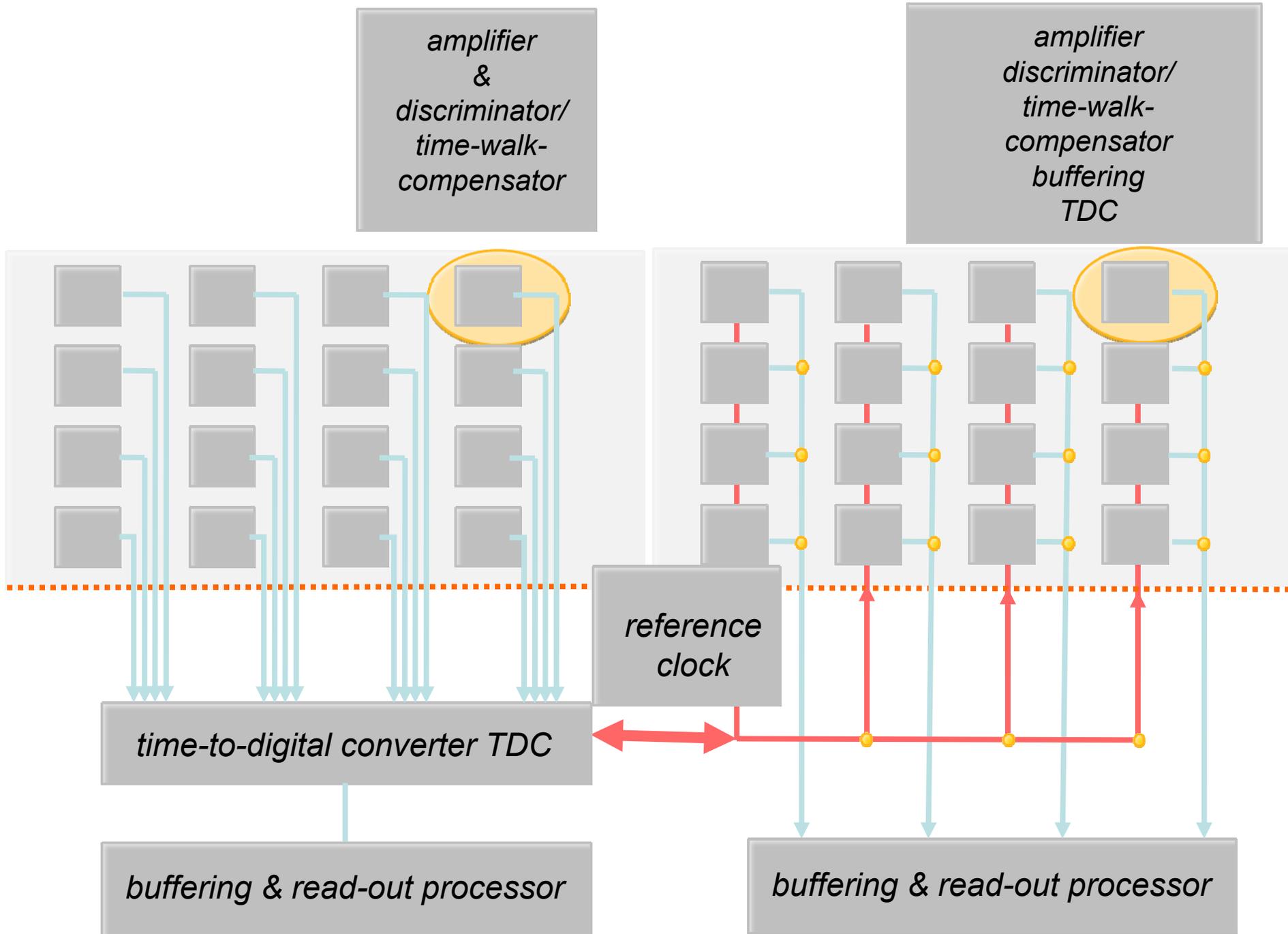
The aim of NA62:



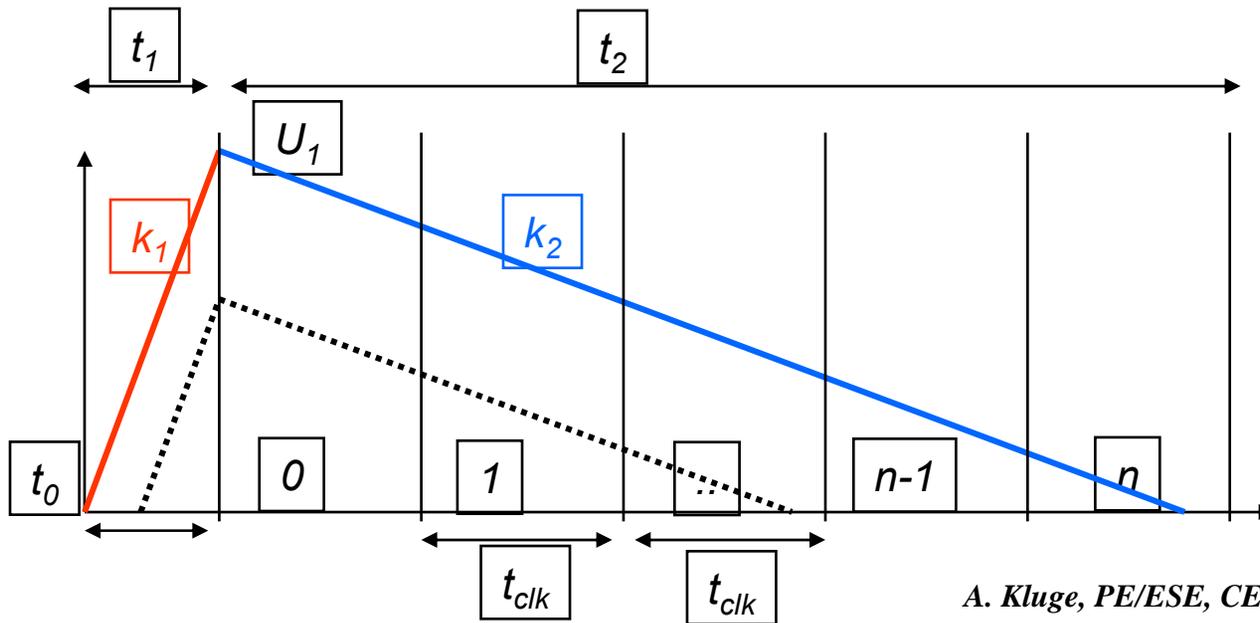
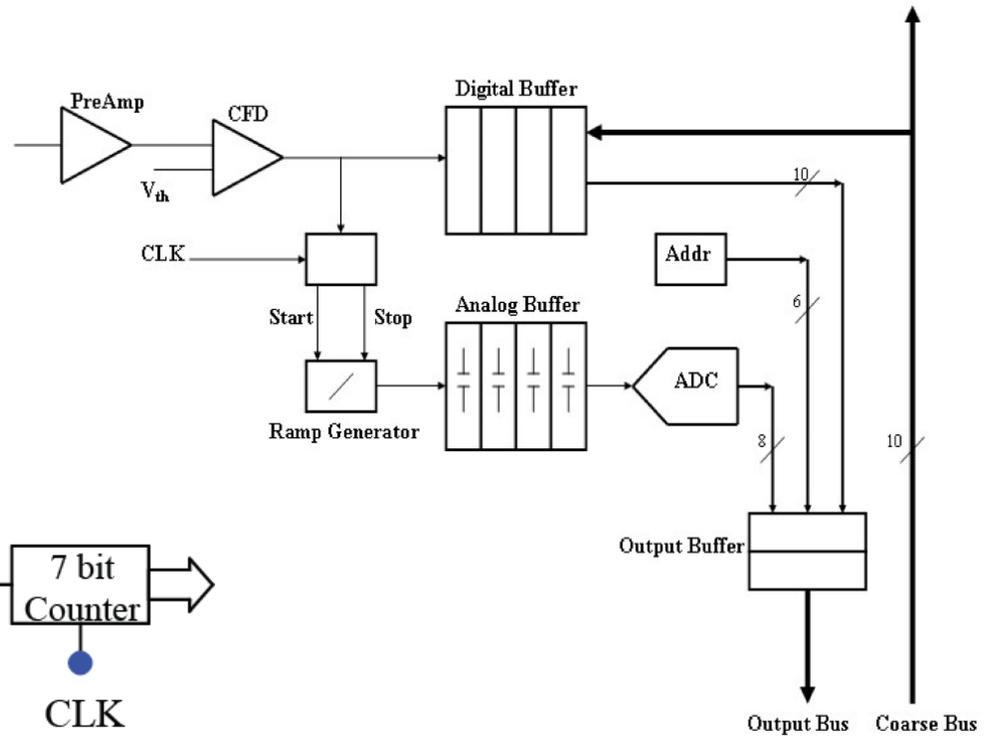
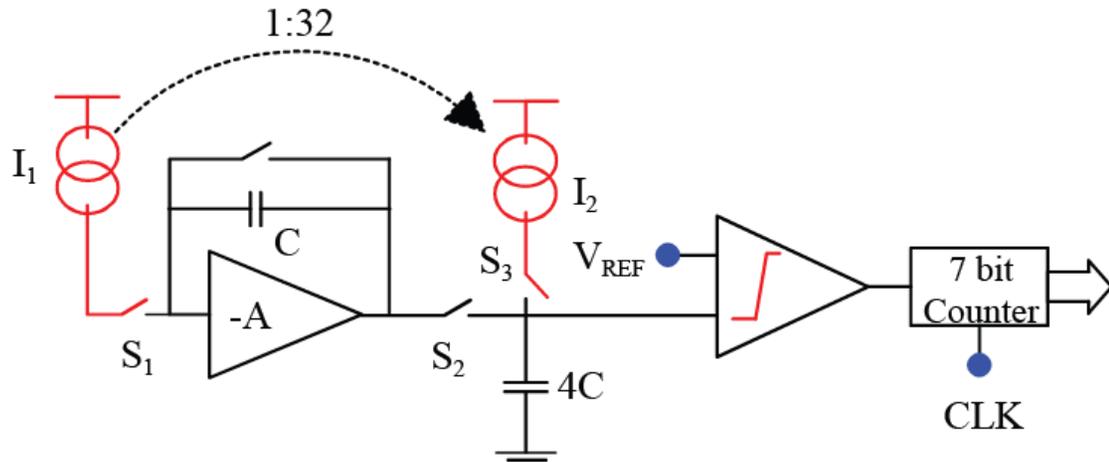
to extract a 10%
measurement of
the CKM parameter $|V_{td}|$.

beam: hadrons, only 6% kaons	0.06
only 20% of charged kaon decay in the vacuum tank	0.20
out of which only 10^{-11} decays are of interest	10^{-11}
decay into one pion, one neutrino and one anti-neutrino	
total probability	1.2×10^{-13}





Wilkinson Time to Digital Converter (dual slope)

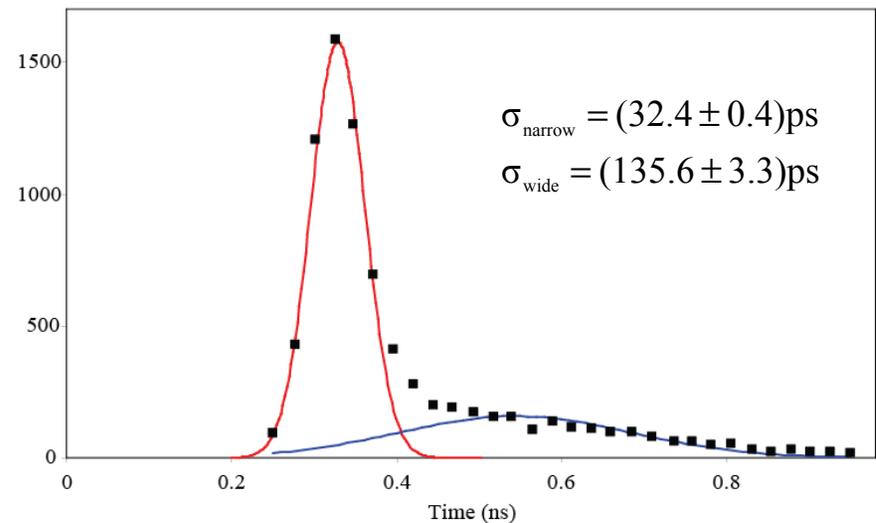
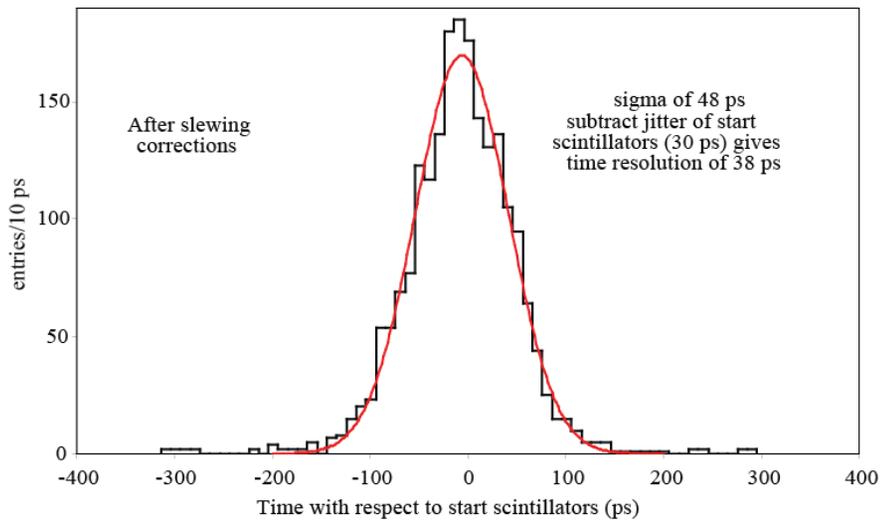
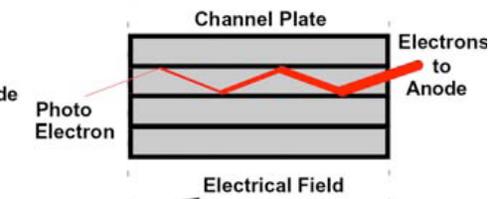
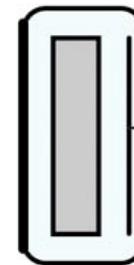
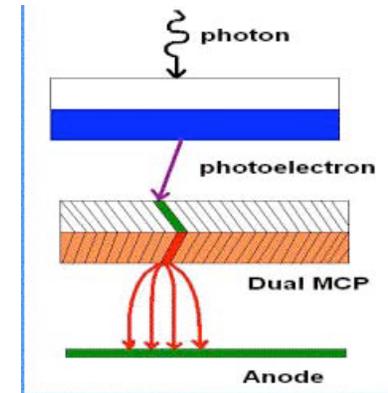
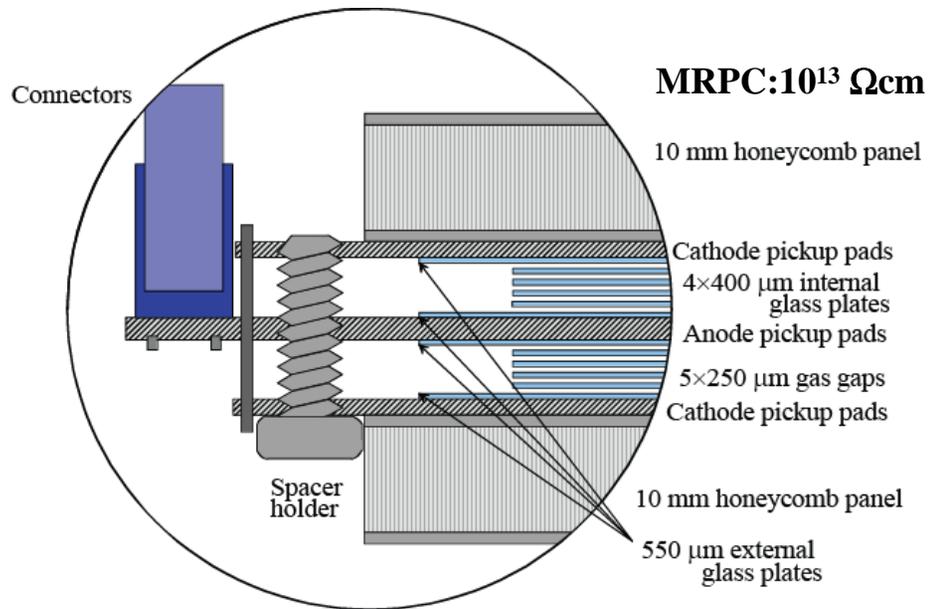


and then:

$$t_0 = n \cdot t_{clk} \cdot \frac{k_2}{k_1}$$

Related solutions with
Delay Locked Loop
and
Phase Locked Loop

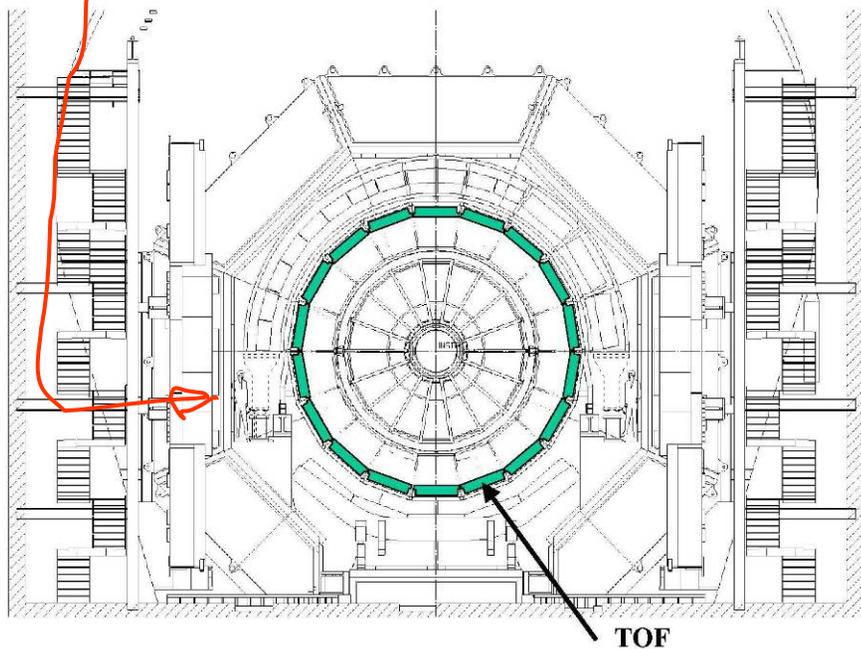
Two very different approaches to an especially good time resolution.



One thing is to have a signal, another thing is to know where the signal is.
Some things to look (out) for.

Will follow B. Zagreev at ACAT2002, 24 June 2002 <http://acat02.sinp.msu.ru/>

ALICE Time-of-Flight detector
R=3.7 m S=100 m² N=160000

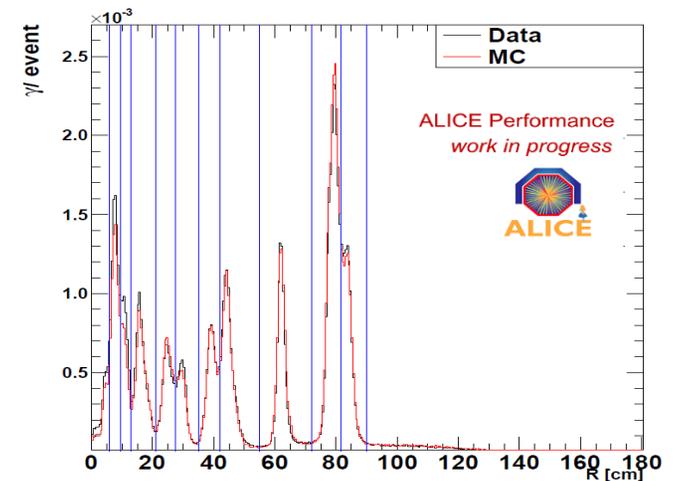


- High multiplicity $dN/dY \approx 8000$ primaries (12000 particles in TOF angular acceptance)
45(35)% of them reach TOF, but they produce a lot of secondaries

- High background
total number of fired pads ~ 25000
occupancy = $25000/160000 = 16\%$
but only 25% of them are fired by particles having track measured by TPC

- Big gap between tracking detector (TPC) and TOF
big track deviation due to multiple scattering

- Tracking (Kalman filtering)
- Matching
- Time measurements
- Particle identification



Combinatorial algorithm for t_0 calculation.

1. Consider a very small subset (n) of primary
 Let $l_1 \dots l_n, p_1 \dots p_n, t_1 \dots t_n$ - be length, momentum
 and time of flight of corresponding tracks.
 Now we can calculate the velocity (v_i) of
 particle i by assuming that the particle is π, K or p .

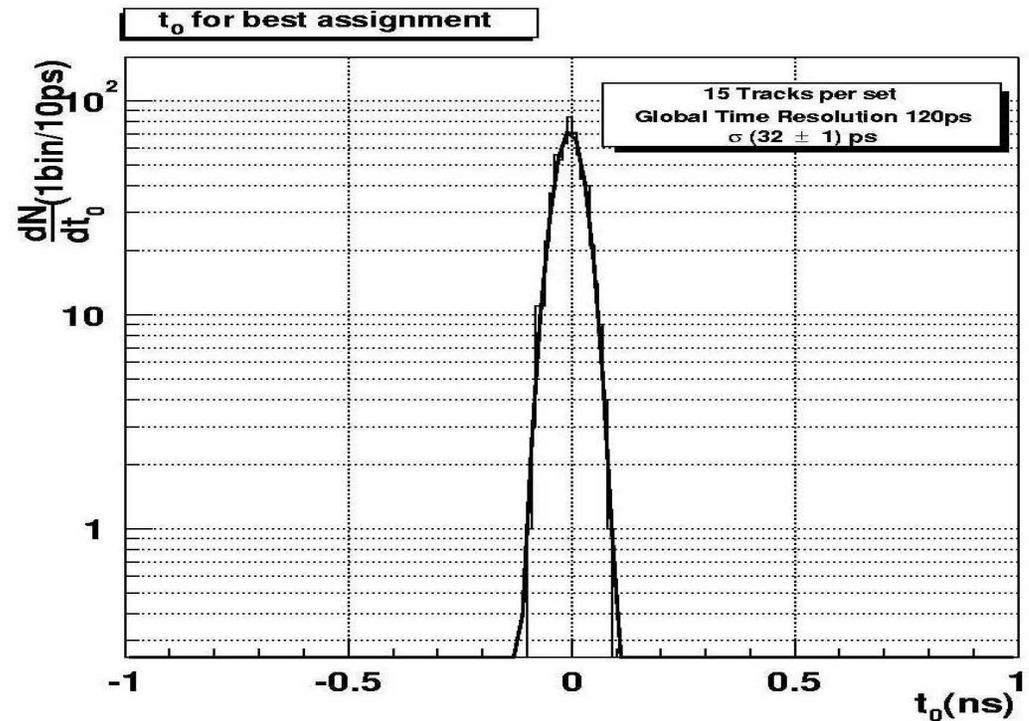


2. Then we can calculate time zero:

$$\langle t_i^0 \rangle = \left\langle \frac{l_i}{v_i(\pi, K, p)} - t_i \right\rangle$$

3. We chose configuration C with
 minimal

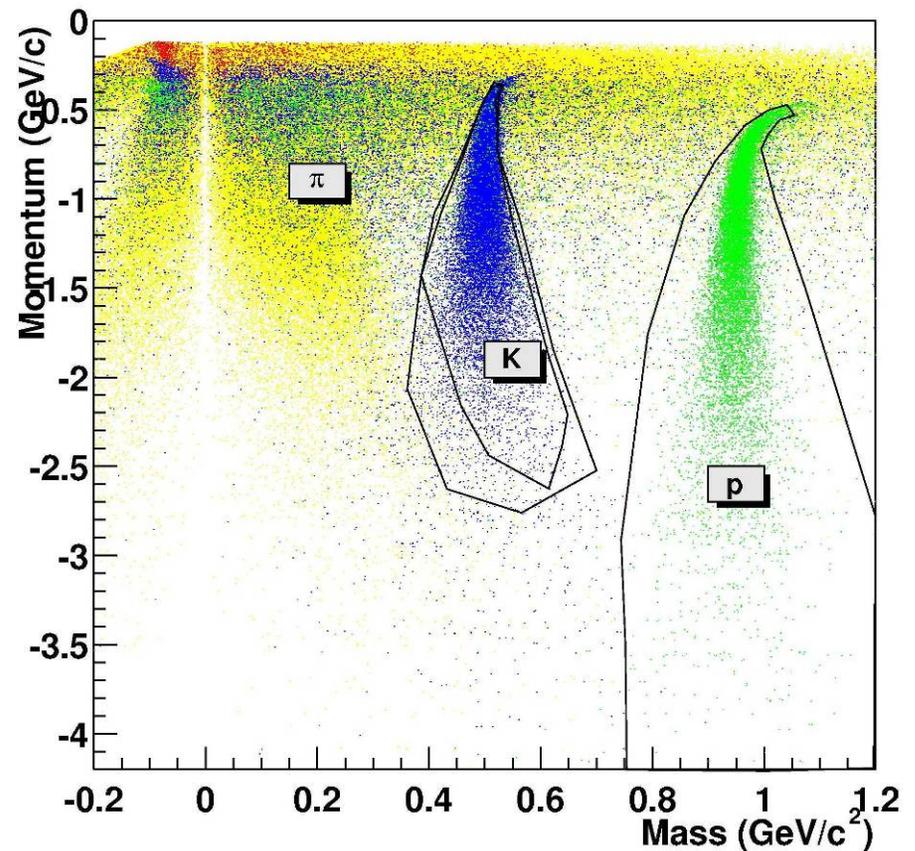
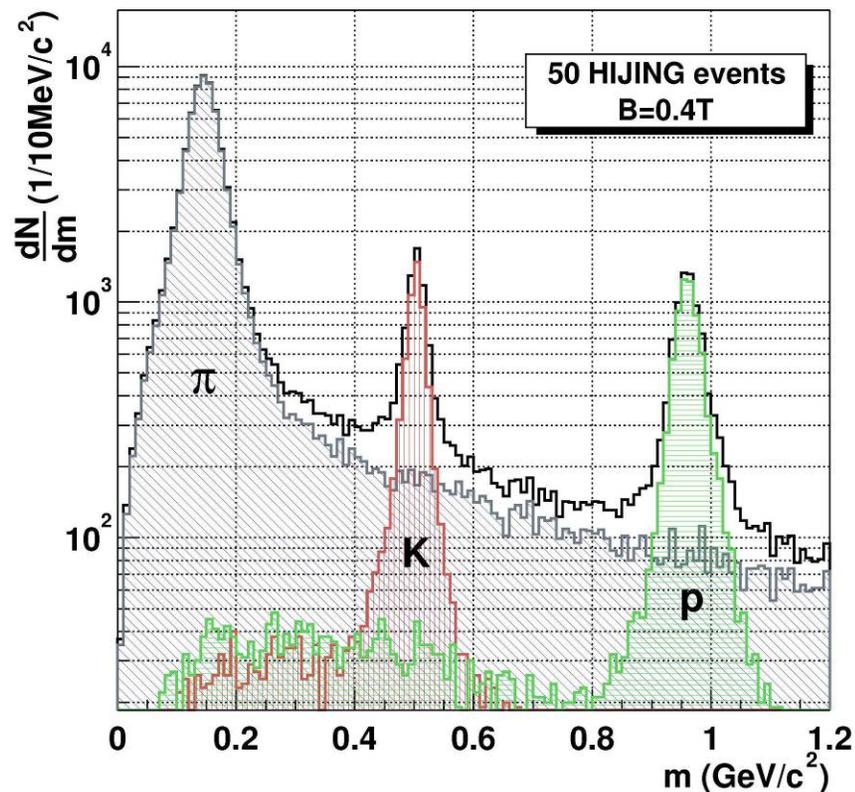
$$\chi^2(C) \approx \sum_i \{t_i^0(C) - \langle t_i^0 \rangle(C)\}^2$$



Which gives, with simulated events, particle identification with simple 1D or 2D cuts:

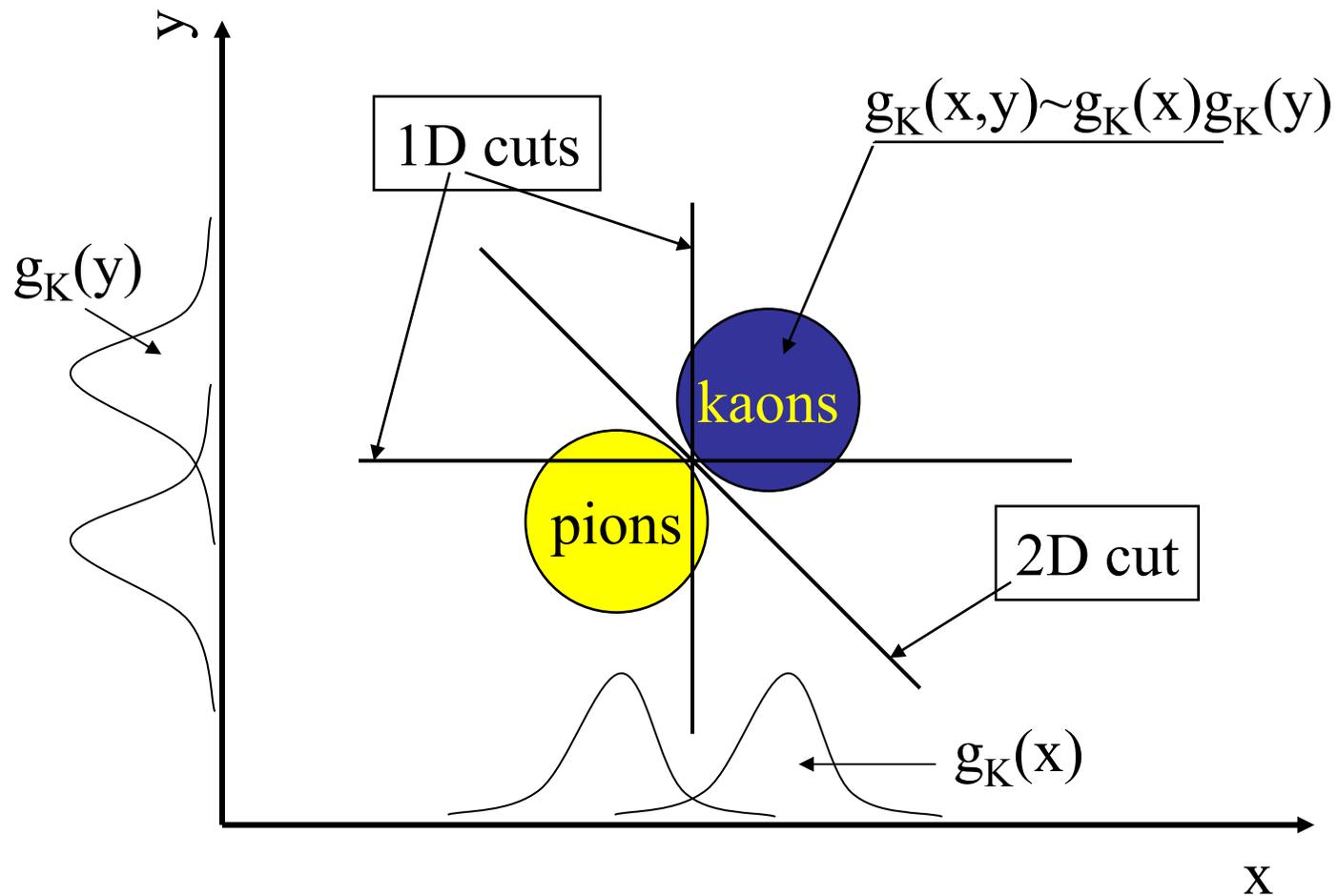
$$m = p \sqrt{c^2 t^2 / l^2 - 1}$$

$$m = \pm p \sqrt{c^2 t^2 / l^2 - 1}$$

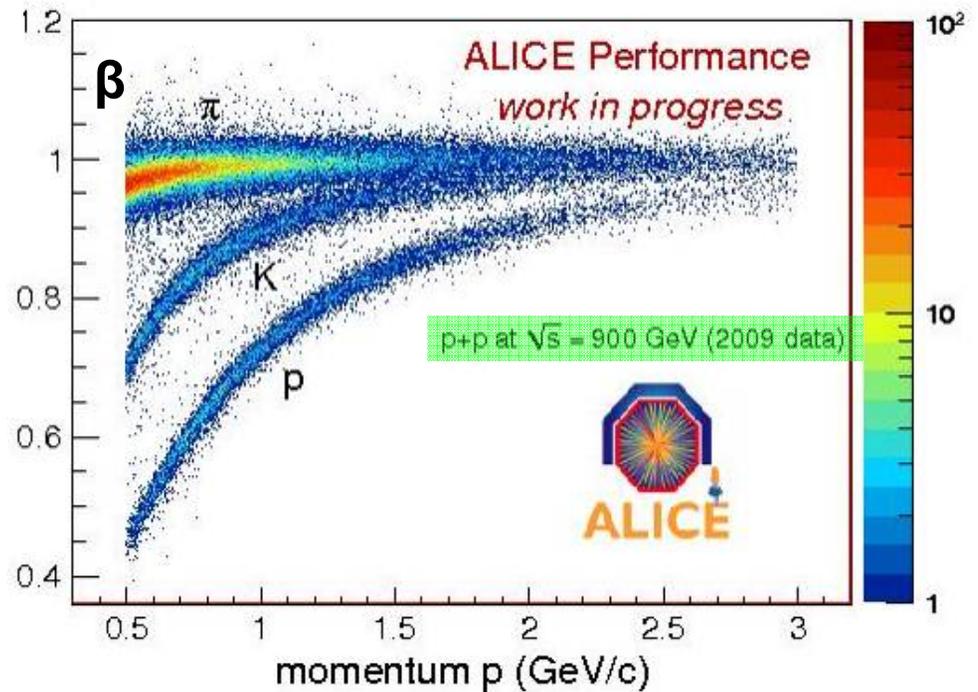
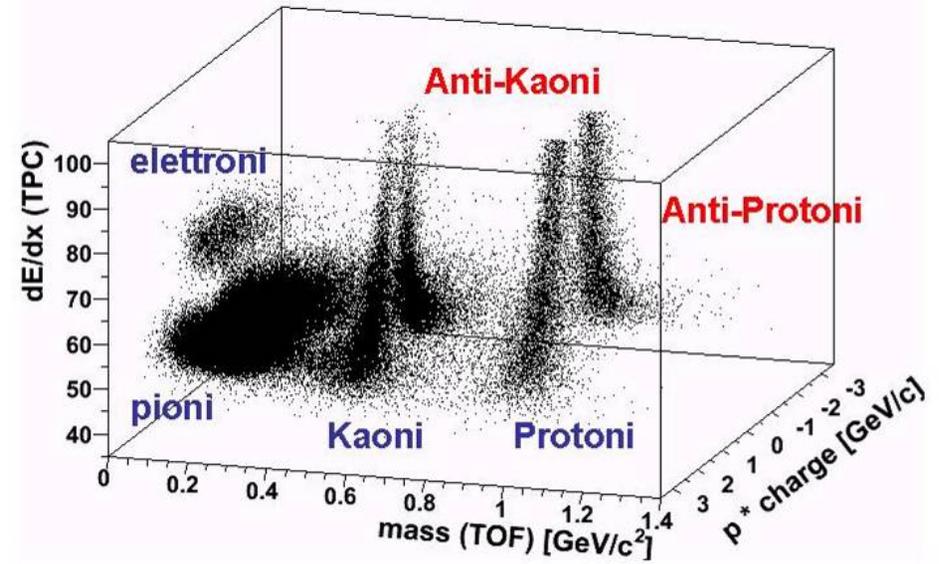
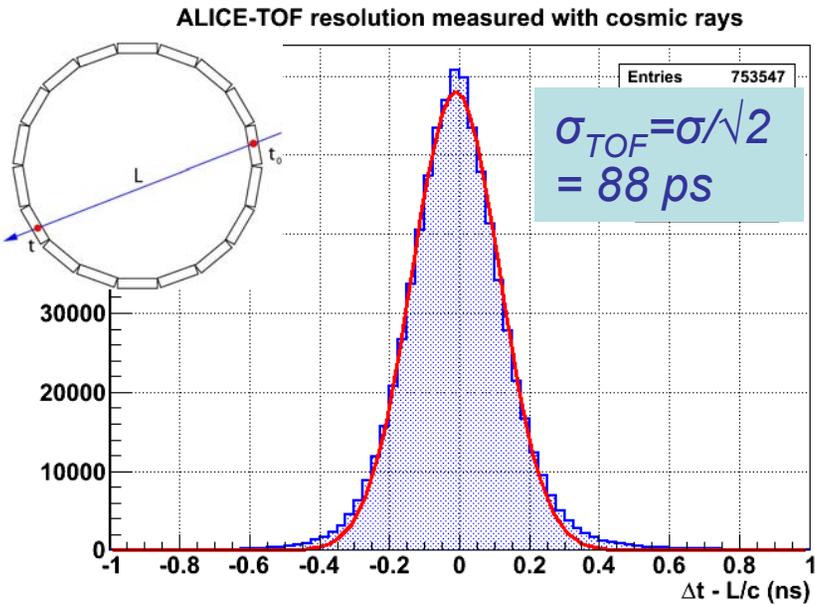


Neural network and Probability approach will of course also be used.

If you have **Detector X** and your friend has **Detector y** recording data of the same event:



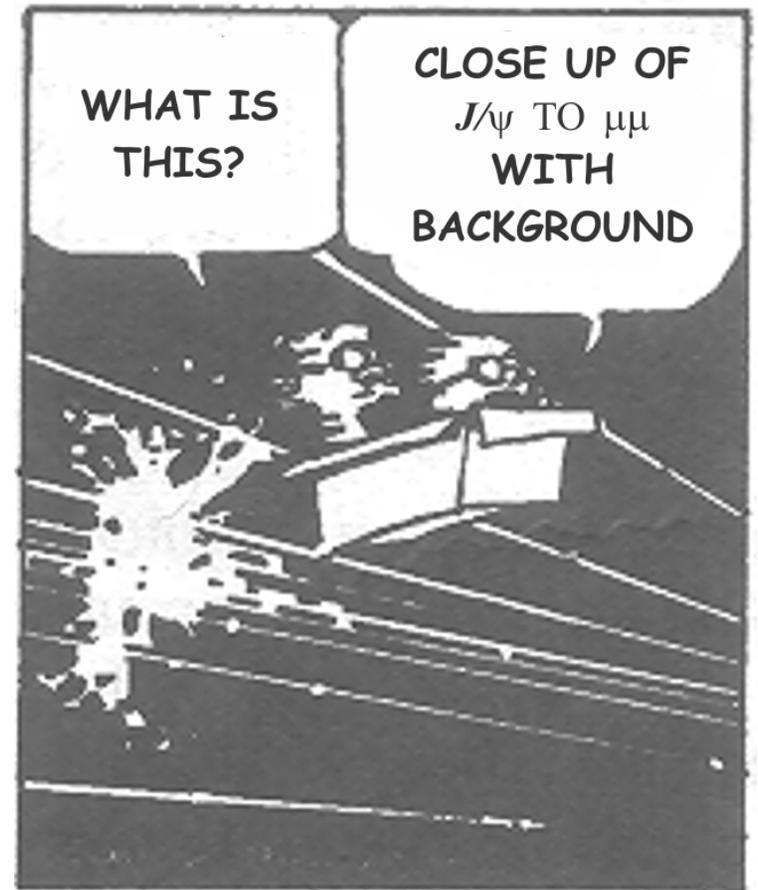
With real data:



That was all
planned for this lecture



Spare slides and back-ups



Kolmogorov-Smirnov tests

There is more to it than what is written here! Frodesen et al., probability and statistics in particle physics, 1979

Assume a sample of n uncorrelated measurements x_i . Let the series be ordered such that $x_1 < x_2 < \dots$. Then the cumulative distribution is defined as:

$$S_n(x) = \begin{cases} 0 & x < x_1 \\ i/n & x_i \leq x < x_{i+1} \\ 1 & x \geq x_n \end{cases}$$

The theoretical model gives the corresponding distribution $F_0(x)$

The null hypothesis is then $H_0: S_n(x) = F_0(x)$

The statistical test is: $D_n = \max |S_n(x) - F_0(x)|$

Example

In 30 events measured proper flight time of the neutral kaon in $\bar{K}^0 \rightarrow \pi^+ e^- \nu$ which gives: $D_{30} = \max |S_{30}(t) - F_0(t)| = 0.17$ or $\sim 50\%$ probability

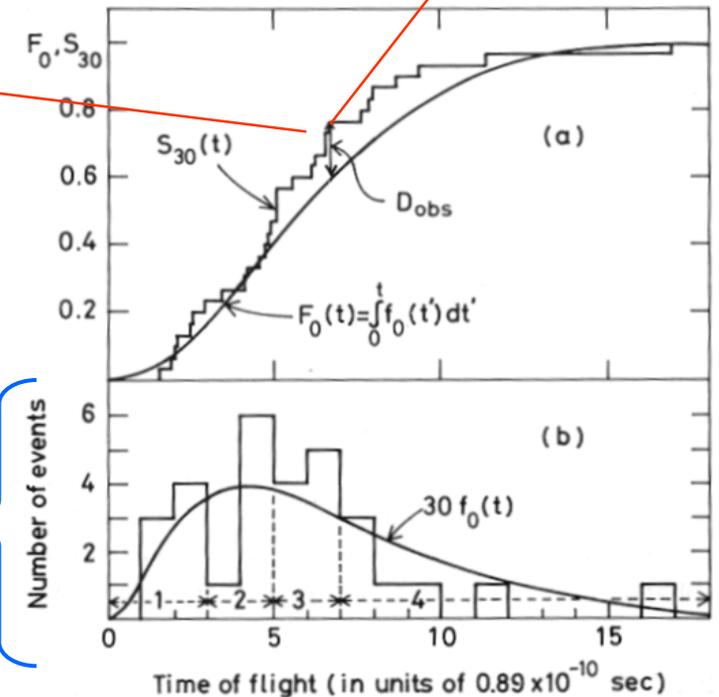
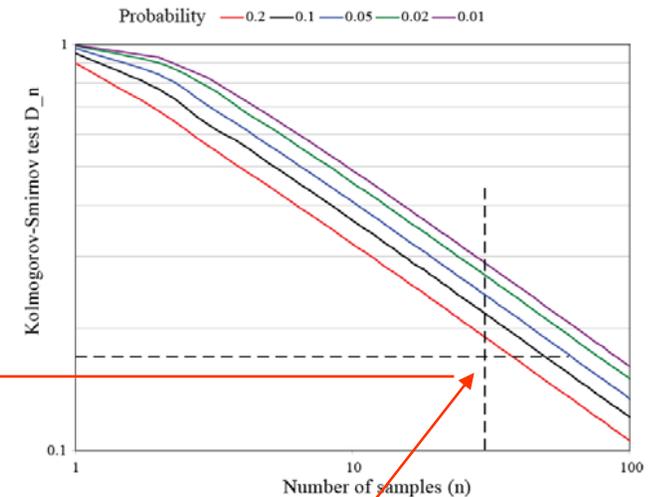
The same observations by χ^2 method.

n observations of x belonging to N mutually exclusive classes. $H_0: p_1 = p_{01}, p_2 = p_{02}, \dots, p_N = p_{0N}$ for $\sum p_{0i} = 1$

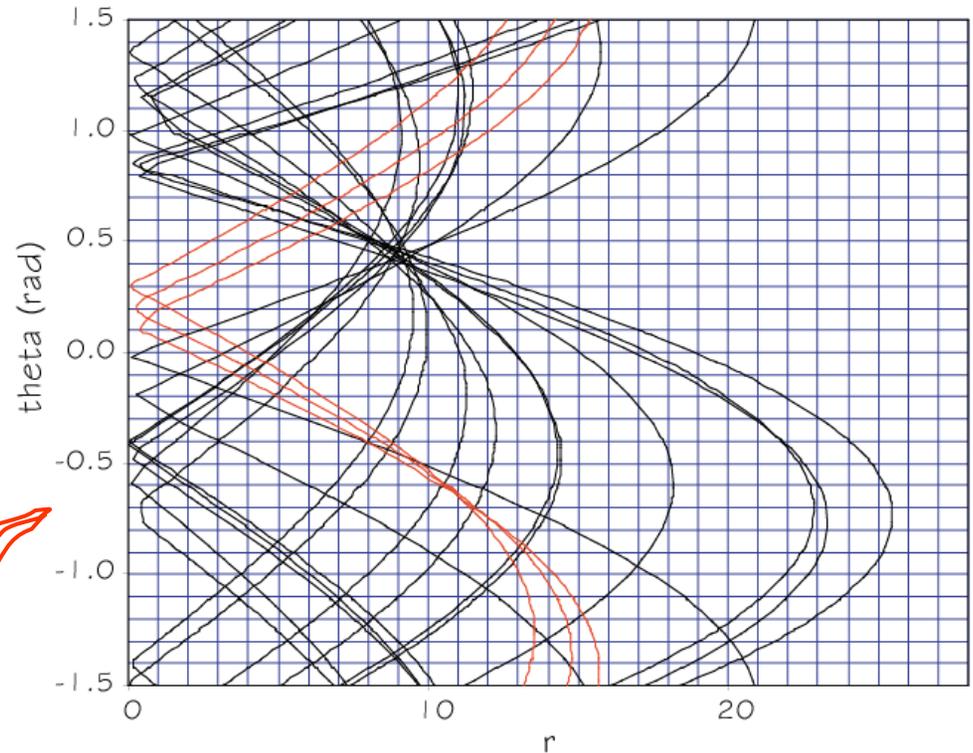
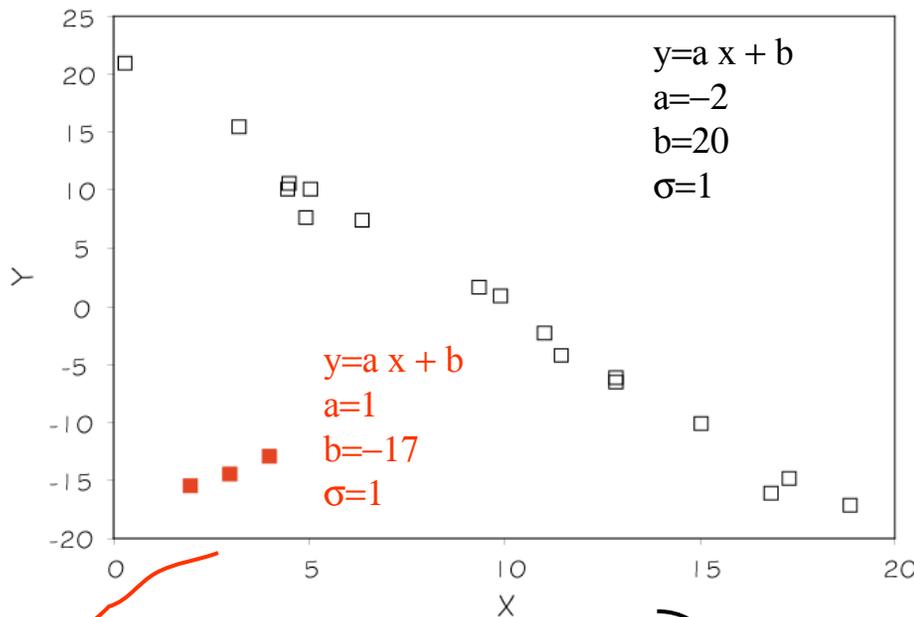
Test statistic:

$$X^2 = \sum_{i=1}^N \frac{(n_i - np_{0i})^2}{np_{0i}} = \frac{1}{n} \sum_{i=1}^N \frac{n_i^2}{p_{0i}} - n$$

when H_0 is true, this statistic is approximately χ^2 distributed with $N-1$ degrees of freedom. $\chi^2(obs) = 3.0$ with 3 degrees of freedom or probability of about 0.40



The Hough transform is a technique which can be used to isolate features of a particular shape within an image. The Hough technique is particularly useful for computing a global description of a feature(s) (where the number of solution classes need not be known *a priori*), given (possibly noisy) local measurements. The motivating idea behind the Hough technique for line detection is that each input measurement (*e.g.* coordinate point) indicates its contribution to a globally consistent solution (*e.g.* the physical line which gave rise to that image point).



$x \cos\Theta + y \sin\Theta = r$
 This *point-to-curve*
 transformation is the
 Hough transformation
 for straight lines

Ring Finding with a Markov Chain. ---

Sample parameter space of ring position and size by use of a Metropolis-Hastings Markov Chain Monte Carlo (MCMC)

Interested people should consult:

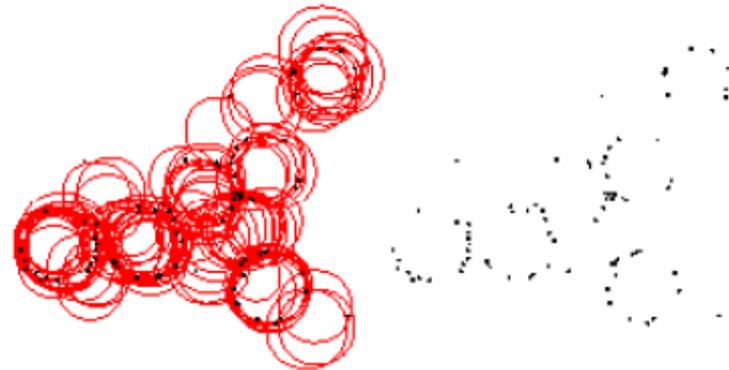
C.G. Lester, *Trackless ring identification and pattern recognition in Ring Imaging Cherenkov (RICH) detectors*, NIM A 560(2006)621-632

<http://lhcb-doc.web.cern.ch/lhcb-doc/presentations/conferencetalks/postscript/2007presentations/G.Wilkinson.pdf>

G. Wilkinson, *In search of the rings: Approaches to Cherenkov ring finding and reconstruction in high energy physics*, NIM A 595(2008)228

W. R. Gilks et al., *Markov chain Monte Carlo in practice*, CRC Press, 1996

Example of 100 new rings *proposed* by the “three hit selection method” for consideration by the MHMC for possible inclusion in the final fit. The hits used to seed the proposal rings are visible as small black circles both superimposed on the proposals (left) and on their own (right).



It is not about Markov chain, but have a look in

M.Morháč et al., Application of deconvolution based pattern recognition algorithm for identification of rings in spectra from RICH detectors, Nucl.Instr. and Meth.A(2010),doi:10.1016/j.nima.2010.05.044

Kalman filter

The Kalman filter is a set of mathematical equations that provides an efficient computational (recursive) means to estimate the state of a process, in a way that minimizes the mean of the squared error.

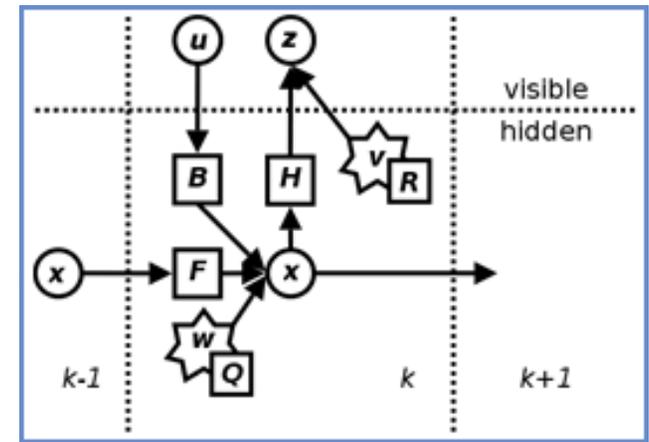
The filter is very powerful in several aspects:

it supports estimations of past, present, and even future states, and it can do so even when the precise nature of the modelled system is unknown.

http://www.cs.unc.edu/~welch/media/pdf/kalman_intro.pdf

iweb.tntech.edu/fhossain/CEE6430/Kalman-filters.ppt

R. Frühwirth, M. Regler (ed), Data analysis techniques for high-energy physics, Cambridge University Press, 2000



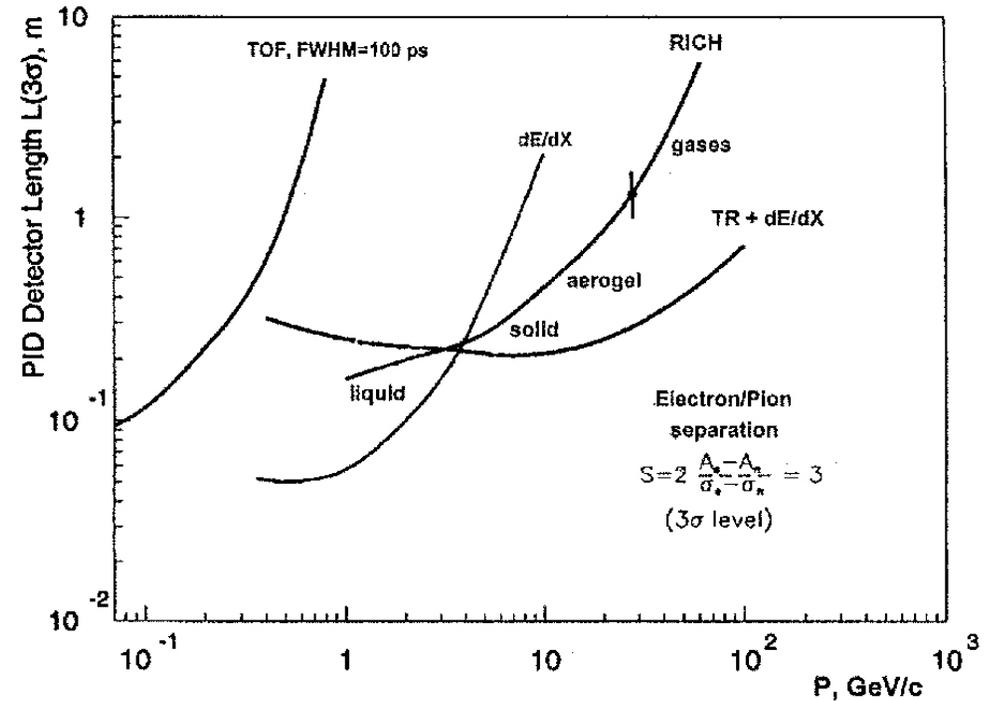
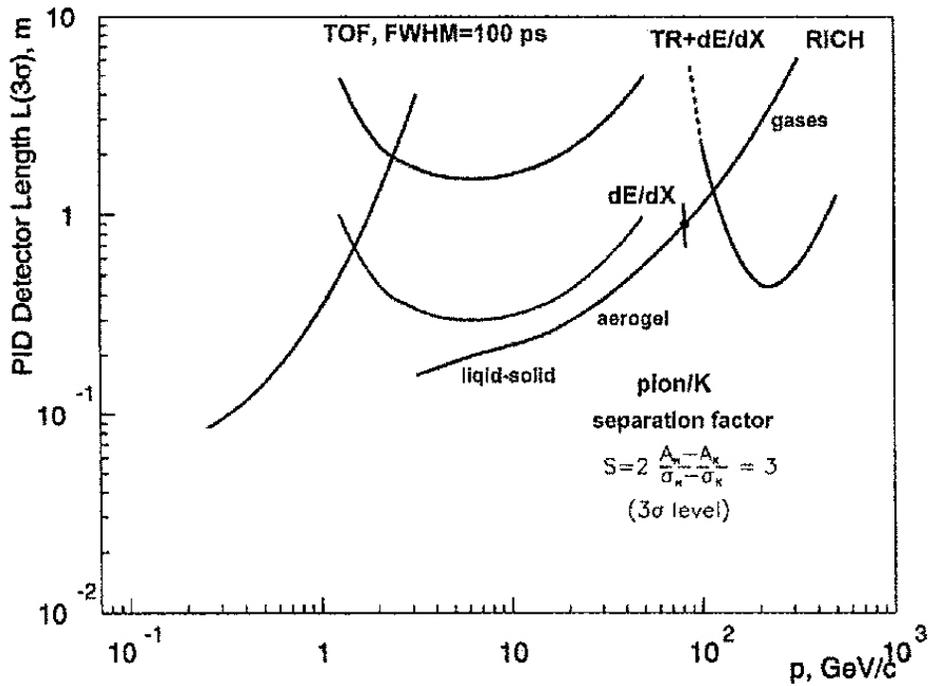
07/10/2009

US President Barack Obama presents the National Medal of Science to **Rudolf Kalman** of the Swiss Federal Institute of Technology in Zurich during a presentation ceremony for the 2008 National Medal of Science and the National Medal of Technology and Innovation October 7, 2009 in the East Room of the White House in Washington, DC.

2008

Academy Fellow **Rudolf Kalman**, Professor Emeritus of the Swiss Federal Institute of Technology in Zurich, has been awarded the Charles Stark Draper Prize by the National Academy of Engineering. The \$500,000 annual award is among the engineering profession's highest honors and recognizes engineers whose accomplishments have significantly benefited society. Kalman is honored for "the development and dissemination of the optimal digital technique (known as the Kalman Filter) that is pervasively used to control a vast array of consumer, health, commercial, and defense products."

Pion-Kaon separation for different PID methods.
The length of the detectors needed for 3σ separation.



The same as above, but for
electron-pion separation.